

United States Patent [19]

Sanders et al.

[54] **AUTOMATIC HTS FORCE MEASUREMENT INSTRUMENT**

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- [58] **Field of Search** 324/71.6; 73/819, 73/824

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[57] **ABSTRACT**

A device for measuring the levitation force of a high temperature superconductor sample with respect to a reference magnet includes a receptacle for holding several high temperature superconductor samples each cooled to superconducting temperature. **A** rotatable carousel successively locates a selected one of the high temperature superconductor samples in registry with the reference magnet. Mechanism varies the distance between one of the high temperature superconductor samples and the reference magnet, and a sensor measures levitation force of the sample as a function of the distance between the reference magnet and the sample. **A** method is also disclosed.

16 Claims, 3 Drawing Sheets

FIG. 2

FIG. 3

AUTOMATIC HTS FORCE MEASUREMENT INSTRUMENT

The United States Government has rights in this invention pursuant to Contract No. W-31-109-ENG-38 between the U.S. Department of Energy and The University of Chicago representing Argonne National Laboratory.

SUMMARY OF THE INVENTION

This invention relates to a machine which measures the 10 quality of **HTS** (high-temperature superconductor) samples used for levitation purposes.

BACKGROUND OF THE INVENTION

To quantify the levitation force of HTS samples in the and many of appreciated. presence of an external magnetic field, a measurement process has evolved. This process, shown in FIG. **1** labeled Previous Testing Method, involves zero-field-cooling a sample **10** in a dish containing a liquid cryogen, such as 20 nitrogen, then moving a reference magnet **12** towards the sample **10** and measuring the repulsive force exerted on the magnet at precise distances from the sample. The force is measured using a load cell **13;** the distance is measured and changed using a motion controller system and stage **15.** In 25 general, a force vs. separation distance hysteresis curve is generated by use of a well known program entitled "Labview" put out by National Instruments of Austin, Tex., and the curve is extrapolated to a distance of zero. The force at zero distance is termed F_o , and this number is representative 30 of the levitation quality of a given **HTS** sample.

This measurement heretofore has been performed on one sample at a time. Prior to the subject invention each sample was cemented upright in a Styrofoam dish and cooled with liquid nitrogen. The load cell/magnet probe approached the sample from above to acquire the necessary data. Lengthy set-up times, manual control of liquid nitrogen addition, and cool-down time for each **HTS** sample ready to be tested made the process slow to produce results, repetitive to perform, and ultimately inaccurate due to human error.

When more samples began accumulating for use such as in an FES (flywheel energy storage) facility, an improved testing method was needed. Preferably, the new method would use the same measurement principles and generate would use the same measurement principles and generate
the same curves, but do so more efficiently and accurately. ⁴⁵ **A** *complex 25 is above in EIC 2. As above in EIC 2.* the

The machine of the present invention was designed to be loaded with a plurality of samples, each sample preferably being a hexagonally shaped disc, and to provide one hysteresis curve and F_o value for each sample, as quickly and accurately as possible. Because of cost and accuracy considerations, only one load cell/magnet probe was used although more are possible, and the samples were to be tested seriatim.

Accordingly, it is an object of the present invention to $\frac{1}{55}$ provide a machine for determining hysteresis curves and F_{α} values for **HTS** samples more rapidly than heretofore possible.

Another object of the invention is to provide a machine for determining hysteresis curves and F_o values for HTS $_{60}$ samples in which a plurality of samples are tested seriatim without the need for individual supervision.

Still another object of the present invention was to provide a machine for determining hysteresis curves and F_{α} values for a plurality of **HTS** samples which can easily be 65 adapted to continuous through semi-continuous modes of operation.

The invention consists of certain novel features and a combination of parts hereinafter fully described, illustrated in the accompanying drawings, and particularly pointed out in the appended claims, it being understood that various 5 changes in the details may be made without departing from the spirit, or sacrificing any of the advantages of the present invention.

BRIEF DESCRIPTION OF THE DRAWINGS

For the purpose of facilitating an understanding of the invention, there is illustrated in the accompanying drawings a preferred embodiment thereof, from an inspection of which, when considered in connection with the following 15 description, the invention, its construction and operation, and many of its advantages should be readily understood and

FIG. 1 is a isometric view of a prior art mechanism for testing HTS samples;

FIG. 2 is a cross section of the inventive device; and

FIG. 3 is a plan view of a carousel useful in the present invention with multiple HTS samples.

DESCRIPTION OF THE PREFERRED EMBODIMENT

A cross-section of the invention is shown in FIG. **2.** The machine **20** includes a sealed cryochamber **21** having a leak-tight pan **22** having an inner bottom surface **23** to hold a cryogen such as liquid nitrogen and a plurality of such as ten **HTS** samples **25.** Because the samples **25** have a top side **26** which outperforms their bottom sides in these measurements, it is important that the samples **25** are placed into the pan **22** with their top sides **26** down. Contrary to the ³⁵prior art, the hexagonal top side **26** of the sample **25** shown in FIG. **2** must face a magnet **27,** which in the machine **20** requires placing the sample **25** upside-down in the pan **22.** The samples **25** are indexed by a rotary table or carousel **30** having a plurality of circumferentially spaced apertures **31** ⁴⁰coupled to a motion controller stage **32** by a shaft **33.** The motion controller system and stage **32** was purchased from Newport and identified as Model No. M-495. The samples **25** are slid along the bottom surface **23** of the pan **22,** which is always stationary.

samples **25** is shown in FIG. **3.** As shown in FIG. **2,** the sample **25** ready for testing is positioned below a mechanically actuated mechanism, such as an air-cylinder mechanism **35** having an air cylinder **36,** a shaft **37** and a disc **38.** 50 The shaft **37** of plunger mechanism **35** is extended after a sample **25** is positioned for testing in order to hold the sample **25** firmly against the bottom **23** of the pan **22,** to counteract the repulsive force exerted by the magnet **27** during testing. The magnet **27** is attached to a load cell **40** and the entire load cell/magnet probe is indexed vertically by a linear screw actuator **41.** The load cell **40** was obtained from **BLH** Electronics, Model No. C2616K and the linear screw actuator was obtained from Newport, Model No. M-360-90.

In order to test a **HTS** sample **25,** the sample is rotated into position by the table or carousel **30** by operation of the motion controller **32,** then locked down by the plunger mechanism **35.** The load cell **40** and magnet probe **27** (which is at a known distance from the sample, often 15 mm) begins approaching the sample **25,** and force vs. separation data is collected at precise intervals. The magnet **27** approaches to a minimum separation distance, often 1 mm since the particular pan **22** used had a wall thickness of 0.737 mm. Then the magnet **27** is returned to its original position, collecting data again at precise intervals. Several variations of this test, all providing force hysteresis data, can be accommodated by the mechanism 20. The plunger mechanism **35** is lifted, the tested sample **25** is rotated away, and the next sample is indexed into position. This process is repeated a predetermined number of times before reloading

Condensation on the cold bottom surface **23** of the pan **22** would interfere with the magnet **27** travel and force measurements. To alleviate this problem, the entire region below the pan **22** is purged with a high-purity nitrogen gas. As an alternative to purging, a vacuum could be drawn in this region, eliminating condensation and also improving ther- 15 mal insulation. The sealed purge chamber **21** consists of a suitable plastic, such as polyvinyl chloride (PVC) bottom mounting plate **45,** transparent plastic, such as acrylic, tube **46,** enclosed at the top by a support ring **47** of a suitable material such as epoxy-fiberglass composite (i.e. **NEMA**grade G-10), and the pan **22.** The temporary seal at the bottom is accomplished with an O-ring **48.** The seal between the tube **46** and support **47** is a permanent joint **49,** of a suitable material such as an epoxy resin. The G-10 ring **47** is sealed to the pan **22** using the closed-cell Styrofoam **51** 25 and vacuum grease. **A** clamp **53** locks the pan **22** to the ring **47** with bolts **54** passing through the Styrofoam **51. A** Styrofoam lid **55** is also placed on the device **20** during testing; both Styrofoam pieces **51, 55** provide thermal insulation to conserve liquid nitrogen in the pan. While various 30 specific plastics have been used herein, they are named for purposes of illustration only. Other plastics are available which would be acceptable alternatives.

previous force-measuring techniques are improved speed, accuracy and efficiency while saving operating costs.

The magnet **27** is never in direct contact with liquid nitrogen, so its temperature is more consistent during testing than in previous measurement schemes. **A** magnet's field varies with temperature, so improved temperature stability ultimately translates into reliable and repeatable force measurements. In previous techniques, when **HTS** samples **25** were measured from above in an open dish, the magnet occasionally contacted free cryogen near the sample, and at this point its force measurements became unreliable.

The **HTS** samples **25** in the present invention are at the bottom rather than the top of the liquid nitrogen bath so their temperature is constant and results are more repeatable. When measuring the sample from above, as was the protocol ζ_0 in previous measurements, the top surface of the sample was left exposed so the magnet could approach, and liquid nitrogen level varied because it was controlled by an operator. This resulted in inconsistent temperature of **HTS** data.

The present method of determining the position of the load cell/magnet probe **40, 27** is improved over previous techniques. The measurement of the separation distance between the magnet **27** and the **HTS** sample **25** is critical to achieving correct F_o values. A reliable measurement can be achieved by zeroing the magnet **27** against a reference surface and relying on accurate motion controller systems to report its position. In previous procedure, the magnet was zeroed against the surface of the warm **HTS** sample to be tested. Then, when liquid nitrogen was added so force measurements could be made, the dish holding the sample

and liquid nitrogen contracted, moving the sample downward, and all position values thus became erroneous. Magnetic interaction between the probe and the sample prohibited zeroing the magnet against the sample after adding liquid nitrogen.

In the machine **20,** the magnet **27** is "zeroed" against the bottom **23** of the pan **22** rather than the sample **25.** This is done after the pan **22** has been filled with liquid nitrogen and has contracted, but before it contains any **HTS** samples **25.** is necessary. The magnet 27 can be "zeroed" against the bottom surface **23** of the pan **22** when the pan **22** is cold since there is no nearby **HTS** material for the magnet to interact with. The position of the magnet **27** is not actually set to zero when it contacts the pan **22,** but is set to 0.737 mm, the thickness of 15 the pan **22.** Then, when a sample **25** is being tested, the distance between the magnet **27** and the top surface **26** of sample **25** is known, since the top surface **26** of sample **25** is pressed to the inner bottom surface **23** of the pan **22,** and both the pan thickness and the distance between the magnet 20 **27** and the top surface **26** of the sample **25** are known.

Because the measurement is made through the same section of the cryochamber pan **22** for each sample **25,** determining the position of the magnet **27** with respect to the sample **25** is simple as well as accurate. The magnet zero is set once and is maintained through the heights of **HTS** samples **25** may vary drastically. This is because the samples 25, top (or measured) surfaces 26 are always in the same location pressed against the pan inner surface bottom **23,** when the sample **25** is being tested. Also, the zero is set after the entire device **20** reaches a thermal steady state, so it never needs to be reset in response to thermal contraction, except after the pan **22** is rewarmed. There is no limit to the number of samples **25** that can be tested before rewarming The primary advantages of the subject invention over the pan **22**. With prior art methods, zeroing the magnet probe prior to the magnet probe prior the magnetic probe prior the magnetic probe prior the magnetic probe prio 35 took approximately 2 minutes per **HTS** sample; whereas this delay is entirely eliminated by the subject invention.

> The delay for cooling each sample **25** between individual sample tests is also eliminated. Ten samples **25** were loaded into the device 20 at once by an operator, and at the same time the operator replaced the small amount of cryogen that boiled off during the previous run with fresh liquid nitrogen. This ensured that the pan **22** always contained plenty of liquid nitrogen to zero-field cool the samples **25** at the time of loading and to keep them cold through the duration of the test. When one **HTS** sample **25** was finished testing, it is indexed out of position, and the next one is slid into the testing location. It was already cool and testing began immediately. The time spent cooling **HTS** samples **25** for testing was approximately 1 minute per sample in the previous testing procedure; now this 1 minute is spent cooling not one but all ten samples **25** during the loading period, reducing this delay drastically.

samples which translated into less reliable and repeatable 55 the subject invention. Each sample **25** was placed into a The efficiency of the loading operation has improved with circular slot **31** as the indexing table or carousel **30** was rotated 360 degrees. This entire loading took approximately 20 seconds. In previous methods, each sample **25** had to be cemented into place using vacuum grease because a hold- $_{60}$ down system like the subject invention has was not easily adaptable to testing from above. It took approximately 1 minute per sample to prepare tests this way. Preparation in the device **20** required about 2 seconds per sample in a single loading operation, and the samples need not be cleaned of vacuum grease after testing.

> In high-volume applications, the device **20** could be easily modified to automatically load **HTS** samples **25** continu

ously rather than interrupting testing for 2 minutes after every ten are tested. As each sample 25 is finished testing and mdexed out of position, a mechanical hand (not shown) could be programmed to pull it out of the slot and replace it with a new **HTS** sample **25** awaiting testing on a conveyor 5 belt (also not shown). In the current operating procedure, identification of the samples 25 after testing relies on preserving an order as they are placed into and removed from the device's pan **22.** However, **HTS** samples **25** could be barcoded prior to testing and packaged in a manufactur- 10 ing plant, and each sample's characteristics could be obtained easily when any consumer desired them.

While there has been disclosed what is considered to be the preferred embodiment of the present invention, it is understood that various changes in the details may be made 15 without departing from the spirit, or sacrificing any of the advantages of the present invention.

The embodiments of the invention in which an exclusive property or privilege is claimed are defined as follows:

1. A device for measuring the levitation force of a high 20 temperature superconductor sample with respect to a reference magnet maintained out of contact with a cryogenicliquid, comprising a receptacle for holding a plurality of high temperature superconductor samples each cooled to superconducting temperature by contact with a cryogenic 25 liquid, a positioning mechanism for successively locating a selected one of said high temperature superconductor samples in registry with said reference magnet, mechanism for varying the distance between said selected one of said high temperature superconductor samples and said reference 30 magnet, and a sensor for measuring levitation force of said sample as a function of the distance between said reference magnet and said selected one of said high temperature superconducting samples.

. **2.** The device of claim **1,** wherein said sensor is opera- 35 tively connected to said magnet.

3. The device of claim **1,** wherein said receptacle has a predetermined wall thickness through which the levitation force is measured.

4. The device of claim **1,** wherein said receptacle and said 40 sample and at least a portion of said positioning mechanism are within an insulated compartment to enable said receptacle and said samples and said portion of said positioning mechanism to be maintained at superconducting temperatures during the measurement of levitation forces for all 45 the cooled samples in registry with the reference magnet. samples.

5. The device of claim 1, wherein said reference magnet is positioned below said receptacle and the high temperature superconductor sample to be measured is positioned in said receptacle and maintained in contact with the bottom of said 50 receptacle during measurements of the levitation device.

6. The device of claim **1,** wherein said positioning mechanism includes an apertured carousel connected to a motor mechanism for rotating the carousel to place a selected high temperature superconductor sample in registry with said 55 reference magnet.

7. The device of claim **6,** and further comprising thermal insulation surrounding said receptacle and said carousel for maintaining a plurality of high temperature superconductor **6**

samples and said receptacle and said carousel at the superconducting temperature during measurement of one sample.

8. A device for measuring the levitation force of a high temperature superconductor sample with respect to a reference magnet, comprising a receptacle for holding a plurality of high temperature superconductor samples each cooled to superconducting temperatures by contact with a cryogenic liquid, a positioning mechanism for successively locating a selected one of said high temperature superconductor samples in registry with said reference magnet, said reference magnet being physically separated from the cryogenic liquid, a thermally insulated chamber housing said receptacle and said samples and at least a portion of said positioning mechanism during measurement of levitation forces at superconducting temperatures, mechanism for varying the distance between said selected one of said high temperature superconductor sample and said reference magnet, a sensor for measuring the levitation force of said selected sample as a function of the distance between said reference magnet and said selected sample, and mechanism for recording the measured levitation force at a plurality of different distances between said reference magnet and selected sample to calculate the levitation force at zero distance.

9. The device of claim **8,** wherein each high temperature superconductor sample is positioned on a bottom wall of said receptacle and held in place during measurement of the levitation force.

10. The device of claim 9, wherein a movable piston mechamsm holds each sample against said receptacle bottom wall during measurement of the levitation force.

11. The device of claim **10,** wherein said position mechanism includes a carousel having a plurality of circumferentially spaced openings each holding for holding a high temperature superconductor sample.

12. A method of measuring the levitation force of a plurality of high temperature superconductor samples, comprising providing a plurality of samples in a receptacle; cooling the samples to superconducting temperatures while maintaining the receptacle at substantially the same temperature as the samples; positioning one of the cooled samples in registry with a reference magnet, varying the distance between the reference magnet and the selected sample to obtain measurements of the levitation force of the selected sample, and thereafter positioning another one of

. **13.** The device of claim **9,** wherein said reference magnet is moved toward and away from said bottom wall of said receptacle.

14. The device of claim **13,** wherein a portion of thermal insulation around said receptacle is removed to permit said reference magnet to move toward and away from said bottom of said receptacle.

~5. The method of claim **12,** wherein the cooled sample being measured is maintained against the receptacle bottom wall during measurement of the levitation force.

16. The method of claim **15,** wherein the reference magnet is moved toward and away from the receptacle bottom wall during measurement of the levitation force.

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