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1.1 | Overview

Let μ be a locally finite Radon measure on \mathbb{C} . A harmonic ball for μ centered at $z \in \mathbb{C}$ is an open set $\Lambda(z) \subset \mathbb{C}$ containing *z* that satisfies the mean-value property

$$f(z) = \frac{1}{\mu(\Lambda(z))} \int_{\Lambda(z)} f(x)\mu(dx), \qquad (1.1)$$

for all functions *f* that are harmonic in a neighborhood of the closure of $\Lambda(z)$.

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Harmonic balls in Liouville quantum gravity

Accepted: 15 November 2024

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RESEARCH ARTICLE

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INTRODUCTION

Funding information NSF, Grant/Award Number: DMS-2202940; Stevanovich; Clay

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Abstract

Harmonic balls are domains that satisfy the mean-value property for harmonic functions. We establish the existence and uniqueness of harmonic balls on Liouville quantum gravity (LQG) surfaces using the obstacle problem formulation of Hele-Shaw flow. We show that LQG harmonic balls are neither Lipschitz domains nor LQG metric balls, and that the boundaries of their complementary connected components are Jordan curves. We conjecture that LQG harmonic balls are the scaling limit of internal diffusion limited aggregation on random planar maps. In a companion paper, we prove this in the special case of mated-CRT maps.

MSC 2020 35B05, 60K35, 82C24 (primary)

Revised: 4 November 2024

Received: 30 January 2023

Proceedings of the London Mathematical Society



1.1.1 | Liouville quantum gravity

In this article, we will construct and study harmonic balls in the setting of *Liouville quantum gravity* (*LQG*). LQG is a canonical one-parameter family of random fractal surfaces that were introduced by Polyakov in the 1980s in the context of bosonic string theory [71]. One sense in which these surfaces are canonical is that they are known or conjectured to describe the scaling limits of various types of random planar maps (see Section 1.3 for more details).

Heuristically, for $\gamma \in (0, 2)$ and a domain $U \subset \mathbb{C}$, a γ -LQG surface parameterized by U is the two-dimensional Riemannian manifold with Riemannian metric tensor $e^{\gamma h} (dx^2 + dy^2)$, where $dx^2 + dy^2$ is the Euclidean metric tensor and h is a variant of the Gaussian free field (GFF) on U. This metric tensor does not make literal sense since h is a random generalized function, not a true function. Nevertheless, it is still possible to define the associated volume form, a.k.a. the γ -Liouville measure. This is a random, locally finite Radon measure on U that is informally given by

$$\mu_h(dz) = e^{\gamma h(z)} \, dz,\tag{1.2}$$

where dz denotes Lebesgue measure.

The expression (1.2) can be made rigorous as part of a general theory of regularized random measures called *Gaussian multiplicative chaos* [50, 74, 75]. This theory shows that the Liouville measure is a well-defined (random) Radon measure that is measurable with respect to *h* (the converse is also true [9]). However, the Liouville measure is quite irregular: μ_h is supported on the "thick" points of the GFF, a dense fractal set of Hausdorff dimension $2 - \frac{\gamma^2}{2}$, and hence is mutually singular with respect to Lebesgue measure [23, 43].

There is a vast literature on LQG: see [33, 83] for introductory survey articles and [8] for a more detailed introduction. However, only minimal prior knowledge of this literature is needed to read this paper. The necessary background will be reviewed in Section 2.

1.1.2 | LQG harmonic balls

We will be interested in harmonic balls, as defined in (1.1), in the case when μ is the γ -Liouville measure, μ_h , for some $\gamma \in (0, 2)$. We call these domains γ -LQG harmonic balls. One of our main motivations for studying LQG harmonic balls is that we expect them to be the scaling limits of internal diffusion limited aggregation (IDLA) [56] on random planar maps. See Section 1.3 for further discussion.

We will construct γ -LQG harmonic balls via a certain partial differential equation involving μ_h . In particular, this PDE *Hele–Shaw flow*[†] (defined in Section 3.1 below) describes the movement of a Newtonian fluid on a γ -LQG surface. The irregularity of μ_h precludes applying the classical theory of existence and uniqueness of harmonic balls [14, 24, 26, 79] in the LQG setting. Much of the existing technology requires μ to be bounded from above and below by a multiple of the Lebesgue measure — a constraint too strict to be satisfied, even approximately, by μ_h . Consequently, even the existence of γ -LQG harmonic balls is far from obvious. Indeed, nontrivial harmonic balls do not exist in general — take, for instance, μ to be a Dirac measure.

[†] The family of γ -LQG harmonic balls we construct are weak solutions to a Hele–Shaw problem, see [30, Section 3.5] and [76].

We address this difficulty by following a different path, inspired by arguments from discrete Laplacian growth [21, 47]. Roughly speaking, we show that it is unlikely for Brownian motion to avoid regions of large μ_h -mass and then use this to show harmonic balls exist. This argument also leads to geometric requirements harmonic balls satisfy. We later use these requirements to show that "typical" γ -LQG harmonic balls are neither Lipschitz domains nor LQG metric balls.

In contrast to the constructions of other objects associated with LQG, such as the LQG measure, the LQG metric, and Liouville Brownian motion, our construction of LQG harmonic balls does not use any approximation or regularization procedure. Rather, LQG harmonic balls are constructed directly as the solutions of an optimization problem involving the LQG measure (see Section 3.1).

An LQG surface is a certain type of random fractal (albeit not one defined as a subset of \mathbb{R}^d for some *d*). Analysis on fractals is a well-studied topic, see, for example, [51, 88, 89]. One program of research in this area is to construct the Laplacian on a fractal and then use this to develop a theory of elliptic PDE on the fractal. As discussed further in Section 2, Brownian motion, and hence the Laplacian, has been constructed on LQG surfaces [6, 25]. The present paper may be thought of as an initial step in the study of PDE on LQG surfaces.

1.2 | Statement of the main result

Fix the LQG parameter $\gamma \in (0, 2)$. Let *h* be a whole-plane GEF, or more generally a whole-plane GEF plus the function $-\alpha_0 \log |\cdot|$, where $\alpha_0 < Q := 2/\gamma + \gamma/2$. Let μ_h be the γ -LQG area measure associated with *h*. The precise definitions of *h* and μ_h will be reviewed in Section 2. For now, the unfamiliar reader can think of μ_h as a random, nonatomic, locally finite Borel measure on \mathbb{C} that assigns positive mass to every open subset of \mathbb{C} .

Our main result concerns existence and uniqueness of a family of γ -LQG harmonic balls. To prove uniqueness, we enlarge the class of harmonic functions in the definition to include those of the form,

$$\tilde{H}_O(D) = \left\{ \int_O G_O(\cdot, y) \,\nu(dy) : \nu \text{ is a signed Radon measure with support in } O \setminus D \right\}, \quad (1.3)$$

where $O, D \subset \mathbb{C}$ are bounded open sets and G_O is the Green's function for Brownian motion in the domain O (defined in Section 2.3 below). That is, $\Lambda(z)$ is a harmonic ball centered at $z \in \mathbb{C}$, if (1.1) is satisfied for all functions $f = f_1 + f_2$ where f_1 is harmonic in a neighborhood of the closure of $\Lambda(z)$ and $f_2 \in \tilde{H}_O(\Lambda(z))$ for some O with $\Lambda(z) \subset \overline{O}$.

We are now ready to state our main existence and uniqueness result.

Theorem 1.1 (Existence and uniqueness of harmonic balls). On an event of probability one, for each $z \in \mathbb{C}$, there exists a unique family of harmonic balls $\{\Lambda_t(z)\}_{t>0}$ satisfying the following properties:

- (a) For each t > 0 and $z \in \mathbb{C}$, $\mu_h(\Lambda_t(z)) = t$, $\mu_h(\partial \Lambda_t(x)) = 0$, and $\Lambda_t(z)$ is equal to the interior of *its closure.*
- (b) The domains Λ_t(z) are bounded, connected, contain {z}, increase continuously in t (in the Hausdorff topology), and satisfy ∩_{t>0}Λ_t(z) = {z}.

In some literature on harmonic balls, for example, [79] or [41], uniqueness is only proven up to sets of zero mass. In our setting, we get exact uniqueness thanks to the requirement that $\Lambda_t(z)$ is equal to the interior of its closure.



FIGURE 1 Simulations of γ -LQG harmonic balls with respect to the same GFF instance for $\gamma = 0.5, 1.0, 1.8$. The colors distinguish harmonic balls of different mass. From the figures, it appears that the complement of an LQG harmonic ball is not necessarily connected. We expect that this is the case for a "typical" LQG harmonic ball.



FIGURE 2 Simulations of γ -LQG metric balls with respect to the same GFF instance as Figure 1 for $\gamma = 0.5, 1.0, 1.8$.

We also show that typical harmonic balls are "novel"; that is, they are neither Euclidean balls nor LQG metric balls. We also show that the boundaries of their complementary connected components are Jordan curves. Compare Figures 1 and 2. The precise definition of the LQG metric ball will be given in Section 2; for now the reader may think of it as the natural notion of metric ball on an LQG surface.

Theorem 1.2 (Novelty of harmonic balls). The following is true on an event of probability 1. For Lebesgue-a.e. t, $\Lambda_t(0)$, constructed in Theorem 1.1, is neither a Lipschitz domain nor an LQG-metric ball. Moreover, for each t > 0, the boundaries of the connected components of $\mathbb{C} \setminus \overline{\Lambda}_t(0)$ are Jordan curves.

We remark that the harmonic balls given by Theorem 1.1 are locally determined by μ_h , in the sense of the following statement.

Proposition 1.3. For each fixed $t \ge 0$ and $x \in \mathbb{C}$, the closed LQG harmonic ball $\overline{\Lambda}_t(x)$ is a local set for h in the sense of [81, Lemma 3.9], that is, for each deterministic open set $U \subset \mathbb{C}$, the event $\{\overline{\Lambda}_t(x) \subset U\}$ is measurable with respect to $\sigma(h|_U)$.

1.3 | Background

We provide some context and motivation for the study of harmonic balls on LQG surfaces.

1.3.1 | Harmonic balls

The term "harmonic ball" was coined by Shahgholian-Sjödin in [82] and is a special case of *quadrature domains* for harmonic functions. A quadrature domain is a subset of \mathbb{C} for which the integral of a harmonic function can be expressed as a sum of simpler functionals (such as point evaluations). Quadrature domains have a long history and are closely related to classical balayage (sweeping) [19], Hele–Shaw flow [30], obstacle problems [79], and Laplacian growth [60, 91]. We direct the interested reader to [27, 29] and the introductions of the theses of Roos [76] and Sjödin [87] for excellent expositions.

Of particular relevance to our work are the papers of Hedenmalm–Shimorin [41] and Gustafsson–Roos [28] that construct and analyze harmonic balls on Riemannian manifolds. Hedenmalm–Shimorin, building upon the work of Sakai [78], show that harmonic balls on sufficiently smooth hyperbolic surfaces have boundaries that are the unions of a finite number of real analytic simple curves. Gustafsson-Roos show that harmonic balls and geodesic balls coincide on Riemannian surfaces if and only if the Gaussian curvature of the manifold is constant. We emphasize that while some of the basic constructions in these works may be adapted to our setting, an LQG surface is not a Riemannian manifold in the literal sense, and so, the results do not apply.

1.3.2 | Internal DLA

One of our main motivations for studying LQG harmonic balls stems from a connection with IDLA on random planar maps. IDLA was introduced as a toy model for chemical corrosion in [65] and is a special case of a growth model studied by Diaconis–Fulton in [16]. IDLA is a random aggregation model defined as follows: start with n walkers at the origin in \mathbb{Z}^2 and let each walker evolve according to a simple random walk until it reach a site in \mathbb{Z}^2 not occupied by any previous walker. This rule generates a growing sequence of sets $A_n \subset \mathbb{Z}^2$ indexed by the number of walkers $n \in \mathbb{N}$.

In a foundational work, Lawler–Bramson–Griffeath proved that A_n , suitably rescaled, converges to a Euclidean ball in \mathbb{R}^2 as *n* goes to infinity [55, 56]. Later, Asselah–Gaudillère [3, 4] and independently Jerison–Levine–Sheffield established logarithmic fluctuations of A_n around its limit [46–48].

Implicit in the proof of Lawler–Bramson–Griffeath is that harmonic balls are Euclidean balls when μ is the Lebesgue measure — a simple proof of this was given by Ülkü Kuran in 1972 [54]. Interestingly, the connection between IDLA and quadrature domains generalizes. Levine–Peres showed in [59] that the scaling limit of IDLA for any initial condition (e.g., multiple-point sources) is given by a corresponding quadrature domain.

IDLA has also been studied on several other graphs including: Cayley graphs of groups with polynomial [10] and exponential [11, 44] growth, supercritical percolation clusters [21, 85], Sierpinski gasket graphs [15], and cylinders [49, 61, 86]— see [80] for a thorough survey of IDLA. In each of these cases, the limit shape is either a Euclidean ball or a metric ball. On the other hand, Asselah–Rahmani showed that IDLA on the comb lattice has a limit shape that is neither a Euclidean ball nor a metric ball but rather a domain that satisfies a certain mean-value property [5] (see also [45]). In a similar vein, Lucas has shown that IDLA with biased random walkers on \mathbb{Z}^d converges under parabolic scaling to a domain that satisfies the mean-value property for caloric functions [62].

1.3.3 | Random planar maps

A *planar map* is a graph embedded in \mathbb{C} in such a way that no two edges cross, viewed modulo orientation preserving homeomorphisms $\mathbb{C} \to \mathbb{C}$. Various types of random planar maps are expected, and in some cases proven, to converge to γ -LQG surfaces. For example, uniform random planar maps (including uniform triangulations, quadrangulations, etc.) converge to $\sqrt{8/3}$ -LQG surfaces in the Gromov–Hausdorff sense [58, 66, 69, 70] and, at least in the case of triangulations, when embedded into \mathbb{C} via the so-called *Cardy embedding* [42]. Similar convergence results are expected to hold for various types of nonuniform random planar maps toward γ -LQG with $\gamma \neq \sqrt{8/3}$. For example, random planar maps sampled with probability proportional to the number of spanning trees they admit are expected to converge to $\sqrt{2}$ -LQG. We refer to [34] for a survey of work relating random planar maps and LQG.

The aforementioned results on IDLA suggest that the scaling limits of IDLA on random planar maps are described by harmonic balls on LQG surfaces. Random walks on (reasonably embedded) random planar maps are also expected to converge to (time changes of) Brownian motions on LQG surfaces — this has recently been proven for a one-parameter family of random planar maps called mated-CRT maps in [7, 38]. In a companion work [12], we verify that the scaling limit of IDLA on mated-CRT maps is given by LQG harmonic balls. It is still an open problem to prove this for other random planar map models, for example, uniform random planar maps (see Problem 1).

1.4 | Open problems

We collect some questions suggested by this work. The first has been mentioned previously and is arguably the most important question here.

Problem 1. Show that the scaling limit of IDLA on random planar maps in the appropriate γ -LQG universality class, other than mated-CRT maps, is described by γ -LQG harmonic balls. For example, on a uniform planar map show that the scaling limit of IDLA is a $\sqrt{8/3}$ -LQG harmonic ball.

Possible topologies of convergence in Problem 1 include a version of the Gromov–Hausdorff distance for metric spaces decorated by compact sets; or convergence of the IDLA clusters w.r.t. the Hausdorff distance when the random planar map is embedded into \mathbb{C} appropriately. There are also some purely continuum directions one could pursue — the following is an example.

Problem 2. Compute the Hausdorff dimension of the boundary of an LQG harmonic ball, with respect to the Euclidean metric and with respect to the LQG metric.

We expect that the Euclidean and LQG dimensions of the harmonic ball boundary are each strictly greater than one. We note that the Hausdorff dimensions of the boundary of an LQG metric ball with respect to the Euclidean and LQG metrics have been computed in [32, 40].

It is also of interest to determine the analogue of LQG metric geodesics in the setting of harmonic balls. In particular, we are interested in extending the theory of "Hele–Shaw geodesics," in the sense of [41], to our setting. As mentioned previously, Hedenmalm–Shimorin in [41] investigated harmonic balls on smooth Riemannian surfaces and showed that their boundaries are piecewise smooth curves. Because of this smoothness, they were able to define *Hele–Shaw geodesics* as a family of curves originating from a fixed point that are orthogonal to the boundary of a harmonic ball at any point. One may think of these geodesics as describing the trajectory of a single fluid particle started at a fixed point on a Riemannian surface. As LQG harmonic balls do not have smooth boundaries, it is unclear how to adapt this to our setting, but a weaker version of these objects may exist.

Problem 3. Construct and analyze the analogue of "Hele-Shaw geodesics" [41] on LQG surfaces.

A helpful intermediate step would be to show some additional regularity of harmonic balls. For example, the harmonic balls we construct are monotone in t but we are unable to show *strict* monotonicity in t.

Problem 4. Prove or disprove that the family of harmonic balls $\{\Lambda_t(0)\}_{t>0}$, given by Theorem 1.1, is strictly monotone in *t*, that is, $\overline{\Lambda_s}(0) \subset \Lambda_t(0)$ whenever s < t.

1.5 | Paper and proof outline

We start in Section 2 by reviewing the definition of the GFF, LQG, and some results about Liouville Brownian motion. We then introduce the fundamental obstacle problem which we use to construct candidate harmonic balls, *clusters*, in Section 3 and establish some basic properties of the constructed clusters in Section 4. Roughly, for each t > 0, the cluster $\Lambda_t := \Lambda_t(0)$ is defined as the support of the solution to an obstacle problem, $v_t : B_1 \to \mathbb{R}$, specifically,

$$\Lambda_t = \{x \in B_1 : v_t > 0\} \text{ where } v_t = \inf\{w \in C(\overline{B_1}) : \Delta w \leq \mu_h - t\delta_0 \text{ in } B_1 \text{ and } w \geq 0 \text{ in } \overline{B_1}\}.$$

Since the obstacle problem is restricted to the unit ball, it is easy to show existence and uniqueness of solutions. In particular, the results of Sections 3 and 4 are straightforward extensions of those appearing in the obstacle problem literature — the only property of the LQG measure that is used there is that it is a Radon measure with certain volume growth bounds, Lemma 2.4 below.

While it is relatively easy to show the existence of clusters, it is not immediate that clusters are harmonic balls. As we will see in Lemma 4.3 below, Λ_t is a harmonic ball only if $\overline{\Lambda_t} \subset B_1$ and $\mu_h(\partial \Lambda_t) = 0$. It is not clear a priori that these hold for any t > 0. These properties, namely, that the clusters do not attain a large Euclidean diameter in an arbitrarily small amount of time and that the boundaries of the clusters have zero LQG mass, do not follow from standard arguments, and are not true for the obstacle problem with an arbitrary Radon measure. Proving this thus requires input from the theory of LQG and is thus the main goal of Sections 5–8.

In Section 5, we outline a strategy for showing that the clusters are harmonic balls; that is, they grow continuously and their boundaries have zero LQG mass. Our approach for verifying these properties is completely new and relies on a novel *Harnack-type estimate*, Proposition 6.1, which clusters must satisfy. In particular, this estimate forces clusters to have "no thin-tentacles," as in [47]. Roughly speaking, our Harnack-type estimate says that there is a constant $\alpha > 0$ such that if $A \subset \mathbb{C}$ is an annulus on which the LQG measure μ_h is reasonably well behaved, then if the cluster Λ_t crosses between the inner and outer boundaries of A, we must have $\mu_h(A \cap \Lambda_t) \ge \alpha \mu_h(A)$. Our proof of the Harnack-type estimate in Section 6 combines potential-theoretic techniques with methods from LQG theory. See the beginning of Section 6 for an outline of the argument.

In Sections 7 and 8, respectively, we use the Harnack-type estimate to prove that the clusters grow continuously in time, Proposition 7.2, and that boundaries of the clusters have measure zero, Proposition 8.1. As demonstrated in Theorem 5.5, these properties are enough to ensure that clusters are LQG harmonic balls.

Having constructed LQG harmonic balls, we show, by adapting ideas from the obstacle problem literature [77], their uniqueness, Proposition 5.6, in Section 9.

The Harnack-type estimate imposes strong geometric constraints on LQG harmonic balls. For instance, it disallows LQG harmonic balls from "crossing" annuli too many times, Lemma 10.1. We use this in Section 10 to show that the boundaries of complementary connected components of LQG harmonic balls are Jordan curves, Proposition 10.6.

These geometric constraints may also be translated into a strong relationship between LQG harmonic balls and the underlying LQG area measure, Lemma 11.6. Since the LQG measure is quite variable, this imposes an irregularity on LQG harmonic balls. We use this to show that LQG harmonic balls do not satisfy the cone condition, Lemma 11.5, in Section 11.1. Consequently, LQG harmonic balls cannot be Lipschitz domains.

Another feature of the Harnack-type estimate is that it precludes LQG harmonic balls from having "approximate pinch points" that have small Euclidean diameter but that come close to disconnecting sets of large LQG mass from the origin within the cluster. On the other hand, an LQG metric ball has such approximate pinch points, as we show in Section 11.3. This shows that LQG harmonic balls are not LQG metric balls. A key technical input in the proof is Proposition 11.9, which shows that a region in the plane can have small LQG diameter but large LQG mass simultaneously with positive probability.

1.6 | Notation and conventions

- · Inequalities/equalities between functions/scalars are interpreted pointwise.
- Differential inequalities/equalities are interpreted in the distributional sense.
- For a set A ⊂ C, ∂A denotes its topological boundary, A = A ∪ ∂A its closure, and int(A) its interior.
- For two sets $A, B \subset \mathbb{C}$, say that $A \in B$ if $\overline{A} \subset B$.
- *B_r(x)* denotes the open ball of Euclidean radius *r* > 0 centered at *x* ∈ C, when *x* is omitted, the ball is centered at 0.
- For a set $A \subset \mathbb{C}$, we denote the *r*-neighborhood of A by $B_r(A) = A + B_r$.
- For $0 < r_1 < r_2$, denote an open annulus centered at *z* by

$$A_{r_1,r_2}(z) = B_{r_2}(z) \setminus \overline{B}_{r_1}(z)$$
(1.4)

and $\mathbb{A}_{r_1, r_2} := \mathbb{A}_{r_1, r_2}(0).$

- Let $\{E^r\}_{r>0}$ be a one-parameter family of events. We say that E^r occurs with polynomially high probability as $r \to 0$ if there exists p > 0 such that $\mathbb{P}[E^r] \ge 1 O(r^p)$.
- For two sets A, B ⊂ C, dist(A, B) = inf_{a∈A,b∈B} dist(a, b) where dist denotes the Euclidean distance between two points.

2 | PRELIMINARIES

In this section, we review the definitions and basic properties of the GFF, the Liouville quantum gravity (LQG) area measure, and the LQG metric. We present just enough exposition for the purposes of this paper; the book [8] and surveys [18, 33, 83] provide more details.

2.1 | Gaussian free field

The whole-plane GFF $h^{\mathbb{C}}$ is the centered Gaussian random generalized function on \mathbb{C} with covariances

$$\mathbf{Cov}(h^{\mathbb{C}}(z), h^{\mathbb{C}}(w)) := \log \frac{\max(|z|, 1) \max(|w|, 1)}{|z - w|}, \quad \forall z, w \in \mathbb{C}.$$
 (2.1)

The GFF $h^{\mathbb{C}}$ is not well-defined pointwise since the covariance kernel in (2.1) diverges to ∞ as $z \to w$. Nevertheless, for $z \in \mathbb{C}$ and r > 0, one can define the average of $h^{\mathbb{C}}$ over the circle of radius r centered at z, which we denote by $h_r^{\mathbb{C}}(z)$ [23, Section 3.1].

The whole plane GFF is usually defined modulo additive constant. Our choice of covariance in (2.1) corresponds to fixing this additive constant so that $h_1^{\mathbb{C}}(0) = 0$ (see, e.g., [90, Section 2.1.1]).

The law of the whole-plane GFF, viewed modulo additive constant, is invariant under complex affine transformations of \mathbb{C} . This translates into the following invariance property for $h^{\mathbb{C}}$,

$$h^{\mathbb{C}} \stackrel{d}{=} h^{\mathbb{C}}(a \cdot +b) - h^{\mathbb{C}}_{|a|}(b), \quad \forall a \in \mathbb{C} \setminus \{0\}, \quad \forall b \in \mathbb{C}.$$
(2.2)

Fix $\gamma \in (0, 2)$ and $\alpha_0 \in (-\infty, Q)$, where

$$Q := \frac{2}{\gamma} + \frac{\gamma}{2}.$$
(2.3)

Throughout this paper, we take *h* to be the whole-plane GFF with an α_0 log singularity at the origin.

Specifically, let $h^{\mathbb{C}}$ denote the whole-plane GFF normalized so that its circle average over the unit disk is zero and set

$$h = h^{\mathbb{C}} - \alpha_0 \log |\cdot|. \tag{2.4}$$

It is immediate from (2.2) that

$$h \stackrel{d}{=} h(a \cdot) - h_{|a|}, \quad \forall a \in \mathbb{C} \setminus \{0\}.$$

$$(2.5)$$

2.2 | Liouville quantum gravity

Let μ_h denote the γ -LQG area (Liouville) measure associated to h. One of the (many) possible ways of defining μ_h is as the a.s. weak limit

$$\mu_h = \lim_{\epsilon \to 0} \epsilon^{\gamma^2/2} e^{\gamma h_\epsilon(z)} \, dz, \tag{2.6}$$

where dz denotes Lebesgue measure and $h_{\epsilon}(z)$ is the circle average [23, 84]. In fact, the measure $\mu_{\tilde{h}}$ exists for any random generalized function \tilde{h} of the form h + f where f is a possibly random continuous function.

Fact 2.1 (LQG measure). The LQG area measure μ_h satisfies the following properties.

- I. **Radon measure.** A.s., μ_h is a nonatomic Radon measure.
- II. **Locality.** For every deterministic open set $U \subset \mathbb{C}$, $\mu_h(U)$ is given by a measurable function of $h|_U$.
- III. Weyl scaling. A.s., $e^{\gamma f} \cdot \mu_h = \mu_{h+f}$ for every continuous function $f : \mathbb{C} \to \mathbb{R}$.
- IV. Conformal covariance. A.s., the following is true. Let $U, \tilde{U} \subset \mathbb{C}$ be open and let ϕ be a conformal map from \tilde{U} to U. Then, with Q as in (2.3),

$$\mu_{h\circ\phi+Q\log|\phi'|}(A) = \mu_h(\phi(A)) \quad \text{for all Borel measurable } A \subset \tilde{U}.$$
(2.7)

The first three properties in Fact 2.1 are immediate from the definition (2.6). The conformal covariance property was proven to hold a.s. for a fixed conformal map in [23, Proposition 2.1] and extended to all conformal maps simultaneously in [84].

It was shown in [17, 37] that one can define also the *LQG metric* D_h , which is the limit of regularized versions of the Riemannian distance function associated with the Riemannian metric tensor $e^{\gamma h}(dx^2 + dy^2)$. Like the LQG measure, the LQG metric is a fractal-type object. It induces the same topology on \mathbb{C} as the Euclidean metric, but the Hausdorff dimension of the metric space (\mathbb{C}, D_h) is a.s. given by a deterministic number $d_{\gamma} > 2$ [39, Corollary 1.7]. The value of d_{γ} is not known explicitly except that $d_{\sqrt{8/3}} = 4$ [57].

In order to state an analog of Fact 2.1 for the LQG metric, we make the following definitions. For a Euclidean-continuous path P in \mathbb{C} , we write $len(P; D_h)$ for its length with respect to D_h . For an open set $U \subset \mathbb{C}$, the *internal metric of* D_h on U is defined by

$$D_h(z, w; U) = \inf\{\operatorname{len}(P; D_h) : P \text{ is a path from } z \text{ to } w \text{ in } U\}, \quad \forall z, w, \in U.$$
(2.8)

As in the case of the measure, the metric $D_{\tilde{h}}$ exists whenever $\tilde{h} = h + f$, where f is a possibly random continuous function.

Fact 2.2 (LQG metric). The LQG metric D_h has the following properties.

- I. Euclidean topology and length metric. A.s., D_h induces the same topology on \mathbb{C} as the Euclidean metric and is a length metric, that is, $D_h(z, w)$ is the infimum of the D_h -length of paths from z to w.
- II. Locality. For every deterministic open set $U \subset \mathbb{C}$, the D_h -internal metric on U is given by a measurable function of $h|_U$.
- III. Weyl scaling. Let

$$\xi = \frac{\gamma}{d_{\gamma}},\tag{2.9}$$

where d_{γ} is the Hausdorff dimension of the γ -LQG metric as above. Almost surely, for every continuous function $f : \mathbb{C} \to \mathbb{R}$,

$$D_{h+f}(u,v) = \inf_{P: u \to v} \int_0^{\operatorname{len}(P;D_h)} e^{\xi f(P(t))} dt, \quad \forall u, v \in \mathbb{C}.$$

IV. Coordinate change for scaling and translation. Let r > 0 and $z \in C$. Almost surely, with Q as in (2.3),

$$D_h(ru+z, rv+z) = D_{h(r+z)+O\log r}(u, v), \quad \forall u, v, \in C.$$

The properties listed in Fact 2.2 were verified for the LQG metric in [17, 20, 37]. In fact, it is shown in [37] that these properties uniquely characterize D_h .

In what follows, for sets $A, B \subset \mathbb{C}$, we write

$$D_h(A,B) = \inf_{x \in A, y \in B} D_h(x,y).$$
 (2.10)

For disjoint compact sets $K_1, K_2 \subset \mathbb{C}$, a D_h -geodesic from K_1 to K_2 is a path from K_1 to K_2 of minimal D_h -length. It is easily seen from the length metric property and a compactness argument that D_h -geodesics always exist (see, e.g., [13, Corollary 2.5.20]).

2.3 | Green's function

Let $G_O : \overline{O} \times \overline{O} \to \mathbb{R} \cup \{\infty\}$ denote the Green's function for standard Brownian motion killed upon exiting a bounded open set $O \subset \mathbb{C}$. We make use of the following standard properties of the Green's function of a (sufficiently nice) set.

Proposition 2.3. The Green's function of a ball, B_R of radius R > 0, has the following properties for every $x \in B_R$.

- Fundamental solution: $\Delta G_{B_R}(x, \cdot) = -\delta_x(\cdot)$ on B_R .
- Positive: $G_{B_R}(x, \cdot) > 0$ on B_R .
- Zero boundary: $G_{B_R}(x, \cdot) = 0$ on ∂B_R .
- Smooth away from the pole: $G_{B_p}(x, \cdot)$ is infinitely differentiable away from x.

2.4 | Liouville potential theory

In this section, we collect well-known potential theoretic estimates on the LQG measure. We first note bounds on the LQG mass of annuli and balls.

Lemma 2.4. For each $\beta^+ \in (0, (2 - \gamma)^2/2)$ and $\beta^- > (2 + \gamma)^2/2$, it holds with polynomially high probability as $\epsilon \to 0$ that

$$\varepsilon^{\beta^-} \leq \mu_h(B_{\varepsilon}(z)) \leq \varepsilon^{\beta^+}, \quad \forall z \in B_1.$$
 (2.11)

Furthermore, for each $0 < r_1 < r_2$, there exists constants C_1, C_2 so that for all $z \in B_1$

$$C_2 \epsilon^{\beta^-} \leq \mu_h(\mathbb{A}_{r_1 \epsilon, r_2 \epsilon}(z)) \leq C_1 \epsilon^{\beta^+}$$
(2.12)

with polynomially high probability as $\epsilon \to 0$, where here we use the notation for annuli from (1.4).

Proof. Exactly the same argument as in [7, Lemma A.1] shows that (2.11) holds with polynomially high probability as $\epsilon \to 0$. The estimate (2.12) follows from (2.11) and the fact that

$$B_{\frac{r_2-r_1}{4}\epsilon}(z+\frac{r_2\epsilon+r_1\epsilon}{2}e_1)\subset \mathbb{A}_{r_1\epsilon,r_2\epsilon}(z)\subset B_{r_2\epsilon}(z),$$

where $e_1 = (1, 0)$.

Liouville Brownian motion (LBM) is the natural diffusion associated with γ -LQG. Roughly speaking, LBM is obtained from ordinary Brownian motion (sampled independently from *h*) by changing time so that the process has "constant γ -LQG speed." LBM was constructed in [6, 25]. It was shown in [7] to describe the scaling limit of random walk on a certain family of random planar maps.

The volume growth bounds given by Lemma 2.4 lead to control on the expected exit time of LBM from balls.

Proposition 2.5. Let O denote a smooth bounded open set. The expected exit time of LBM from O started at $x \in O$ is finite and Hölder continuous in x. More generally, any q of the form,

$$q(x) = \int_{O} G_{O}(x, y) f(y) d\mu_{h}(y) \quad \text{for some } f \in L^{\infty}(\overline{O})$$

is finite and Hölder continuous in \overline{O} .

Proof. Finiteness follows immediately from Lemma 2.4. Hölder continuity uses the embedding of Campanato spaces into Hölder spaces together with Lemma 2.4. See, for example, Section 16.2 (or the remark after Proposition 13.5) in [73]. □

The bounds also lead to continuity of the LBM heat kernel using the main result of [52]. Continuity of the LBM heat kernel (for other versions of the GFF) was previously established by [1] and [63].

Let *K* be a square in \mathbb{C} and for $x \in \mathbb{C}$, let $\{B_t^x\}_{t>0}$ denote γ -LBM with respect to the field *h* started from *x* with Neumann (reflecting) boundary conditions on *K*. The heat kernel p_t^K of reflected LBM in *K* is the function $p_t^K(x, y) : (0, \infty) \times K \times K \to [0, \infty)$ such that

$$\mathbb{P}[\mathcal{B}_t^x \in dy|h] = p_t^K(x, y)dy.$$
(2.13)

Proposition 2.6. Let K be a square in \mathbb{C} . Almost surely, the heat kernel $p_t^K(x, y)$ associated to γ -LBM with Neumann boundary conditions on K exists, is finite, jointly continuous, and strictly positive for all $(t, x, y) \in (0, \infty) \times K \times K$.

Proof. This is [52, Theorem 13.1] with input given by Lemma 2.4. Strictly speaking, [52, Theorem 13.1] concerns the transition density of reflecting γ -LBM in the unit square. A scaling argument shows that [52, Theorem 13.1] applies to the transition density of reflecting γ -LBM in any fixed square.

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3 | CONSTRUCTION OF CANDIDATE HARMONIC BALLS VIA HELE-SHAW FLOW

In this section, we construct domains which we will later show are γ -LQG harmonic balls. Specifically, we construct a family of sets $\{\Lambda_t(z)\}_{t>0}$ via an obstacle problem involving the Green's function for the ball. This family of sets models the flow of a Newtonian fluid injected at a constant rate into an LQG surface, restricted to a ball on the surface. The movement of this fluid is called *Hele–Shaw flow*. As exposited in [30, Chapter 3], one way of defining Hele–Shaw flow mathematically is via the obstacle problem construction below. The construction itself is fairly standard see, for example, [26, 41, 82] and originates from the work of Sakai [79].

While the construction is standard, since the obstacle problem is restricted to a ball, it is not obvious that the construction gives γ -LQG harmonic balls. We will later show, using LQG specific arguments, the existence of T > 0 so that $\{\Lambda_t\}_{0 < t < T}$ are a family of harmonic balls satisfying the conditions in Theorem 1.1. We then use scale invariance and compatibility to extend this construction to all t > 0.

3.1 | Definition of the obstacle problem

We construct candidate harmonic balls via a technique similar to the Perron method involving the measure μ_h and the Green's function for the ball. For each t, r > 0 and $z \in B_r$, the set of *supersolutions* is

$$S_t^{B_r;z} = \{ w \in C(\overline{B_r}) : \Delta w \leq \mu_h \text{ in } B_r \text{ and } w \geq -tG_{B_r}(z, \cdot) \text{ in } \overline{B_r} \},$$
(3.1)

where $C(\overline{B_r})$ denotes the set of continuous functions on the closed ball. The *least supersolution* is defined as the pointwise infimum of all functions in $S_t^{B_r}$,

$$w_t^{B_r;Z} = \inf\left\{w \in \mathcal{S}_t^{B_r;Z}\right\}$$
(3.2)

and the cluster as

$$\Lambda_t^{B_r;z} = \{ x \in B_r : w_t^{B_r;z}(x) > -tG_{B_r;z}(z,x) \}.$$
(3.3)

We also consider the odometer

$$v_t^{B_r;z} = w_t^{B_r;z} + tG_{B_r;z}(0,\cdot).$$
(3.4)

Note that $S_t^{B_r;z}$ is nonempty as it contains the zero function — thus $w_t^{B_r;z}$ always exists. This equation in (3.1) is known as an *obstacle problem* with obstacle given by the Green's function. When B_r is the unit ball, we write, for example, S_t^z , and if additionally z = 0, we write, for example, S_t .

We think of the above obstacle problem as modeling the flow of liquid on a rough surface. A mass *t* of fluid is injected at $\{z\}$ and its growth is dictated by the infinitesimal capacity of the surface, namely, the measure μ_h . The cluster Λ_t^z represents the settled fluid and v_t^z captures the "work" needed to spread the fluid. Specifically, the family of sets $\{\Lambda_t^z\}_{t>0}$ is a weak solution to a *restricted Hele–Shaw problem* involving the measure μ_h . The Hele–Shaw problem is restricted because of the fact that (3.1) is only defined in the ball B_r . Physically what this means is that the flow is stopped upon exiting B_r . The obstacle problem (3.1) is a variational formulation of this restricted Hele–Shaw problem. See [30, Section 3.5] and [76] for an explicit description of the Hele–Shaw equation and how the obstacle problem relates to it.

From the physical picture described in the previous paragraph, one expects that if *t* is larger than $\mu_h(B_r)$, then Λ_t should fill the entire ball. Moreover, if μ_h is regular enough, then for *t* small the clusters should be strictly contained in B_r . Further, clusters with closures that do not intersect the boundary of B_r should be compatible with clusters restricted to $B_{r'}$ for r' < r. We provide rigorous statements of these heuristics below.

3.2 | Basic properties of the obstacle problem

We assert existence and basic regularity of solutions to the obstacle problem. These results are standard but for completeness are proved in the Appendix.

We first note that the least supersolution is indeed a supersolution.

Lemma 3.1. On an event of probability 1, for all t, r > 0 and $z \in B_r$, $w_t^{B_r;z}$ is finite, continuous, and an element of $S_t^{B_r;z}$.

The next lemma is a consequence of being the least supersolution.

Lemma 3.2. On an event of probability 1, for all t, r > 0, and $z \in B_r$, the cluster $\Lambda_t^{B_r;z}$ is open and connected and

$$\Delta w_t^{B_r;z} = \mu_h|_{A_t^{B_r;z}} + \nu|_{\partial A_t^{B_r;z}} \quad on \ B_r,$$

where ν is a Radon measure that is absolutely continuous with respect to μ_h on B_r and satisfies $0 \leq \nu \leq \mu_h$ on B_r . In particular,

$$\Delta v_t^{B_r;z} = -t\delta_z + \mu_h|_{A_t^{B_r;z}} + \nu|_{\partial A_t^{B_r;z}} \quad on \, B_r.$$

We will eventually show that on an event of probability one, $\mu_h(\partial \Lambda_t^{B_r;z}) = 0$ for all t, r > 0and $z \in B_r$, which implies that $\nu = 0$. However, for the time being we need to allow for the possibility that there is some mass on $\partial \Lambda_t^{B_r;z}$.

We also have monotonicity of the clusters in *t*.

Lemma 3.3. On an event of probability 1, for all $t_1 \leq t_2$ and r > 0, $z \in B_r$, we have $\Lambda_{t_1}^{B_r} \subseteq \Lambda_{t_2}^{B_r}$.

Clusters also have a conservation of mass property.

Lemma 3.4. On an event of probability 1, for all r, t > 0 and $z \in B_r$, we have $\mu_h(\Lambda_t^{B_r;z}) \leq t$ and $v_t^{B_r;z} = 0$ on ∂B_r . Moreover, if $\overline{\Lambda_t^{B_r;z}} \subset B_r$ and $\mu(\partial \Lambda_t^{B_r;z}) = 0$, then $\mu_h(\Lambda_t^{B_r;z}) = t$.

We conclude with a compatibility result for clusters across different domains.

Lemma 3.5. The following holds for each R > 0 on an event of probability 1. For all $s_1 \le R$ and $z \in B_{s_1}$ if, for some $s_2 \in [s_1, R]$, we have $\overline{\Lambda_t^{B_{s_2};z}} \subset B_{s_1}$, then $\Lambda_t^{B_{s_1};z} = \Lambda_t^{B_{s_2};z}$ for all $s \in [s_1, R]$.

4 | **BASIC PROPERTIES OF CLUSTERS**

In this section, we note some basic properties of the clusters $\{A_t\}_{t>0}$ and odometers $\{v_t\}_{t>0}$. As in Section 3, these results are fairly standard, for example, [26, 41, 79, 82], but (short) proofs are included for completeness.

4.1 | Lower bound

We first show that each cluster contains a Euclidean ball of sufficiently small radius and eventually the family coincides with the unit ball.

Proposition 4.1. On an event of probability 1, for each t > 0 and $z \in B_1$, there exists a random $\epsilon = \epsilon(t) > 0$ so that

$$B_{\varepsilon}(z) \subset \Lambda_t^z. \tag{4.1}$$

Moreover, for each $\delta \in (|z|, 1)$, there exists a random $t(\delta) > 0$ such that for all $t \ge t(\delta)$,

$$B_{1-\delta}(z) \subset \Lambda_t^z \tag{4.2}$$

and there exists a random $t^+ > 0$ so that for all $t \ge t^+$

$$\overline{\Lambda_t^z} \cap \partial B_1 \neq \emptyset. \tag{4.3}$$

Our proof uses the fact that the logarithm function blows up near the origin together with the finiteness of the expected exit time of Liouville Brownian motion (LBM) from the unit ball.

Proof of Proposition 4.1. Let $q_1(y)$ denote the expected exit time of LBM started at a point y from the unit ball,

$$\begin{cases} \Delta q_1 = -\mu_h & \text{in } B_1 \\ q_1 = 0 & \text{on } \partial B_1 \end{cases}$$

Let t > 0 and $z \in B_1$ be given. As $\Delta w_t^z \leq \mu_h$ (Lemma 3.1), the function $w_t^z + q_1$ is superharmonic in B_1 . Hence, as $w_t^z + q_1 \geq 0$ on ∂B_1 , we have $w_t^z \geq -q_1$ in $\overline{B_1}$. Since

$$\lim_{\epsilon \to 0} \sup_{x \in B_{\epsilon}(z)} t \log |x - z| \to -\infty,$$

we have that

$$w_t^z(x) \ge -q_1(x) > t \log |x - z|, \quad \forall x \in B_{\varepsilon}(z), \quad \forall \varepsilon > 0 \text{ sufficiently small.}$$
 (4.4)

Indeed, by Proposition 2.5, q_1 is finite. By the definition (3.3) of Λ_t^z and the fact that $G_{B_1}(z, x) = O(-\log |z - x|)$, this shows that $B_{\epsilon}(z) \subset \Lambda_t^z$. Similarly, for each $\delta \in (|z|, 1)$, for all $t > t(\delta)$, (4.4) is satisfied for all $x \in B_{1-\delta}(z)$. The last assertion follows by choosing $t^+ = \mu_h(B_1)$ and using Lemma 3.4.

4.2 | Hölder continuity of the odometer

We observe that w_t is Hölder for a deterministic exponent depending only on γ .

Lemma 4.2. There exists a deterministic exponent $\alpha = \alpha(\gamma)$ so that on an event of probability 1, there exists a constant C > 0

$$|w_t^z(x) - w_t^z(y)| \le C|x - y|^{\alpha}$$

for all t > 0, $z \in B_1$, and $x, y \in B_1$.

Proof. By Lemma 3.2, $\Delta w_t^z = \mu_h |_{A_t^z} + \nu |_{\partial A_t^z}$ and ν is absolutely continuous with respect to μ_h in B_1 . Thus, the claim follows by Proposition 2.5.

4.3 | Nondegenerate clusters are subharmonic balls

We prove that clusters that do not intersect the boundary of B_1 are harmonic balls. In fact, we observe a stronger property — each Λ_t^z strictly contained in B_1 is a subharmonic ball. That is, subharmonic functions satisfy the submean-value property on such Λ_t^z .

Specifically, for $z \in \mathbb{C}$, an open set $\Lambda(z)$ is a *subharmonic ball* centered at $z \in \mathbb{C}$ with respect to a Radon measure μ if

$$\mu(\Lambda(z))f(z) \leq \int_{\Lambda(z)} f(x)\mu(dx)$$
(4.5)

for all functions $f : \overline{O} \to \mathbb{R}$ of the form

$$f(x) = \int_{O} G_{O}(x, y) d\nu(y) + q(x)$$
(4.6)

where *O* is an open set containing a neighborhood of the closure of $\Lambda(z)$, ν is a signed Radon measure, $\nu|_{\Lambda(z)} \leq 0$, with compact support in *O*, and $q : \overline{O} \to \mathbb{R}$ is a harmonic function on *O*.

We note that every subharmonic ball is a harmonic ball in the sense described just above Theorem 1.1. Indeed, the set of harmonic functions in the definition of a harmonic ball (as described above Theorem 1.1) is the same as the set of functions f of the form (4.6) with $\nu|_{\Lambda(z)} = 0$. Since this set of functions is closed under replacing f with -f, the inequality (4.5) gives both the submean-value property and the super-mean-value property for functions in this set.

Lemma 4.3. On an event of probability 1, for all r, t > 0 and $z \in B_r$, if $\overline{\Lambda_t^{B_r;z}} \subset B_r$ and $\mu_h(\partial \Lambda_t^{B_r;z}) = 0$, then $\Lambda_t^{B_r;z}$ is a subharmonic ball.

We do not know a priori that the hypotheses $\overline{\Lambda_t^{B_r;z}} \subset B_r$ and $\mu_h(\partial \Lambda_t^{B_r;z}) = 0$ are satisfied for any value of t, r > 0 with $z \in B_r$. We will prove that these hypotheses are satisfied, at least when t depending on r, z is small, in Sections 7 and 8, respectively. In fact, we will show some uniformity in z of how small t needs to be. By the Riesz decomposition theorem, see, for example, [2, Section 4], functions of the form (4.6) include functions that are subharmonic in a neighborhood of \overline{O} .

Proof of Lemma 4.3. Let $r, t > 0, z \in B_r$, an open set $O \supset \overline{\Lambda_t^{B_r;z}}$, and f, q, ν as in (4.6) be given. By Lemma 3.4, Lemma 3.2, and Proposition 2.3, and our assumption that $\mu_h(\partial \Lambda_t^{B_r;z}) = 0, \Lambda_t^{B_r;z}$ is open and

$$\begin{cases} v_t^{B_r;z} = 0 & \text{on } \partial B_r \\ \Delta v_t^{B_r;z} = -t\delta_z + \mu|_{\Lambda_t^{B_r;z}} & \text{on } B_r, \end{cases}$$
(4.7)

and $\mu_h(\Lambda_t^{B_r;z}) = t$. As $\overline{\Lambda_t^{B_r;z}} \subset O$, we can find a smooth domain Λ_t' with $\Lambda_t^{B_r;z} \subset \Lambda_t' \subset O$ so that

$$0 = \int_{\Lambda_t^{B_r;z}} \Delta q(x) v_l^{B_r;z}(x) dx$$

= $\int_{\Lambda_t'} \Delta q(z) v_l^{B_r;z}(x) dx$ (since $v_l^{B_r;z} = 0$ on $B_r \setminus \Lambda_t^{B_r;z}$)
= $\int_{\Lambda_t'} q(x) \Delta v_l^{B_r;z}(x) dx$ (integration by parts)
= $-tq(z) + \int_{\Lambda_t^{B_r;z}} q(x) \mu_h(dx)$ (by (4.7)).

Moreover,

$$\begin{split} t(f-q)(z) &= \int_{\Lambda_t^{B_r;z}} (f-q)(y) d\mu_h(y) \\ &= \int_{\Lambda_t^{B_r;z}} \int_{\Lambda_t^{B_r;z}} (G_O(z,x) - G_O(y,x)) d\nu(x) d\mu_h(y) \qquad (\text{definition of } f) \\ &= \int_{\Lambda_t^{B_r;z}} \int_{\Lambda_t^{B_r;z}} (G_O(z,x) - G_O(y,x)) d\mu_h(y) d\nu(x) \qquad (\text{by Fubini}) \\ &= \int_{\Lambda_t^{B_r;z}} v_t^{B_r;z}(z) d\nu(x) \qquad (\text{by (4.7)}) \\ &\leqslant 0 \qquad (\text{since } v_t^{B_r;z} \geqslant 0 \text{ and } \nu \leqslant 0). \end{split}$$

We conclude by combining the above two expressions.

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5 | NONDEGENERACY OF THE FLOW

In this section, we set up the proof of our main result Theorem 1.1 by dividing it into several intermediate results that will be proven in Sections 6–9. We then show how these intermediate results imply the claim. In the last subsection, we observe that the clusters which we construct are locally determined in the sense of Proposition 1.3.

5.1 | Properties of the restricted flow

We first show in Section 7 that clusters do not immediately exit the unit ball.

Proposition 5.1. On an event of probability 1, there exists a (random) $T = T(\gamma, h) > 0$ so that for each $z \in B_{1/2}$ and all 0 < t < T

$$\overline{\Lambda_t^z} \subset B_1. \tag{5.1}$$

We show in the second part of Section 7 that the family is continuous.

Proposition 5.2. On an event of probability 1, for all $z \in B_{1/2}$, the cluster centered at z decreases to $\{z\}$,

$$\bigcap_{t>0} \overline{\Lambda}_t^z = \{z\}$$
(5.2)

and continuously increase in t: for each t > 0, for all $\epsilon > 0$ sufficiently small, there exists $\delta(z) > 0$ so that for all $t' \in [t, t + \delta(z)]$,

$$\overline{\Lambda_{t'}^z} \subset \Lambda_t^z + B_{\varepsilon}(z).$$
(5.3)

In Section 8, we show that each cluster has zero boundary area measure.

Proposition 5.3. On an event of probability 1, for all $z \in B_1$ and t > 0 such that $\overline{\Lambda_t^z} \subset B_r(z)$.

$$\mu_h(\partial \Lambda_t^z) = 0. \tag{5.4}$$

In order to ensure exact uniqueness, the family of harmonic balls appearing in our final theorem differs from the above clusters via a set of μ_h -measure zero,

$$\Lambda_t^z := \operatorname{int}(\overline{\Lambda_t^z}), \quad \forall t > 0, z \in B_1.$$
(5.5)

Indeed, by definition, $\Lambda_t \subset \operatorname{int}(\overline{\Lambda_t})$ and as $\mu_h(\partial \Lambda_t) = 0$, $\mu_h(\operatorname{int}(\overline{\Lambda_t}) \setminus \Lambda_t) = 0$. This shows that Λ_t is a subharmonic ball and Propositions 5.1–5.3 hold with Λ_t in place of Λ_t . Thus, we may combine Proposition 4.1, Lemma 4.3, and Propositions 5.1–5.3 into the following statement.

Proposition 5.4. On an event of probability 1, for all r > 0 and $z \in B_{1/2}$, there exists a family of clusters $\{\Lambda_t^z\}_{0 < t < T}$ strictly contained in $\overline{B_1}$ satisfying the conditions of Theorem 1.1 for 0 < t < T and $\overline{\Lambda_T^z} \cap \partial B_1 \neq \emptyset$.

In the next two subsections, we use the compatibility property Lemma 3.5 together with a certain scale invariance of clusters to extend the construction in Proposition 5.4 to the entire plane.

Theorem 5.5. On an event of probability 1, for all $z \in \mathbb{C}$, there exists a family of clusters $\{A_t(z)\}_{t>0}$ satisfying the conditions of Theorem 1.1. Moreover, each cluster is a subharmonic ball related to the

clusters of (3.3) in the following way: if for some $s > 0, z \in \mathbb{C}$, if $\Lambda_t(z) \in B_s$, then $\Lambda_t(z) = int(\Lambda_t^{B_r;z})$ for all $r \ge s$.

In Section 9, we prove that the family given by Theorem 5.5 is the unique such family, completing the proof of Theorem 1.1.

Proposition 5.6. Let $\{\Lambda_t(z)\}_{t>0,z\in\mathbb{C}}$ be given by Theorem 5.5. On an event of probability 1, if for some $z \in \mathbb{C}$, $\{A_t(z)\}_{t>0}$ is a family of harmonic balls satisfying the assumptions in Theorem 1.1, then $A_t(z) = \Lambda_t(z)$ for all t > 0.

5.2 | Scale invariance

We now give the relevant scale invariance property which we then use to prove Theorem 5.5. Specifically, we show that the law of a cluster stopped upon exiting a ball of arbitrary radius coincides with the law of a rescaled cluster that is stopped upon exiting the unit ball.

Lemma 5.7. For each k > 0 and $z \in B_1$, the laws of $\{A_t^z\}_{t>0}$ and $\{k^{-1}A_{A_kt}^{B_k;kz}\}_{t>0}$ coincide, where $A_k := e^{\gamma(Q \log k + h_k(0))}$.

Proof. Let t, k > 0 and $z \in B_1$ be given. Consider the continuous function $\tilde{w}_t \in C(\overline{B_1})$ defined by

$$\tilde{w}_t := A_k^{-1} w_{A_k t}^{B_k; k z}(k \cdot) \qquad \text{on } \overline{B_1}$$
(5.6)

and the fields

$$\tilde{h} = h(k \cdot) + Q \log k$$
, where $Q = \frac{2}{\gamma} + \frac{\gamma}{2}$ (5.7)

and

$$h' = h(k \cdot) - h_k(0), \tag{5.8}$$

where $h_k(0)$ is the average of *h* on the circle of radius *k* around 0. By (2.5), we have $h' \stackrel{d}{=} h$.

We claim that

$$\tilde{w}_t = \tilde{u}_t := \inf\left\{w \in \mathcal{S}_t^{h'}\right\},\tag{5.9}$$

where \tilde{u}_t is the pointwise infimum over the family

$$S_t^{h'} = \{ w \in C(\overline{B_1}) : \Delta w \leqslant \mu_{h'} \text{ in } B_1 \text{ and } w \geqslant -tG_{B_1}(z, \cdot) \text{ in } \overline{B_1} \},$$
(5.10)

defined in the same manner as S but with h' instead of h. Write $S_t^h(B_k)$ when B_1 in (5.10) is replaced by B_k and h' by h.

We first show that $\tilde{w}_t \in S_t^{h'}$. By the fact that $\Delta w_t \leq \mu_h$ (Lemma 3.1), the LQG coordinate change formula, and Weyl scaling (Fact 2.1),

$$\Delta \tilde{w}_t \leqslant A_k^{-1} \mu_h(k \cdot) = \mu_{h'} \quad \text{on } \overline{B_1}.$$
(5.11)

Also, since $w_{A_kt}^{B_k;kz} \in S_{A_kt}^h(B_k)$ and $G_{B_k}(kz,kx) = G_{B_1}(z,x)$,

$$\tilde{w}_{t}(x) \ge -tA_{k}^{-1}A_{k}G_{B_{rk}(z)}(kz,kx) = -tG_{B_{1}}(z,x) \text{ on } \overline{B_{1}}.$$
 (5.12)

Hence, $\tilde{w}_t \in S_t^{h'}$. Similarly, $A_k \tilde{u}_t(\cdot/k) \in S_{A_k t}^h(B_k)$, which shows $\tilde{u}_t = \tilde{w}_t$. Indeed, $A_k \tilde{u}_t(\cdot/k) \leq w_{A_k t}^{B_k}(\cdot)$ implies $\tilde{u}_t(\cdot/k) \leq A_k^{-1} w_{A_k t}^{B_k}(\cdot) = \tilde{w}_t(\cdot/k)$ by (5.6). Hence, as h' has the same law as h,

$$\Lambda_t^z \stackrel{d}{=} \{ x \in B_1 : \tilde{u}_t(x) > -tG_{B_1}(z, x) \} = k^{-1} \Lambda_{A_k t}^{B_k; zk};$$
(5.13)

the last equality uses $\tilde{u}_t = \tilde{w}_t$.

5.3 | Proof of Theorem 5.5 assuming Proposition 5.4

By combining Lemma 5.7 together with Proposition 5.4 and a union bound, on an event of probability 1, for each $k \in \mathbb{N}$, there exists $T^{(k)} > 0$ so that for all $x \in B_{1/2}$, the family of sets

$$\left\{\Lambda_t^{B_k;kx}\right\}_{0 < t < A_k T^{(k)}}$$
(5.14)

is compactly embedded in $\overline{B_{k/2}}$, and $\operatorname{int}(\overline{A_t^{B_k;kx}})$ satisfies the properties of Theorem 1.1 for $t < A_k T^{(k)}$, and $\overline{A_{A_k}^{B_k;kx}} \cap \partial B_k \neq \emptyset$.

Let $z \in \mathbb{C}$ be given, select $k_0 = 3|z|$ (so that there exists $x \in B_{1/2}$ with $k_0 x = z$) and define

$$\Lambda_{t}(z) = \begin{cases} \Lambda_{t}^{B_{k_{0}};z} & \text{for } t < A_{k_{0}}T^{(k_{0})} \\ \Lambda_{t}^{B_{k};z} & \text{if } A_{k-1}T^{(k-1)} \leqslant t < A_{k}T^{(k)} \text{ for some } k \in [k_{0}+1,\infty) \cap \mathbb{N}, \end{cases}$$
(5.15)

and $\Lambda_t(z) = \operatorname{int}(\overline{\Lambda_t(z)})$. By the compatibility property, Lemma 3.5, the times $A_k T^{(k)}$ are increasing in *k* and hence the construction is well defined. Compatibility also implies that the family $\{\Lambda_t\}_{t>0}$ satisfies the properties of Theorem 1.1.

It remains to show that for each t > 0, there exists a $k \in \mathbb{N}$ so that $t < A_k T^{(k)}$. That is, we must show that

$$A_k T^{(k)} \to \infty$$
 with probability 1. (5.16)

Indeed, if this were the case, this would give us a complete family $\{\Lambda(z)\}_{t>0}$ satisfying the properties of Theorem 1.1, and we have uniqueness of such a family by Proposition 5.6.

First note that by Lemma 5.7, $T^{(k)} \stackrel{d}{=} T^{(1)}$ for each k. Since $T^{(1)}$ is strictly positive, for each $p \in (0, 1)$, there exists $c_p > 0$ so that

$$\mathbb{P}[T^{(k)} > c_p] \ge p$$

for all $k \in \mathbb{N}$. In particular,

$$\mathbb{P}[\bigcap_{m=1}^{\infty} \cup_{k=m}^{\infty} T^{(k)} > c_p] \ge p.$$
(5.17)

We claim that also

$$\lim_{k \to \infty} A_k = \infty. \tag{5.18}$$

Indeed, the process,

 $t \rightarrow h_{e^t}(0)$

has a continuous modification that is a standard two-sided Brownian motion [23, Section 3.1]. Thus,

$$t \rightarrow A_{at} = e^{\gamma(Qt+h_{et}(0))}$$

is a geometric Brownian motion with percentage drift $\gamma Q + \gamma^2/2$ and percentage volatility γ — this implies (5.18). Combining (5.18) with (5.17) and using that $T^{(k)}$ is increasing in *k* shows that with probability at least *p*,

$$A_k T^{(k)} \to \infty.$$

Since this holds for any $p \in (0, 1)$, we have (5.16), completing the proof.

5.4 | Harmonic balls are local

In this subsection, we prove that the harmonic balls given by Theorem 5.5 are local; that is, we prove Proposition 1.3.



FIGURE 3 An example of the Harnack-type property. The cluster Λ_t is in gray with a solid boundary and an annulus $\mathbb{A}_{\rho/2,\rho}(x_0)$ for which $\overline{E}_{\rho}(x_0)$ occurs is displayed in light-gray with a dashed-line boundary. Proposition 6.1 asserts that if $\mu_h(\Lambda_t \cap \mathbb{A}_{\rho/2,\rho}(x_0))$ is small, then $\Lambda_t \cap B_{\rho/2}(x_0) = \emptyset$.

Before doing so, we note that we have constructed clusters and stated Lemma 3.5 for clusters restricted to domains that are balls. However, the definition of $\Lambda_t^{B_r;z}$ and the proof of Lemma 3.5 extend essentially verbatim to the case when B_r is replaced by any bounded open set containing the origin.

Lemma 5.8. Let U be a deterministic bounded open set. For all t > 0 and $z \in \mathbb{C}$, we have $\overline{\Lambda_t(z)} = \overline{\Lambda_t^{U;z}}$ if either $\Lambda_t(z) \in U$ or $\Lambda_t^{U;z} \in U$.

Proof. This is immediate from the proof of Lemma 3.5 together with Theorem 5.5.

Proof of Proposition 1.3. Let the deterministic open set U, base point $z \in \mathbb{C}$, t > 0, and cluster $\Lambda_t(z)$ be given. As $\mathbb{P}[\Lambda_t(z) \subset U] = 0$ if $z \notin U$, we suppose $z \in U$. As we may approximate U by an increasing sequence of bounded open sets, we further suppose that U is bounded.

The cluster $\Lambda_t^{\overline{U};z}$ depends only on $\mu_h|_U$ and hence, by locality (Fact 2.1), only on $h|_U$. Therefore, it suffices to observe from Lemma 5.8 that

$$\overline{\Lambda_t(z)} \subset U \iff \overline{\Lambda_t^{U;z}} \subset U.$$
(5.19)

This completes the proof.

6 | HARNACK-TYPE ESTIMATE

Recall the notation for Euclidean annuli from (1.4). The main goal of this section is to prove the following Harnack-type estimate for clusters: for every $z \in B_{1/2}$,

$$\mu_h(\Lambda_t^z \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leqslant \alpha \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0)) \Rightarrow \Lambda_t^z \cap B_{\rho/2}(x_0) = \emptyset$$
(6.1)

for all t > 0 where $\overline{B_{\rho}}(x_0) \subset B_1 \setminus \{z\}$ and $\alpha \in (0, 1)$ is some fixed, small constant. See Figure 3 for

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a visualization of this condition.

Due to the variable nature of the Liouville measure, we cannot show that this holds for every annulus but rather for "most" annuli. Specifically, we show the following.

Proposition 6.1. There exists $\alpha = \alpha(\gamma) > 0$ and events $\overline{E}_{\rho}(x_0)$ for $\rho \in (0, 1)$ and $x_0 \in \mathbb{C}$ with the following properties: for each $z \in B_1$, if $\overline{E}_{\rho}(x_0)$ occurs, $\overline{B_{\rho}}(x_0) \subset B_1 \setminus \{z\}$, and $\mu_h(\Lambda_t^z \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leq \alpha \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0))$, then $\Lambda_t^z \cap B_{\rho/2}(x_0) = \emptyset$.

Moreover, there is a universal constant c > 0 so that with polynomially high probability as $\epsilon \to 0$ for each $x_0 \in (B_{1+\epsilon} \setminus B_{10\sqrt{\epsilon}}) \cap \frac{\epsilon}{100} \mathbb{Z}^2$, there are at least $c \log \epsilon^{-1/2}$ radii $\rho \in [\epsilon, \epsilon^{1/2}] \cap \{8^{-n}\}_{n \in \mathbb{N}}$ for which $\overline{E}_{\rho}(x_0)$ occurs.

In fact, we prove the following stronger statement.

Proposition 6.2. Assume that we are in the setting of Proposition 6.1 and let $\rho \in (0, 1)$ and $x_0 \in \mathbb{C}$. If $\overline{E}_{\rho}(x_0)$ occurs, $\overline{B}_{\rho}(x_0) \subset B_1 \setminus \{z\}$, and $\widetilde{\Lambda}_t$ is a connected component of $\Lambda_t^z \cap B_{\rho}(x_0)$ then the following occurs. If $\mu_h(\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leq \alpha \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0))$, then $\widetilde{\Lambda}_t \cap \overline{B}_{\rho/2}(x_0) = \emptyset$.

We note that Proposition 6.2 implies the first part of Proposition 6.1. Indeed, if $\mu_h(\Lambda_t^z \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leq \alpha \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0))$, then each connected component $\widetilde{\Lambda}_t$ as in Proposition 6.2 satisfies $\mu_h(\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leq \alpha \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0))$. So, if $\overline{E}_{\rho}(x_0)$ occurs, then Proposition 6.2 implies that none of these connected components intersect $\overline{B}_{\rho/2}(x_0)$.

Proposition 6.1 is sufficient for most of our applications, but Proposition 6.2 is needed in Section 10 to show that the boundaries of the complementary connected components of Λ_t are curves.

The proof of the Harnack-type estimate is inspired by the "no thin tentacles" argument of Jerison–Levine–Sheffield [46] and the IDLA bound of [21]. The idea is as follows. If A is an annulus, then with high probability for every set $Y \subset A$ such that $\mu_h(Y)$ is much smaller than $\mu_h(A)$, it is unlikely for a Brownian motion to cross between the inner and outer boundaries of A without exiting Y (Lemma 6.4). Hence, if $\mu_h(\Lambda_t \cap A)/\mu_h(A)$ is small, then a Brownian motion is unlikely to cross between the inner and outer boundaries of A before exiting Λ_t . Since the cluster Λ_t is "grown according to harmonic measure," one can show that if A' is a smaller annulus that is disconnected from 0 by A, then $\mu_h(\Lambda_t \cap A')/\mu_h(A')$ is even smaller than $\mu_h(\Lambda_t \cap A)/\mu_h(A)$. See Section 6.4 for precise statements to this effect. Iterating this across several nested annuli (with decreasing aspect ratios) allows us to prevent Λ_t from intersecting an appropriate Euclidean ball.

We make the above argument precise via a combination of potential theory and LQG arguments. We simultaneously study the odometer and the mass of the cluster. Specifically, we study the decay of the odometer and mass in disjoint shells of geometrically decreasing radii. We show that whenever an annulus is "very good" (as defined in Section 6.1) and the mass is small in that annulus, then the odometer has to decrease by a geometric amount from one shell to the next (Lemma 6.9). If the odometer is small, then the mass is also small (Lemma 6.8). This together with the prevalence of "very good" annuli established below forces the odometer (and mass) to go to zero.

We start by introducing notions of "good" and "very good" annuli in Section 6.1. We show in Sections 6.2 and 6.3 that there are many "good" and "very good" annuli. We then establish harmonic comparison lemmas that allow us to compare the size of the odometer and the LQG mass of the cluster in Section 6.4. In Section 6.5, we use these harmonic comparison lemmas to show that very good annuli satisfy the Harnack-type estimate. This result combined with the prevalence of very good annuli leads to the proof of Proposition 6.2.

6.1 | Good and very good annuli

In this subsection, we define what it means for an annulus to be good and very good. Roughly, for a good annulus, it is difficult for Brownian motion to stay within a set of relatively small LQG measure until it exits the annulus. Very good annuli contain lots of good annuli and satisfy additional regularity properties. We will later see that very good annuli satisfy (6.1).

6.1.1 | Good annuli

We start with defining good annuli. For $z \in \mathbb{C}$, r > 0 and parameters $a, b \in (0, 1)$, let $E_r(z) = E_r(z; a, b)$ be the event that the following is true. For each Borel set $Y \subset \mathbb{A}_{3r,5r}(z)$ such that $\mu_h(Y) \leq a\mu_h(\mathbb{A}_{3r,5r}(z))$, we have

$$\sup_{u \in \partial B_{4r}(z)} P[\mathcal{B}^u \text{ exits } \mathbb{A}_{3r,5r}(z) \text{ before exiting } Y \mid h] \leq b,$$
(6.2)

where \mathcal{B}^u denotes standard planar Brownian motion started from u. We note that $E_r(z) \in \sigma(h|_{\mathbb{A}_{3r,5r}(z)})$. The annuli $\mathbb{A}_{3r,5r}(z)$ for which $E_r(z)$ holds are good.

6.1.2 | Alternative measures of the LQG size of an annulus

It will be convenient to go back and forth between Liouville measure and two other notions of size when using (6.2). To that end, let β^- be the growth lower bound exponent appearing in Lemma 2.4 and define

$$M_{\rho}(x_0) = \inf_{z \in \mathbb{A}_{\rho/2,\rho}(x_0)} \inf_{r \in (0,\rho/4)} \frac{\mu_h(B_r(z))}{(r/\rho)^{\beta^-}}.$$
(6.3)

By Lemma 2.4, a.s. $0 < M_{\rho}(x_0) < \infty$ for each $\rho \in (0, 1)$ and each $x_0 \in \mathbb{C}$. We also define

$$SG_{\rho}(x_{0}) = \sup_{x \in \mathbb{A}_{\rho/4,2\rho}(x_{0})} \left(\int_{\mathbb{A}_{\rho/4,2\rho}(x_{0})} G_{B_{2\rho}(x_{0})}(x,y) d\mu_{h}(y) \right),$$
(6.4)

where $G_A : \overline{A} \times \overline{A} \to \overline{\mathbb{R}}$ is the Green's function for the set *A*. By Proposition 2.5, a.s. $SG_{\rho}(x_0)$ is finite and positive for each $\rho \in (0, 1)$ and each $x_0 \in \mathbb{C}$. For later use, we also define a version of $SG_{\rho}(x_0)$ with a variable aspect ratio,

$$SG_{s_1\rho,s_2\rho}(x_0) = \sup_{x \in \mathbb{A}_{s_1\rho,s_2\rho}(x_0)} \left(\int_{\mathbb{A}_{s_1\rho,s_2\rho}(x_0)} G_{B_{s_2\rho}(x_0)}(x,y) d\mu_h(y) \right).$$
(6.5)

6.1.3 | Very good annuli

For $x_0 \in \mathbb{C}, \rho > 0$, and parameters $N_0 \ge 1, a \in (0, 1), b \in (0, 1), C_1^{\pm} > 0, C_2^{\pm} > 0, C_3 > 0$, let $\overline{E}_{\rho}(x_0) = \overline{E}_{\rho}(x_0; N_0, a, b, C_1^{\pm}, C_2^{\pm}, C_3)$ be the event that the following are true:

$$\begin{array}{ll} (\text{VG-i}) \ \ C_{1}^{-} \leqslant \frac{M_{\rho}(x_{0})}{\mu_{h}(A_{\rho/4,2\rho}(x_{0}))} \leqslant C_{1}^{+}. \\ (\text{VG-ii}) \ \ C_{2}^{-} \leqslant \frac{SG_{\rho}(x_{0})}{\mu_{h}(A_{\rho/4,2\rho}(x_{0}))} \leqslant C_{2}^{+}. \end{array}$$

(VG-iii) For each $\epsilon \in \{2^{-n}\}_{n \ge N_0}$ and each $z \in \frac{\epsilon \rho}{100} \mathbb{Z}^2 \cap \mathbb{A}_{\rho/2,\rho}(x_0)$, there are at least $C_3 \log_7 \epsilon^{-1/2}$ radii $r \in [\epsilon \rho, \epsilon^{1/2} \rho] \cap \{\rho 7^{-k}\}_{k \ge 1}$ for which $E_r(z; a, b)$ occurs.

The annuli for which $\overline{E}_{\rho}(x_0)$ occur are *very good*. Our goal in the next two sections is to show that with high probability, there are many very good annuli surrounding each point in B_1 .

6.2 | There are many good annuli

We start by showing that good annuli are prevalent, that is, we prove the following.

Lemma 6.3. Fix $b \in (0, 1)$. There exists $a = a(b, \gamma) > 0$ and a universal constant c > 0 such that the following holds with polynomially high probability as $\epsilon \to 0$. For each $z \in (B_{1+\epsilon} \setminus B_{10\sqrt{\epsilon}}) \cap \frac{\epsilon}{100} \mathbb{Z}^2$, there are at least $c \log_7 \epsilon^{-1/2}$ radii $r \in [\epsilon, \epsilon^{1/2}] \cap \{7^{-n}\}_{n \in \mathbb{N}}$ for which $E_r(z)$ occurs, where $E_r(z) = E_r(z; a, b)$ is as in (6.2).

We note the similarity between Lemma 6.3 and condition 6.1.3 in the definition of very good annuli. To prove Lemma 6.3, we will first show that for each $z \in \mathbb{C}$ and r > 0, the event $E_r(z)$ occurs with high probability, provided that a is chosen to be sufficiently small depending on b (Lemma 6.4). We will then use the near-independence of the GFF across disjoint concentric annuli (Lemma 6.5) to show that for each fixed $z \in \mathbb{C}$, it holds with very high probability when ϵ is small that there are many radii $r \in [\epsilon, \epsilon^{1/2}] \cap \{7^{-n}\}_{n \in \mathbb{N}}$ for which $E_r(z)$ occurs. Finally, we will take a union bound over all $z \in B_{1+\epsilon} \cap \frac{\epsilon}{100} \mathbb{Z}^2$.

Lemma 6.4. Let $b \in (0, 1)$ and $p \in (0, 1)$. There exists $a = a(b, p, \gamma) \in (0, 1)$ such that the event $E_r(z) = E_r(z; a, b)$ of (6.2) satisfies

 $P[E_r(z)] \ge p, \quad \forall r > 0, \quad \forall z \text{ such that } \operatorname{dist}(\mathbb{A}_{3r,5r}(z), \{0\}) \ge r/100.$

Proof. We first show that it suffices to prove the lemma for $h^{\mathbb{C}}$, that is, the GFF without a log-singularity ($\alpha_0 = 0$ in (2.4)). We then prove the lemma for the case $\alpha_0 = 0$.

Step 1: Reduction to $\alpha_0 = 0$.

Recall that $h = h^{\mathbb{C}} - \alpha_0 \log |\cdot|$, where $h^{\mathbb{C}}$ is a whole-plane GFF. We first explain why it is sufficient to prove the lemma with $h^{\mathbb{C}}$ in place of *h*. Suppose the statement of the lemma holds for $h^{\mathbb{C}}$ with $a' \in (0, 1)$ in place of *a*.

Fix r > 0 and then z such that the annulus $\mathbb{A}_{3r,5r}(z)$ lies at Euclidean distance at least r/100 from the origin. By Weyl scaling (Fact 2.1), there are constants $C_1, C_2 > 0$ depending only on γ

such that

$$\mu_h(Y) \ge C_1 |z|^{-\alpha_0 \gamma} \mu_{h^{\mathbb{C}}}(Y), \quad \forall Y \in \mathbb{A}_{3r, 5r}(z)$$
(6.6)

and

$$\mu_h(Y) \leqslant C_2 |z|^{-\alpha_0 \gamma} \mu_h^{\mathbb{C}}(Y), \quad \forall Y \in \mathbb{A}_{3r,5r}(z).$$
(6.7)

Thus, for all $Y \subset \mathbb{A}_{3r,5r}(z)$

$$\mu_{h^{\mathbb{C}}}(Y) \leq a' \mu_{h^{\mathbb{C}}}(\mathbb{A}_{3r,5r}(z)) \Rightarrow \mu_{h}(Y) \leq \frac{C_{2}}{C_{1}} \times a' \mu_{h}(\mathbb{A}_{3r,5r}(z)),$$

and hence $\mathbb{P}[E_r(z)] \ge p$ for $a := \frac{C_2}{C_1} \times a'$.

Step 2: Case when $\alpha_0 = 0$.

For the rest of the proof, we assume that $\alpha_0 = 0$. The law of $h = h^{\mathbb{C}}$ is both scale and translation invariant modulo additive constant. By the Weyl scaling property of the measure μ_h (Fact 2.1), the event $E_r(z)$ is a.s. determined by h viewed modulo additive constant. From this and the LQG coordinate change formula for μ_h , we infer that the probability of $E_r(z)$ does not depend on r or z. Hence, it suffices to find $a \in (0, 1)$ as in the lemma statement such that $\mathbb{P}[E_1(0)] \ge p$.

To this end, for $u \in \mathbb{C}$, let \mathcal{B}^u denote γ -LBM with respect to the field *h*, started from *u* with reflecting boundary conditions in a square *K* centered at the origin with side length 100.

By [25, Proposition 2.19], the conditional law of \mathcal{B}^u stopped when exiting $\mathbb{A}_{3,5}(0)$ depends continuously on *u*. Although the proof in [25] is for the whole-plane massive GFF, as explained in [25, Section 9], [25, Proposition 2.19] extends to the massless GFF in a finite domain. Moreover, ordinary LBM and reflected LBM coincide until the first exit from $\mathbb{A}_{3,5}(0)$. Hence, by the compactness of the circle $\partial B_4(0)$, we may therefore find a random T = T(h) > 0 such that a.s.

$$\sup_{u \in \partial B_4(0)} P[\mathcal{B}^u \text{ exits } \mathbb{A}_{3,5}(0) \text{ before time } T \mid h] \leq \frac{b}{2}.$$
(6.8)

For t > 0, let $p_t^K(u, \cdot)$ be the time t Liouville heat kernel for \mathcal{B}^u , so that $p_t^K(u, \cdot) d\mu_h$ is the law of \mathcal{B}^u_t . By Proposition 2.6 a.s. $p_t^K(u, v)$ is a continuous function of (t, u, v) and $p_t^K(u, v) > 0$ for all t > 0 and all $u, v \in K$. Again using the compactness of $\partial B_4(0)$, we infer that with T as in (6.8), there exists a random C = C(h) > 0 such that a.s.

$$\sup_{u \in \partial B_4(0)} \sup_{v \in B_5(0)} p_T(u, v) \le C.$$
(6.9)

From (6.9), we get that for each Borel set $Y \subset A_{3,5}(0)$,

$$\sup_{u \in \partial B_4(0)} P[\mathcal{B}_T^u \in Y \mid h] \leq C\mu_h(Y).$$
(6.10)

Hence, if $\mu_h(Y) \leq [C\mu_h(\mathbb{A}_{3,5}(0))]^{-1}(b/2) \times \mu_h(\mathbb{A}_{3,5}(0))$, then $P\left[\mathcal{B}_T^u \in Y \mid h\right] \leq b/2$ for each $u \in \partial B_4(0)$. Combining this with (6.8) shows that for every such Borel set Y,

$$\sup_{u \in \partial B_4(0)} P[\mathcal{B}^u \text{ exits } \mathbb{A}_{3,5}(0) \text{ before exiting } Y \mid h] \leq b.$$
(6.11)

That is, a.s. $E_1(0)$ occurs with *a* replaced by the random variable $[C\mu_h(\mathbb{A}_{3,5}(0))]^{-1}(b/2)$. This random variable is a.s. positive, so we can find a deterministic $a \in (0, 1)$ such that

$$P[[C\mu_h(\mathbb{A}_{3,5}(0))]^{-1}(b/2) \ge a] \ge p.$$
(6.12)

Hence, for this choice of *a*, we have $\mathbb{P}[E_1(0)] \ge p$, as required.

The following lemma is a consequence of the fact that the restrictions of the GFF to disjoint concentric annuli, viewed modulo additive constant, are nearly independent. See [36, Lemma 3.1] for a slightly more general statement.

Lemma 6.5 [36]. Fix $0 < s_1 < s_2 < 1$. Let $\{r_k\}_{k \in \mathbb{N}}$ be a decreasing sequence of positive numbers such that $r_{k+1}/r_k \leq s_1$ for each $k \in \mathbb{N}$ and let $\{E_{r_k}\}_{k \in \mathbb{N}}$ be events such that E_{r_k} is measurable with respect to $h|_{\mathbb{A}_{s_1r_k,s_2r_k}(0)}$, viewed modulo additive constant, for each $k \in \mathbb{N}$. For $K \in \mathbb{N}$, let N(K) be the number of $k \in [1, K] \cap \mathbb{Z}$ for which E_{r_k} occurs. For each $\alpha > 0$ and each $\beta \in (0, 1)$, there exists $p = p(\alpha, \beta, s_1, s_2) \in (0, 1)$ and $C = C(\alpha, \beta, s_1, s_2) > 0$ (independent of the particular choice of $\{r_k\}$ and $\{E_{r_k}\}$) such that if

$$P\left[E_{r_k}\right] \ge p, \quad \forall k \in \mathbb{N}, 0 \tag{6.13}$$

then

$$P[N(K) < \beta K] \le Ce^{-\alpha K}, \quad \forall K \in \mathbb{N}.$$
(6.14)

We now prove the desired claim.

Proof of Lemma 6.3. The event $E_r(z)$ depends only on the measure $\mu_h|_{\mathbb{A}_{3r,5r}(z)}$. Moreover, multiplying this measure by a constant does not change whether $E_r(z)$ occurs. Therefore, $E_r(z)$ is a.s. determined by $h|_{\mathbb{A}_{3r,5r}(z)}$ viewed modulo additive constant.

We now apply Lemma 6.5 with $K = \lfloor \log_7 e^{-1/2} \rfloor$, the radii $r_1, ..., r_K \in [\epsilon, \epsilon^{1/2}] \cap \{7^{-n}\}_{n \in \mathbb{N}}$, the events $E_{r_k} = E_{r_k}(z)$, and appropriate universal constant choices of α and β . We find that there exist universal constants $p \in (0, 1)$ and c > 0 such that if $\mathbb{P}[E_r(z)] \ge p$ for each r > 0 and each $z \in \mathbb{C} \setminus B_{10r}$, then for all $z \in \mathbb{C} \setminus B_{10\sqrt{\epsilon}}$,

$$P\left[E_r(z) \text{ occurs for at least } c \log \epsilon^{-1/2} \text{ values of } r \in [\epsilon, \epsilon^{1/2}] \cap \{7^{-n}\}_{n \in \mathbb{N}}\right] \ge 1 - O_{\epsilon}(\epsilon^3)$$
(6.15)

with a universal implicit constant in the $O_{\epsilon}(\cdot)$.

By Lemma 6.4, there exists $a = a(b, \gamma) > 0$ such that for this choice of a, one has $\mathbb{P}[E_r(z)] \ge p$ for each r > 0 and each $z \in \mathbb{C} \setminus B_{10r}$. Therefore, the estimate (6.15) holds for this choice of a. We now conclude by means of a union bound over all $z \in (B_{1+\epsilon} \setminus B_{10\sqrt{\epsilon}}) \cap \frac{\varepsilon}{100} \mathbb{Z}^2$.

6.3 | There are many very good annuli

In this section, we prove that very good annuli are prevalent, following the same strategy as the last section.

 \Box

Lemma 6.6. Fix $b \in (0, 1)$. There exists $a = a(b, \gamma) > 0$, universal constants $c, C_3 > 0, C_1^{\pm}, C_2^{\pm} > 0$ depending on a, γ , and $N_1 = N_1(b, \gamma) \ge 1$ such that for all $N_0 \ge N_1$, the following holds with polynomially high probability as $\epsilon \to 0$. For each $x_0 \in (B_{1+\epsilon} \setminus B_{10\sqrt{\epsilon}}) \cap \frac{\epsilon}{100} \mathbb{Z}^2$, there are at least $c \log_8 \epsilon^{-1/2}$ radii $\rho \in [\epsilon, \epsilon^{1/2}] \cap \{8^{-n}\}_{n \in \mathbb{N}}$ for which $\overline{E}_{\rho}(x_0)$ occurs, where $\overline{E}_{\rho}(x_0) = \overline{E}_{\rho}(x_0; N_0, a, b, C_1^{\pm}, C_2^{\pm}, C_3)$ is as in (VG-i), (VG-ii), and (VG-iii).

We start by showing the event $\overline{E}_{\rho}(x_0)$ occurs with high probability with *a*, *b* chosen as in Lemma 6.3, N_0 large, and C_1^{\pm}, C_2^{\pm} chosen appropriately.

Lemma 6.7. Let $b \in (0, 1)$ and $p \in (0, 1)$. There exists $a = a(b, p, \gamma) \in (0, 1)$, C_1^{\pm}, C_2^{\pm} depending on a, γ, p and a universal constant $C_3 > 0$ such that the event $\overline{E}_{\rho}(x_0)$ of (VG-i), (VG-ii), and (VG-iii) satisfies

$$P\left[\overline{E}_{\rho}(x_0)\right] \ge p, \quad \forall \rho > 0, \quad \forall x_0 \text{ such that } \mathbf{dist}(\mathbb{A}_{\rho/4,2\rho}(x_0), \{0\}) \ge \rho/100$$

for all $N_0 \ge N_1(b, p, \gamma) \ge 1$ sufficiently large.

Proof. Recall that $h = h^{\mathbb{C}} - \alpha_0 \log |\cdot|$. The proof is similar to that of Lemma 6.4. We show that we can reduce to the case $\alpha_0 = 0$ and then give a proof in that case.

Step 1: Reduction to $\alpha_0 = 0$.

Suppose that the statement of the lemma holds for $h^{\mathbb{C}}$ with constants \underline{C}_{1}^{\pm} in place of C_{1}^{\pm} . Write $M_{\alpha}^{h}(x_{0})$ to indicate the dependence in the definition of $M_{\alpha}(x_{0})$ on the GFF.

Fix $\rho > 0$ and then x_0 such that the annulus $\mathbb{A}_{\rho/4,2\rho}(x_0)$ lies at Euclidean distance at least $\rho/100$ from the origin. By Weyl scaling (Fact 2.1), there are constants $A_1, A_2 > 0$ depending only on γ such that

$$\frac{M_{\rho}^{h}(x_{0})}{\mu_{h}(A_{\rho/4,2\rho}(x_{0}))} \ge A_{1} \frac{M_{\rho}^{h^{\mathbb{C}}}(x_{0})}{\mu_{h^{\mathbb{C}}}(A_{\rho/4,2\rho}(x_{0}))}$$
(6.16)

and

$$\frac{M_{\rho}^{h}(x_{0})}{\mu_{h}(A_{\rho/4,2\rho}(x_{0}))} \leqslant A_{2} \frac{M_{\rho}^{h^{\mathbb{C}}}(x_{0})}{\mu_{h^{\mathbb{C}}}(A_{\rho/4,2\rho}(x_{0}))}.$$
(6.17)

Thus,

$$\underline{C}_{1}^{-} \leqslant \frac{M_{\rho}^{h^{\mathbb{C}}}(x_{0})}{\mu_{h^{\mathbb{C}}}(A_{\rho/4,2\rho}(x_{0}))} \leqslant \underline{C}_{1}^{+} \Rightarrow A_{1}\underline{C}_{1}^{-} \leqslant \frac{M_{\rho}^{h}(x_{0})}{\mu_{h}(A_{\rho/4,2\rho}(x_{0}))} \leqslant A_{2}\underline{C}_{1}^{+},$$

and hence (VG-i) occurs for $C_1^+ := A_2 \underline{C}_1^+$ and $C_1^- := A_1 \underline{C}_1^-$ if it occurs under $h^{\mathbb{C}}$. The argument for (VG-ii) is nearly identical. Step 1 of the proof of Lemma 6.4 also shows that we can reduce to the case $\alpha_0 = 0$ for (VG-iii).

Step 2: Case when $\alpha_0 = 0$.

As in Step 2 of the proof of Lemma 6.4, it suffices to find $a \in (0, 1)$ and $C_1^{\pm}, C_2^{\pm}, C_3 > 0$ such that $\mathbb{P}[\overline{E}_1(0)] \ge p$.

Note that by Lemma 2.4, $M_1(0)$ is a strictly positive, finite random variable. Since $\mu_h(\mathbb{A}_{1/4,2}(0))$ and $SG_1(0)$ are also strictly positive and finite random variables, there exists $C_1^{\pm}, C_2^{\pm} > 0$ so that

$$P\left[C_1^- \leqslant \frac{M_1(0)}{\mu_h(A_{1/4,2}(0))} \leqslant C_1^+\right] \ge p_1 \quad \text{and} \quad P\left[C_2^- \leqslant \frac{SG_1(0)}{\mu_h(A_{1/4,2}(0))} \leqslant C_2^+\right] \ge p_2.$$
(6.18)

Also, by Lemma 6.3, for N_0 sufficiently large, with probability at least p_3 , the event in (VG-iii) occurs with $\rho = 1$ and C_3 an appropriate universal constant.

By adjusting our choices of parameters so that $(1 - p_1) + (1 - p_2) + (1 - p_3) \le 1 - p$, we may conclude via a union bound.

Proof of Lemma 6.6. Given Lemma 6.7, the argument is identical to the proof of Lemma 6.3.

6.4 | Harmonic comparison

In this section, we prove lemmas which let us compare the size of the odometer to the LQG mass of the cluster. Our first lemma allows us to show that the LQG mass of the cluster is small in annuli where the odometer is small.

Lemma 6.8. Fix $0 < s_1 < s_2 < s_3 < s_4$ and $z \in B_1$. Let $\mathbb{A}_{s_1r,s_4r}(w) \subset B_1$ be an annulus not containing z and let $\hat{\Lambda}_t$ be a union of connected components of $\mathbb{A}_{s_1r,s_4r}(w) \cap \Lambda_t^z$. There exists a constant C, depending only on s_1, \ldots, s_4 , so that for all such annuli

$$\mu_h(\mathbb{A}_{s_2r,s_3r}(w)\cap \hat{\Lambda}_t) \leq C \sup_{x\in \hat{\Lambda}_t} v_t^z(x).$$

Proof. First note that there is a positive constant c_1 so that the annulus \mathbb{A}_{s_2,s_3} can be covered by c_1^{-1} balls of radius $c_2 := \min(s_2 - s_1, s_3 - s_2, s_4 - s_3)/4$ centered at points in \mathbb{A}_{s_2,s_3} . Therefore, by scaling, this implies that the annulus $\mathbb{A}_{s_2r,s_3r}(w)$ can be covered by c_1^{-1} balls of radius c_2r centered at points in $\mathbb{A}_{s_2r,s_3r}(w)$. By the pigeonhole principle, there is at least one such ball $B_{2c_3r}(x) \in \mathbb{A}_{s_1r,s_4r}(w)$ with

$$\mu_h(B_{c_2r}(x) \cap \hat{\Lambda}_t) \ge c_1 \mu_h(\mathbb{A}_{s_2r, s_2r}(w) \cap \hat{\Lambda}_t).$$
(6.19)

Write $v_t^z|_{\hat{\Lambda}_t}$ for $v_t^z(\cdot)1\{\cdot \in \hat{\Lambda}_t\}$. As we will explain just below, one can deduce from Lemma 3.2 that

$$\Delta(v_t^z|_{\hat{\Lambda}_t}) = \begin{cases} \mu_h & \text{on } \hat{\Lambda}_t \\ 0 & \text{on } \mathbb{A}_{s_1 r, s_4 r}(w) \setminus \overline{\hat{\Lambda}_t} \\ \ge 0 & \text{on } \partial \hat{\Lambda}_t \cap \mathbb{A}_{s_1 r, s_4 r}(w). \end{cases}$$
(6.20)

Indeed, $\hat{\Lambda}_t$ is a union of connected components of $\Lambda_t^z \cap \mathbb{A}_{s_1r,s_4r}(w)$, an open set. The odometer, v_t^z is nonnegative and continuous on $B_1 \setminus \{z\}$ and $v_t^z = 0$ on $\partial \hat{\Lambda}_t \cap \mathbb{A}_{s_1r,s_4r}(w)$. Therefore, $v_t^z|_{\hat{\Lambda}_t}$ is con-

tinuous on $\hat{\Lambda}_t \cap \mathbb{A}_{s_1r,s_4r}(w)$ and $v_t^z|_{\hat{\Lambda}_t}$ satisfies the submean-value property on $\partial \hat{\Lambda}_t \cap \mathbb{A}_{s_1r,s_4r}(w)$. As $v_t^z|_{\hat{\Lambda}_t}$ coincides with v_t^z on $\hat{\Lambda}_t$, this shows (6.20) by Lemma 3.2.

Let G_A denote the Green's function for the domain A with zero boundary conditions and let

$$u(\cdot) = \int_{B_{2c_2r}(x)\cap \hat{\Lambda}_t} G_{B_{2c_2r}(x)}(\cdot, y) \mu_h(dy).$$

Observe that $\Delta(u + v_t^z|_{\hat{\Lambda}_t}) \ge 0$ on $B_{2c_2r}(x)$: indeed, by the definition of u, we have $\Delta u = -\mu_h$ on $\hat{\Lambda}_t \cap B_{2c_2r}(x)$ and $\Delta u = 0$ elsewhere which, together with (6.20), shows $u + v_t^z|_{\hat{\Lambda}_t}$ is subharmonic on $B_{2c_2r}(x)$.

Hence, by the maximum principle, on $B_{2c_{2}r}(x)$,

$$u + v_t^z|_{\hat{\Lambda}_t} \leq \sup_{\partial B_{2c_2r}(x)} (u + v_t^z|_{\hat{\Lambda}_t}) = \sup_{\partial B_{2c_2r}(x)} v_t^z|_{\hat{\Lambda}_t} \leq \sup_{A_{s_1r,s_4r}(w)} v_t^z|_{\hat{\Lambda}_t} = \sup_{\hat{\Lambda}_t} v_t^z$$

as u = 0 on $\partial B_{2c_2r}(x)$ and $B_{2c_2r}(x) \in \mathbb{A}_{s_1r,s_4r}(w)$. Thus, as $v_t^z|_{\hat{\Lambda}_t} \ge 0$,

$$0 \leq \left(\sup_{\hat{\Lambda}_{t}} v_{t}\right) - u, \quad \text{on } B_{2c_{2}r}(x).$$
(6.21)

We now estimate *u* at the center of $B_{2c_2r}(x)$. By the definition of *u* and then the scale invariance of the Green's function for a ball,

$$u(x) = \int_{B_{2c_2r}(x)\cap\hat{\Lambda}_t} G_{B_{2c_2r}(x)}(x, y)\mu_h(dy)$$

$$\ge \int_{B_{c_2r}(x)\cap\hat{\Lambda}_t} G_{B_1}(0, (2c_2r)^{-1}(y-x))\mu_h(dy)$$

$$\ge C\mu_h(A_{s_2r,s_2r}(w)\cap\hat{\Lambda}_t), \quad (by (6.19))$$

where $C := c_1 \inf_{y \in B_{1/2}(0)} G_{B_1(0)}(0, y) > 0$ is independent of *r*. We conclude the proof by combining this lower bound for u(x) with (6.21).

We next show that if it is difficult for Brownian motion to get through a domain without exiting Λ_t , then the odometer must be small within the domain.

Lemma 6.9. Let $z \in B_1$, and let A denote an open set in B_1 not containing z. For all $x \in A \cap \Lambda_t^z$,

$$v_t^z(x) \leq \left(\sup_{\partial A \cap \overline{\Lambda}_t^x} v_t^z\right) \mathbb{P}[B^x \text{ exits } A \text{ before hitting } A \setminus \Lambda_t^x | h], \qquad (6.22)$$

where B^x denotes an independent Brownian motion started at x and Λ_t^x is the connected component of $A \cap \Lambda_t^z$ containing x.

Proof. Write $f_A(x) = \mathbb{P}[\mathcal{B}^x \text{ exits } A \text{ before hitting } A \setminus \Lambda_t^z | h]$. Observe that

$$\begin{cases} \Delta f_A = 0 & \text{in } A \cap \Lambda_t^z \\ f_A = 1 & \text{on } \partial A \cap \Lambda_t^z \\ f_A = 0 & \text{on } A \cap \partial \Lambda_t^z \end{cases}$$
(6.23)

and by Lemma 3.2,

$$\begin{cases} \Delta v_t^z \ge 0 & \text{in } A \cap \Lambda_t^z \\ v_t \le \sup_{\partial A \cap \Lambda_t} v_t^z & \text{on } \partial A \cap \Lambda_t^z \\ v_t^z = 0 & \text{on } A \cap \partial \Lambda_t^z. \end{cases}$$
(6.24)

Now, fix $x \in A \cap A_t^z$ and consider Λ_t^x , the connected component of $A \cap A_t^z$ containing x. As $A \cap \Lambda_t^x$ is a connected component of $A \cap \Lambda_t^z$, (6.23) and (6.24) show that

$$v_t^z(\cdot) - \left(\sup_{\partial A \cap \overline{\Lambda}_t^x} v_t^z\right) f_A(\cdot)$$

is subharmonic in $A \cap \Lambda_t^x$, equal to 0 on $A \cap \partial \Lambda_t^x$, and less than or equal to 0 on $\partial A \cap \overline{\Lambda}_t^x$. Hence, by the maximum principle,

$$v_t^z(y) \leq \left(\sup_{\partial A \cap \overline{\Lambda}_t^x} v_t^z\right) f_A(y), \quad \text{for } y \in A \cap \Lambda_t^x.$$

Moreover,

 $f_A(y) = \mathbb{P}[\mathcal{B}^y \text{ exits } A \text{ before hitting } A \setminus \Lambda_t^x | h] \text{ for } y \in A \cap \Lambda_t^x$

since there is no path in A from y to any point of $\Lambda_t \setminus \Lambda_t^x$. The previous two sentences imply

$$v_t^z(y) \leq \left(\sup_{\partial A \cap \overline{\Lambda}_t^x} v_t^z\right) \mathbb{P}[\mathcal{B}^y \text{ exits } A \text{ before hitting } A \setminus \Lambda_t^x | h] \quad \text{for } y \in A \cap \Lambda_t^x$$

completing the proof.

We next provide a weak upper bound on the growth of the odometer around its zeros.

Lemma 6.10. Fix $0 < s_1 < s_2 < s_3 < s_4$. There exists a constant c > 0, depending only on s_1, \dots, s_4 , so that, with $SG_{s_1\rho,s_4\rho}(x_0)$ as in (6.5), for all $z \in B_1$

$$\sup_{x \in \mathbb{A}_{s_2\rho, s_3\rho}(x_0)} v_t^z(x) \leq cSG_{s_1\rho, s_4\rho}(x_0)$$

for all $\mathbb{A}_{s_1\rho,s_4\rho}(x_0) \subset B_1 \setminus \{z\}$ such that $\Lambda_t^{z^c} \cap \mathbb{A}_{s_2\rho,s_3\rho}(x_0) \neq \emptyset$.

Proof. Fix an annulus $\mathbb{A}_{s_1\rho,s_4\rho}(x_0) \subset B_1 \setminus \{z\}$ and let $\lambda = \Delta v_t^z$. Consider the positive function

$$q(w) = \int_{\mathbb{A}_{s_1\rho,s_4\rho}(x_0)} G_{B_{s_4\rho}(x_0)}(w, y) d\lambda(y).$$

for $w \in \mathbb{A}_{s_1\rho,s_4\rho}(x_0)$. Since $\lambda \leq \mu_h$ (Lemma 3.2),

$$\sup_{w \in \mathbb{A}_{s_1\rho, s_4\rho}} q(w) \leqslant SG_{s_1\rho, s_4\rho}(x_0).$$
(6.25)

Hence, the statement of the lemma will follow once we bound v_t^z by q. We do this via Harnack's inequality for positive harmonic functions.

Our choice of q ensures that it is positive and

$$\Delta q = -\lambda \qquad \text{on } \mathbb{A}_{s_1 \rho, s_4 \rho}(x_0)$$

This implies that the function $g : \mathbb{A}_{s_1\rho,s_4\rho}(x_0) \to \mathbb{R}$ defined by

$$g := v_t^z + q$$

is harmonic and nonnegative in $\mathbb{A}_{s_1\rho,s_4\rho}(x_0)$. Fix s'_2, s'_3 so that

$$0 < s_1 < s_2' < s_2 < s_3 < s_3' < s_4.$$

By Harnack's inequality for positive harmonic functions,

$$\sup_{z \in \mathbb{A}_{s'_2\rho, s'_3\rho}} g(z) \leqslant c \inf_{y \in \mathbb{A}_{s_2\rho, s_3\rho}(x_0)} g(y)$$
(6.26)

for a constant *c* (depending only on the ratio of the domains on the left and right of (6.26)). Note that the assumption $\Lambda_t^{z^c} \cap \mathbb{A}_{s_2\rho,s_3\rho}(x_0) \neq \emptyset$ implies the existence of $z_0 \in \mathbb{A}_{s_2\rho,s_3\rho}(x_0)$ with $v_t^z(z_0) = 0$. Hence,

$$\sup_{z \in \mathbb{A}_{s'_{2}\rho,s'_{3}\rho}(x_{0})} v_{t}^{z}(z) \leq \sup_{w \in \mathbb{A}_{s'_{2}\rho,s'_{3}\rho}(x_{0})} g(w) \quad (\text{since } q \geq 0)$$

$$\leq c \inf_{y \in \mathbb{A}_{s_{2}\rho,s_{3}\rho}(x_{0})} g(y) \quad (\text{by (6.26)})$$

$$\leq cg(z_{0}) \quad (\text{since } z_{0} \in \mathbb{A}_{s_{2}\rho,s_{3}\rho}(x_{0}))$$

$$= cq(z_{0}) \quad (\text{since } v_{t}^{z}(z_{0}) = 0)$$

$$\leq c \sup_{w \in \mathbb{A}_{s_{2}\rho,s_{3}\rho}(x_{0})} q(w),$$

which together with (6.25) completes the proof.



FIGURE 4 Illustration of the choice of constants and dependencies in the proof of Proposition 6.2. A line between two constants indicates that the downward constant is chosen in a way that depends directly on the upward constant. Where the constant is chosen is written directly next to it. Note that $b = b(\gamma)$. Otherwise, dependence on $\gamma \in (0, 2)$ and some universal constants is not indicated. N_0 can be any number larger than N_1 . This is done so that there is flexibility later (the proof of Proposition 8.1) to choose the initial scale N_0 to be large.

6.5 | Very good annuli satisfy the Harnack-type estimate

In this section, we prove that there are choices of parameters so that for every $z \in B_1$, every annulus $\mathbb{A}_{\rho/2,\rho}(x_0)$ with $\overline{B}_{\rho}(x_0) \subset B_1 \setminus \{z\}$ that is very good also satisfies the Harnack-type property at z.

Lemma 6.11. There exists a universal constant $C_3 > 0$ and $b = b(\gamma) \in (0, 1)$ so that the following is true for every $z \in B_1$. For every choice of $C_1^{\pm}, C_2^{\pm} > 0$ and $a \in (0, 1)$, there exists

- $N_1 \ge 200$ depending only on a, γ, C_1^-, C_2^+ ;
- for each $N_0 \ge N_1$, a parameter $\alpha \in (0, \tilde{1})$ depending on a, N_0, γ , and C_1^- ;

with the following property. If $\rho \in (0, 1)$ and $x_0 \in B_1$ are such that $\overline{B}_{\rho}(x_0) \subset B_1 \setminus \{z\}$, the event $\overline{E}_{\rho}(x_0)$ of (VG-i), (VG-ii), and (VG-iii) occurs, and $\widetilde{\Lambda}_t$ is a connected component of $\Lambda_t^z \cap B_{\rho}(x_0)$ for which $\mu_h(\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leq \alpha \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0))$, then $\widetilde{\Lambda}_t \cap \overline{B_{\rho/2}(x_0)} = \emptyset$.

This leads to the Harnack-type inequality.

Proof of Propositions 6.1 and 6.2. Combine Lemma 6.6 and Lemma 6.11. See Figure 4 for an illustration of how the constants are chosen.

The proof of Lemma 6.11 is purely deterministic. We now outline the proof (in the case z = 0 for convenience) — also see Figure 5. As mentioned previously, we will use (VG-i) and (VG-ii) to switch between μ_h , $SG_\rho(\cdot)$, and $M_\rho(\cdot)$ when convenient.

Set up the iteration by decomposing A_{ρ/2,ρ}(x₀) into a disjoint, sparse collection of shells {S_j}_{j≥0} contained in {A_{ρ/2,dj}(x₀)}_{j≥0} for some infinite geometric sequence d_j ↓ d_∞ > ρ/2 (Lemma 6.12).



FIGURE 5 Visual explanation of the proof of Lemma 6.11. We display some of the shells in the shell decomposition, the grid of points in each shell surrounded by good annuli, and some of the good annuli $A_{r_i, 7r_i}(z)$ surrounding one of the grid points z_i . The shells are displayed in gray, the good annuli are in purple, and the grid of points are black dots. Aspect ratios of annuli are not shown to scale.

- (2) Show that if $\mu_h(\mathbb{A}_{\rho/2,d_j}(x_0) \cap \Lambda_t)$ is very small, then the supremum of the odometer decreases by a multiplicative factor from $\mathbb{A}_{\rho/2,d_j}(x_0)$ to $\mathbb{A}_{\rho/2,d_{j+1}}(x_0)$ (Lemma 6.13).
 - (a) As $\mu_h(\mathbb{A}_{d_j,\rho}(x_0) \cap \Lambda_t)$ is small, we may use (VG-iii) to cover S_j by a dense grid of points surrounded by a large number N of concentric good annuli.
 - (b) For each good annulus, apply harmonic comparison, Lemma 6.9, together with (6.2) to see that the supremum of the odometer decreases by a factor of b from one concentric annulus to the next.
 - (c) Since the concentric annuli cover S_j and v_t is subharmonic, iterating shows that the odometer decreases by a factor of b^N .
- (3) Show that if $\sup_{\mathbb{A}_{\rho/2,d_{j+1}}(x_0)} v_t$ is small, then $\mu_h(\mathbb{A}_{3r,5r}(z) \cap \Lambda_t)$ is small for each annulus $\mathbb{A}_{r,7r}(z) \subset \mathbb{A}_{\rho/2,d_{j+1}}(x_0)$ (using Lemma 6.8).
- (4) Start with a weak initial bound on the odometer, Lemma 6.10 and the initial assumption that $\mu_h(\mathbb{A}_{\rho/2,\rho}(x_0) \cap \Lambda_t) \leq \alpha \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0))$ and iterate the previous two steps to see that $\lim \left(\sup_{\mathbb{A}_{\rho/2,d_i}(x_0)} v_t \right) \to 0.$

We start with the shell decomposition.

Lemma 6.12. Fix $\rho \in (0, 1)$ and $x_0 \in B_1$. Define the collection of shells

$$S_j = \partial B_{d_j}(x_0) + B_{l_j} \qquad \text{for } j \ge 0 \tag{6.27}$$

where

$$l_j = \rho \times 2^{-j/4} \times 2^{-50} \quad \text{for } j \ge 0$$
 (6.28)

and

$$d_{0} = \frac{3}{4}\rho$$

$$d_{i} = d_{i-1} - 32l_{i-1} \quad \text{for } j \ge 1.$$
(6.29)

For each $N_0 \ge 200$, the shells satisfy the following properties.

• The union of fattened shells is contained in an annulus:

$$\bigcup_{j \ge 0} (S_j + B_{8l_j}) \in \mathbb{A}_{\rho/2,\rho}(x_0).$$
(6.30)

• Shells are sufficiently far apart:

$$(S_j + B_{8l_j}) \cap \left(\cup_{j' \neq j} S_{j'} \right) = \emptyset \qquad \text{for } j \ge 0.$$
(6.31)

• Balls centered at points of a shell are contained in an annulus: for each $j \ge 0$, let

$$\epsilon_j := 2^{-(N_0+j)} \quad and \quad d_j^+ := d_j + 8l_j.$$
 (6.32)

Then, for each $z \in S_i$,

$$B_{8\varepsilon_{j}^{1/2}\rho}(z) \subset \mathbb{A}_{\rho/2,d_{j}^{+}}(x_{0}) \subset \mathbb{A}_{\rho/2,\rho}(x_{0}).$$
(6.33)

Proof. The first two properties (6.30) and (6.31) are immediate from the definitions of d_j and l_j . The second inclusion in (6.33) follows from unpacking the definitions:

$$d_j^+ = d_j + 8l_j \le d_0 + 8l_0 = (3/4 + 8 \times 2^{-100})\rho < \rho.$$

We now check the first inclusion in (6.33). First note

$$d_j - l_j \le |z - x_0| \le d_j + l_j, \quad \forall z \in S_j$$
(6.34)

and

$$d_{j} - l_{j} - 8\epsilon_{j}^{1/2}\rho \leq |z' - x_{0}| \leq d_{j} + l_{j} + 8\epsilon_{j}^{1/2}\rho, \quad \forall z' \in B_{8\epsilon_{j}^{1/2}\rho}(z), z \in S_{j}.$$
(6.35)

We claim that the first inclusion in (6.33) follows from the following inequality which we verify below:

$$l_j + 8\varepsilon_j^{1/2} \rho \leqslant 4l_j. \tag{6.36}$$

Indeed, if (6.36) holds, then by (6.35) and the definitions of d_j^+ and S_j ,

$$B_{8\epsilon_j^{1/2}\rho}(z) \subset S_j + B_{4l_j} \subset \mathbb{A}_{\rho/2,d_j^+}, \quad \forall z \in S_j$$

It remains to check (6.36):

$$l_j + 8\epsilon_j^{1/2}\rho = \rho \times 2^{-j/4} \times 2^{-50} + 8 \times 2^{-N_0/2 - j/2} \times \rho$$

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$$\leq \rho \times 2^{-j/4} \left(2^{-50} + 8 \times 2^{-N_0/2} \right) \quad (\text{since } 2^{-j/4} \ge 2^{-j/2} \text{ for } j \ge 0)$$

$$\leq 2 \times \rho \times 2^{-j/4} \times 2^{-50} \quad (\text{since } N_0 \ge 200)$$

$$= 2l_j.$$

We next show that an upper bound for the amount of mass in $\mathbb{A}_{\rho/2,d_j^+}(x_0)$ implies an upper bound for the odometer in $\mathbb{A}_{\rho/2,d_{j+1}^+}(x_0)$. This will be a key input in the induction argument in the proof of Lemma 6.11.

Lemma 6.13. Let $z \in B_1$, and fix an annulus $\mathbb{A}_{\rho/2,\rho}(x_0)$ not containing z for which (VG-iii) occurs with parameters $a, b \in (0, 1)$, $N_0 \ge 200$, and universal constant $C_3 > 0$. Let the shell decomposition $\{S_j, d_j^+\}_{j\ge 0}$ be given by Lemma 6.12 and let $\widetilde{\Lambda}_t$ be a connected component of $\Lambda_t^z \cap B_\rho(x_0)$. For $j \ge 0$, let

$$K_{j} = a \times M_{\rho}(x_{0}) \times \epsilon_{j}^{\beta^{-}} \qquad (\epsilon_{j} \text{ from (6.32) and } \beta^{-} \text{ from Lemma 2.4).}$$
(6.37)

Then, for each $j \ge 0$,

$$\sup_{\substack{r>0, z\in B_1:\\ \mathbb{A}_{r,7r}(z)\subset \mathbb{A}_{\rho/2,d_j^+}(x_0)}} \mu_h(\widetilde{\Lambda}_t \cap \mathbb{A}_{3r,5r}(z)) \leqslant K_j$$

$$\Rightarrow \sup_{\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2,d_{j+1}^+}(x_0)} v_t \leqslant b^{C' \times C_3 \times (N_0+j)} \left(\sup_{\tilde{\Lambda}_t \cap \mathbb{A}_{\rho/2,d_j^+}(x_0)} v_t \right), \quad (6.38)$$

where C' > 0 is a universal constant.

Proof. Let $j \ge 0$ be given and let $\widetilde{\Lambda}_t$ be a connected component of $\Lambda_t^z \cap B_\rho(x_0)$. We first check that the assumption

$$\sup_{\substack{r>0, w\in B_1:\\ \mathbb{A}_{r,7r}(z)\subset \mathbb{A}_{\rho/2,d_i^+}(x_0)}} \mu_h(\bar{\Lambda}_t \cap \mathbb{A}_{3r,5r}(w)) \leqslant K_j$$

allows us to use (6.2) on sufficiently many annuli covering S_i .

In particular, there exists a finite set of points $Z \subset S_j \cap \frac{\epsilon_j \rho}{100} \mathbb{Z}^2$ so that $\bigcup_{z \in \mathbb{Z}} B_{\rho \epsilon_j}(z)$ covers S_j . Fix one such $w \in \mathbb{Z}$, define

$$N = \lfloor C_3 \log \epsilon_j^{-1/2} \rfloor,$$

and let $r_1, ..., r_N \in [\epsilon_j \rho, \epsilon_j^{1/2} \rho] \cap \{\rho 7^{-n}\}_{n \in \mathbb{N}}$ be distinct radii $r_1 > r_2 > \cdots > r_N$ for which the event $E_r(w)$ occurs, as provided by (VG-iii).

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For each $r \in \{r_1, \dots, r_N\}$,

$$\begin{split} \mu_{h}(\widetilde{\Lambda}_{t} \cap \mathbb{A}_{3r,5r}(z)) &\leq K_{j} \qquad (\mathbb{A}_{r,7r}(z) \subset \mathbb{A}_{\rho/2,d_{j}^{+}}(x_{0}) \text{ by (6.33) and since } r \leq \epsilon_{j}^{1/2}\rho) \\ &= a \times M_{\rho}(x_{0}) \times \epsilon_{j}^{\beta^{-}} \qquad (\text{definition of } K_{j}) \\ &\leq a \times \frac{\mu_{h}(B_{\epsilon_{j}\rho}(z+4re_{1}))}{\epsilon_{j}^{\beta^{-}}} \times \epsilon_{j}^{\beta^{-}} \qquad (\text{definition of } M_{\rho}(x_{0}) \text{ and (6.33)}) \\ &= a \times \mu_{h}(B_{\epsilon_{j}\rho}(z+4re_{1})) \\ &\leq a \times \mu_{h}(\mathbb{A}_{3r,5r}(z)) \qquad (\text{since } r \geq r_{N} \geq \epsilon_{j}\rho). \end{split}$$

Hence, we may use the estimate on the exit probability (6.2) on each such annulus with $Y = \widetilde{\Lambda}_t \cap \mathbb{A}_{3r,5r}(z)$. In fact, we may use it with Y set to be any connected component of $\widetilde{\Lambda}_t \cap \mathbb{A}_{3r,5r}(z)$.

Step 2: Small mass in good annulus implies small odometer. First note that as $\mathbb{A}_{3r_1,5r_1}(w) \in \mathbb{A}_{\rho/2,d^+_1}(x_0)$,

$$\sup_{\partial \mathbb{A}_{3r_1,5r_1}(w)\cap \widetilde{\Lambda}_t} v_t^z \leq \sup_{\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2,d_t^+}(x_0)} v_t^z.$$
(6.39)

For each $x \in \tilde{\Lambda}_t \cap \partial B_{4r_1}(w)$, let \mathcal{B}^x denote an independent Brownian motion started at x and Λ_t^x the connected component of $\mathbb{A}_{3r_1,5r_1}(w) \cap \Lambda_t^z$ containing x. Note that for each such x, we have $\Lambda_t^x \subset \tilde{\Lambda}_t$ (and hence $\mu_h(\Lambda_t^x) \leq \mu_h(\tilde{\Lambda}_t)$). We use this to see that for each $x \in \tilde{\Lambda}_t \cap \partial B_{4r_1}(w)$,

$$\begin{aligned} & \leq \left(\sup_{\partial \mathbb{A}_{3r_{1},5r_{1}}(w)\cap\overline{\Lambda}_{t}^{x}} v_{t}^{z} \right) \mathbb{P}[\mathcal{B}^{x} \text{ exits } \mathbb{A}_{3r_{1},5r_{1}}(w) \text{ before } \Lambda_{t}^{x} | h] \quad (\text{Lemma 6.9 with } A = \mathbb{A}_{3r_{1},5r_{1}}(w)) \\ & \leq b \left(\sup_{\partial \mathbb{A}_{3r_{1},5r_{1}}(w)\cap\overline{\Lambda}_{t}^{x}} v_{t}^{z} \right) \quad ((6.2) \text{ with } Y = \Lambda_{t}^{x}) \\ & \leq b \left(\sup_{\mathbb{A}_{3r_{1},5r_{1}}(w)\cap\overline{\Lambda}_{t}} v_{t}^{z} \right) \quad (\Lambda_{t}^{x} \subset \widetilde{\Lambda}_{t}). \end{aligned}$$

As $\widetilde{\Lambda}_t$ is a connected component of $\Lambda_t^z \cap \mathbb{A}_{\rho/2,\rho}(x_0)$, $\widetilde{\Lambda}_t \cap B_{4r_1}(w)$ is a union of connected components of $\Lambda_t^z \cap B_{4r_1}(w)$. The same argument in the proof of Lemma 6.8 shows that $v_t^z \mathbb{1}\{\cdot \in \widetilde{\Lambda}_t\}$ is subharmonic in $B_{\rho}(x_0)$.

This together with the maximum principle and the most recent indented inequality shows that

$$\sup_{\widetilde{\Lambda}_{t}\cap B_{4r_{1}}(w)} v_{t}^{z} \leq \sup_{\widetilde{\Lambda}_{t}\cap\partial B_{4r_{1}}(w)} v_{t} \leq b \left(\sup_{\mathbb{A}_{3r_{1},5r_{1}}(w)\cap\widetilde{\Lambda}_{t}} v_{t}^{z} \right)$$

Since the next annulus, $\mathbb{A}_{r_2,7r_2}(w) \subset B_{4r_1}(w)$ ($r_2 \leq r_1/7$ by construction), this implies that

$$\sup_{\mathbb{A}_{r_2,7r_2}(w)\cap\widetilde{\Lambda}_t} v_t^z \leqslant b \left(\sup_{\mathbb{A}_{3r_1,5r_1}(w)\cap\widetilde{\Lambda}_t} v_t^z \right).$$

Step 3: Iterate.

We have shown in Step 1 that each annulus $\mathbb{A}_{r,7r}(w)$ for $r \in \{r_1, \dots, r_N\}$ satisfies the conditions required to use (6.2), so we may iterate Step 2 (N - 1) times, then apply (6.39), to get

$$\sup_{\widetilde{\Lambda}_{t}\cap\mathbb{A}_{r_{N},7r_{N}}(w)} v_{t}^{z} \leqslant b^{N-1} \left(\sup_{\mathbb{A}_{3r_{1},5r_{1}}(w)\cap\widetilde{\Lambda}_{t}} v_{t}^{z} \right) \leqslant b^{N-1} \left(\sup_{\widetilde{\Lambda}_{t}\cap\mathbb{A}_{\rho/2,d_{j}^{+}}(x_{0})} v_{t}^{z} \right).$$
(6.40)

Since the estimate (6.40) holds for all $w \in Z$, $r_N \ge \rho \epsilon_j$, and $\bigcup_{w \in Z} B_{\rho \epsilon_j}(w) \supseteq S_j$, the maximum principle applied in $B_{r_N}(w)$ for each $w \in Z$ gives

$$\sup_{\widetilde{\Lambda}_t \cap S_j} v_t^z \leqslant b^{N-1} \left(\sup_{\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2, d_j^+}(x_0)} v_t^z \right).$$
(6.41)

As previously mentioned, $v_t 1 \{ \in \widetilde{\Lambda}_t \}$ is subharmonic in $B_{\rho}(x_0)$. Therefore, as S_j disconnects $\partial B_{d_{j+1}^+}(x_0)$ from $\partial B_{\rho}(x_0)$,

$$\sup_{\widetilde{\Lambda}_{t} \cap \mathbb{A}_{\rho/2, d^{+}_{i+1}}(x_{0})} v_{t}^{z} \leqslant \sup_{\widetilde{\Lambda}_{t} \cap S_{j}} v_{t}^{z}$$

This combined with (6.41) gives

$$\sup_{\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2, d_{j+1}^+}(x_0)} v_t^z \leqslant b^{N-1} \left(\sup_{\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2, d_j^+}(x_0)} v_t^z \right).$$
(6.42)

We now recall that $N = \lfloor C_3 \log \epsilon_j^{-1/2} \rfloor$ and $\epsilon_j = 2^{-(N_0+j)}$ (6.32). Hence, the lemma statement follows from (6.42).

We conclude with the proof of the desired claim. See Figure 6.

Proof of Lemma 6.11. Let $C_1^{\pm} > 0$, $C_2^{\pm} > 0$, corresponding to (VG-i) and (VG-ii), and $a \in (0, 1)$, $C_3 > 0$, corresponding to (VG-iii), be given. Fix $b = b(\gamma) \in (0, 1)$, $N_0 \ge N_1(a, C_1^-, C_2^+) \ge 200$, and then $\alpha = \alpha(a, N_0, \gamma, C_1^-) \in (0, 1)$ which will be specified in (6.53), (6.54), and (6.45), respectively.

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FIGURE 6 Schematic outline of the proof of Lemma 6.11.

Fix $z \in B_1$, $\rho \in (0, 1)$ and $x_0 \in B_1$ such that $\overline{E}_{\rho}(x_0)$ occurs, $\overline{B}_{\rho} \subset B_1 \setminus \{z\}$ and let $\widetilde{\Lambda}_t$ be a connected component of $\Lambda_t^z \cap \mathbb{A}_{\rho/2,\rho}(x_0)$ with $\overline{\widetilde{\Lambda}_t} \cap \partial B_{\rho}(x_0) \neq \emptyset$. We assume that

$$\mu_h(\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leqslant \alpha \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0)), \tag{6.43}$$

and we seek to show that $\widetilde{\Lambda}_t \cap \partial B_{\rho/2}(x_0) = \emptyset$.

Start by decomposing the annulus via the shell decomposition $\{S_j, d_j^+\}_{j\geq 0}$ given by Lemma 6.12. We will iteratively apply Lemma 6.13 and Lemma 6.8. Suppose r > 0 and $w \in B_1$ such that $\mathbb{A}_{r,7r}(w) \subset \mathbb{A}_{\rho/2,d_{j+1}^+}(x_0)$. As $\widetilde{\Lambda}_t$ is a connected component of $\mathbb{A}_{\rho/2,\rho}(x_0)$ and $\mathbb{A}_{r,7r}(w) \in \mathbb{A}_{\rho/2,\rho}(x_0)$, we have that $\mathbb{A}_{r,7r}(w) \cap \widetilde{\Lambda}_t$ is a union of connected components of $\Lambda_t^z \cap \mathbb{A}_{r,7r}(w)$. Hence, we may use the following consequence of Lemma 6.8:

$$u_{h}(\mathbb{A}_{3r,5r}(w) \cap \widetilde{\Lambda}_{t}) \leq C_{4} \sup_{\widetilde{\Lambda}_{t} \cap \mathbb{A}_{\rho/2,d_{j+1}^{+}}(x_{0})} v_{t}^{z}$$

$$\forall j \geq 0 \text{ and all } r > 0 \text{ and } w \in B_{1} \text{ such that } \mathbb{A}_{r,7r}(w) \subset \mathbb{A}_{\rho/2,d_{j+1}^{+}}(x_{0}), \qquad (6.4)$$

where $C_4 > 0$ is a universal constant.

Step 1: Choose α and set up iteration.

We set up the iteration of Lemma 6.13 and Lemma 6.8. Start by choosing

$$\alpha := a \times 2^{-N_0 \beta^-} \times \frac{1}{C_1^- \vee 1}$$
(6.45)

so that our assumption (6.43) implies

$$\mu_h(\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leqslant a \times 2^{-N_0\beta^-} \times \frac{1}{C_1^- \vee 1} \times \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0)).$$
(6.46)

Let K_i be as in Lemma 6.13. We will show

$$\sup_{\substack{r>0, w \in B_1:\\ \mathbb{A}_{r,7r}(w) \subset \mathbb{A}_{\rho/2,d_i^+}(x_0)}} \mu_h(\widetilde{\Lambda}_t \cap \mathbb{A}_{3r,5r}(w)) \leqslant K_j, \quad \forall j \ge 0$$
(6.47)

and

$$\sup_{\widetilde{\Lambda}_t \cap \mathbb{A}_{\rho/2, d_i^+(x_0)}} v_t^z \leqslant \frac{1}{C_4 \vee 1} K_j, \quad \forall j \ge 1,$$
(6.48)

where the universal constant C_4 is from (6.44).

Once we show this, then we may take $j \to \infty$ in (6.48) and use that $\lim_{j\to\infty} K_j = 0$ to get that v_t^z is zero on $\widetilde{\Lambda}_t \cap \partial B_{d_{\infty}^+}(x_0)$, where $d_{\infty}^+ := \lim_{j\to\infty} d_j^+ \in (\rho/2, \rho)$. Since $v_t^z \mathbb{1}\{\cdot \in \widetilde{\Lambda}_t\}$ is subharmonic in $B_{\rho}(x_0)$, this implies that

$$\sup_{\widetilde{\Lambda}_t \cap \overline{B}_{\rho/2}(x_0)} v_t^z = 0, \tag{6.49}$$

implying the desired statement by the definition of Λ_t^z .

Hence, it remains to prove (6.47) and (6.48). Our strategy is to induct on $j \ge 0$ and show the following chain of implications:

 $\{(6.47) \text{ for } j \text{ and } (6.48) \text{ for } (j+1)\} \Rightarrow \{(6.47) \text{ for } (j+1) \text{ and } (6.48) \text{ for } (j+2)\}.$

We start with the base case.

Step 2: Base case j = 0. By (VG-i) and the inequality (6.46)

$$\mu_h(\bar{\Lambda}_t \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leqslant a \times M_\rho(x_0) \times 2^{-N_0\beta^-} = K_0, \tag{6.50}$$

which is (6.47) for j = 0. Since $\alpha \in (0, 1)$, by (6.43),

$$\mathbb{A}_{\rho/2,\rho}(x_0) \cap \widetilde{\Lambda}_t^c \neq \emptyset.$$

Therefore, by Lemma 6.10,

$$\sup_{\mathbb{A}_{\rho/2,\rho}(x_0)} v_t^z \leqslant c \times SG_{\rho}(x_0) \leqslant c \times C_2^+ \times \frac{1}{C_1^- \vee 1} \times M_{\rho}(x_0)$$
(6.51)

with the latter inequality following from (VG-i) and (VG-ii). The inequality (6.50) allows us to use Lemma 6.13 to see that

$$\sup_{\widetilde{\Lambda}_{t} \cap \mathbb{A}_{\rho/2,d_{1}^{+}}(x_{0})} v_{t}^{z} \leq b^{C' \times C_{3} \times N_{0}} \left(\sup_{\widetilde{\Lambda}_{t} \cap \mathbb{A}_{\rho/2,d_{0}^{+}}(x_{0})} v_{t}^{z} \right).$$
(6.52)

Now, pick

$$b := 2^{-\frac{2\beta^{-}}{(C' \times C_{3}) \vee 1}}.$$
(6.53)

We emphasize that *b* depends only on γ (through β^-) since C_3 is a universal constant. We also choose N_1 sufficiently large so that

$$2^{-\beta^{-}N_{1}} \leq a \times 2^{-\beta^{-}} \times \frac{\frac{1}{C_{4} \vee 1}}{(c \times C_{2}^{+} \times \frac{1}{C_{1}^{-} \vee 1}) \vee 1}.$$
(6.54)

Fix some $N_0 \ge N_1$. With these choices of *b* and N_0 , we have

$$b^{C' \times C_3 \times N_0} \leq 2^{-N_0 \times 2\beta^-} \leq \frac{\frac{1}{C_4 \vee 1} \times a 2^{-\beta^-(N_0+1)}}{(c \times C_2^+ \times \frac{1}{C_1^- \vee 1}) \vee 1}.$$
(6.55)

Hence, by (6.52) followed by (6.51) and (6.55),

$$\sup_{\widetilde{\Lambda}_{t} \cap \mathbb{A}_{\rho/2, d_{1}^{+}(x_{0})}} v_{t}^{z} \leq b^{C' \times C_{3} \times N_{0}} \left(\sup_{\widetilde{\Lambda}_{t} \cap \mathbb{A}_{\rho/2, \rho}(x_{0})} v_{t}^{z} \right) \leq \frac{1}{C_{4} \vee 1} a^{2^{-\beta^{-}(N_{0}+1)}} M_{\rho}(x_{0}) = \frac{1}{C_{4} \vee 1} K_{1}, \quad (6.56)$$

which is (6.48) for j = 1.

Step 3: Inductive step, $j \rightarrow (j + 1)$.

If (6.48) holds for (j + 1), then by (6.44), we have (6.47) for (j + 1). It remains to show that

 $\{(6.47) \text{ for } (j+1) \text{ and } (6.48) \text{ for } (j+1)\} \Rightarrow \{(6.48) \text{ for } (j+2)\}.$

This is similar to the argument of the base case; however, we will not need the full strength of the inductive step (unlike the base case). In particular, we will use the very crude bound $b^{C' \times C_3 \times (N_0+j)} \leq 2^{-\beta^-}$.

By (6.47) for (j + 1), we may use Lemma 6.13. Hence,

$$\begin{split} \sup_{\mathbb{A}_{\rho/2,d_{j+2}^+}(x_0)} v_t^z &\leq b^{C' \times C_3 \times (N_0 + j + 1)} \sup_{\mathbb{A}_{\rho/2,d_{j+1}^+}(x_0)} v_t^z \quad (by \ (6.38)) \\ &\leq b^{C' \times C_3 \times (N_0 + j)} \frac{1}{C_4 \vee 1} K_{j+1} \quad (by \ (6.48) \ for \ (j+1)) \\ &\leq 2^{-\beta^-} \times \frac{1}{C_4 \vee 1} K_{j+1} \quad (by \ (6.55)) \\ &= \frac{1}{C_4 \vee 1} K_{j+2} \quad (by \ (6.37)), \end{split}$$

which is (6.48) for (j + 2), completing the proof.



FIGURE 7 Covering of $\partial B_{r/2}$ by very good annuli as in the proof of Proposition 7.1. The cluster A_t is displayed in gray with a solid black border and the good annuli are light gray with a dotted black border.

7 | UPPER BOUND AND CONTINUITY

In this section we prove, using the Harnack-type estimate Proposition 6.1, that clusters do not immediately exit the unit ball and are in fact Hölder-continuous in the parameter *t*. We start with the upper bound.

Proposition 7.1. For each $r \in (0, 1)$, on an event which occurs with polynomially high probability as $T \to 0$,

$$\overline{\Lambda_t^z} \subset B_{r/2}(z), \quad \forall t \leq T, \quad \forall z \in B_{1/2}.$$

Proof. Fix $r \in (0, 1)$ and let $\overline{E}_{\rho}(x_0)$ and $\alpha \in (0, 1)$ be the event and parameter from Proposition 6.1. By Proposition 6.1, it holds with polynomially high probability as $\epsilon \to 0$ that for each $x \in (B_{1+\epsilon} \setminus B_{10\sqrt{\epsilon}}) \cap \frac{\epsilon}{100} \mathbb{Z}^2$, there exists $\rho_x \in [\epsilon, \epsilon^{1/2}]$ such that $\overline{E}_{\rho_x}(x)$ occurs. Henceforth, assume that this is the case for some $\epsilon \in (0, 2^{-20}r^2)$.

Let $\mathbf{X} \subset (B_{1+\epsilon} \setminus B_{10\sqrt{\epsilon}}) \cap \frac{\epsilon}{100} \mathbb{Z}^2$ be a set such that

$$\bigcup_{x \in \mathbf{X}} \mathbb{A}_{\rho_x/2, \rho_x}(x) \in B_1 \setminus B_{r/4}(z)$$
(7.1)

and

$$\partial B_{r/2}(z) \subset \bigcup_{x \in \mathbf{X}} B_{\rho_x/2}(x).$$
(7.2)

This is possible since for each *x*, we have $\epsilon \leq \rho_x$ and $\rho_x^{1/2} \leq r/100$ — see Figure 7.

By Lemma 2.4, it holds with polynomially high probability as $\epsilon \rightarrow 0$ that

$$\mu_h(\mathbb{A}_{\rho_x/2,\rho_x}(x)) \ge \rho_x^{2\beta^-}, \quad \forall x \in \mathbf{X}, \quad \beta^- \text{ from Lemma 2.4.}$$
(7.3)

Henceforth assume that $\epsilon \in (0, 2^{-20}r^2)$ is such that (7.3) holds.

Now choose $T \leq \alpha \epsilon^{2\beta^-}$. Then, for each $x \in \mathbf{X}$, $z \in B_{1/2}$, and each $t \leq T$,

$$\mu_h(\Lambda_t^z \cap \mathbb{A}_{\rho_y/2,\rho_y}(x)) \leq \mu_h(\Lambda_t^z)$$
 (monotonicity, Lemma 3.3)

$$\leq \alpha \epsilon^{2\beta^{-}}$$
 (choice of *T* and Lemma 3.4)

$$\leq \alpha \rho_x^{2\beta^-} \qquad (\rho_x \geq \varepsilon)$$
$$\leq \alpha \mu_h(\mathbb{A}_{\rho_x/2,\rho_x}(x)). \qquad (by (7.3)).$$

Thus, we may apply Proposition 6.1 and (7.2) to see that

$$\sup_{\partial B_{r/2}(z)} v_t^z = 0, \quad \forall t \le T, \quad \forall z \in B_{1/2}.$$
(7.4)

Since $\sup_{\partial B_1} v_t^z = 0$ by Lemma 3.4 and v_t^z is subharmonic away from $B_{r/2}(z)$, this implies

$$\sup_{B_1 \setminus B_{r/2}(z)} v_t^z = 0, \quad \forall t \le T, \quad \forall z \in B_{1/2}.$$

$$(7.5)$$

By the definition (3.3) of Λ_t , (7.5) implies that $\Lambda_t^z \subset B_{r/2}(z)$. We conclude by recalling that both the condition in the first paragraph and (7.3) hold with polynomially high probability as $\epsilon \rightarrow 0$. Π

We next prove continuity of the clusters, using a similar argument as in the proof of Proposition 7.1.

Proposition 7.2. The following occurs on an event of probability 1. For each t > 0 and $z \in B_1$ such that $\Lambda_t^z \Subset B_1$, for all $\epsilon > 0$ sufficiently small, depending on t,

$$\Lambda_{t+\epsilon}^{z} \in \Lambda_{t}^{z} + B_{\delta}(z), \quad \text{for } \delta = C\epsilon^{1/(4\beta^{-})},$$

where $\beta^- > (2 + \gamma)^2/2$ is from Lemma 2.4 and $C = C(\beta^-) > 0$ is a deterministic constant.

Proof. Let $E_{\rho}(x_0)$ and $\alpha \in (0,1)$ be the event and parameter from Proposition 6.1. By Proposition 6.1, it holds with polynomially high probability as $\delta \to 0$ that for each $x \in (B_{1+\delta} \setminus B_{10\sqrt{\delta}}) \cap$ $\frac{\delta}{100}\mathbb{Z}^2$, there exists $\rho_x = \rho_x(\delta) \in [\delta, \delta^{1/2}]$ such that $\overline{E}_{\rho_x}(x)$ occurs. By Lemma 2.4, it also holds with polynomially high probability as $\delta \rightarrow 0$ that

$$\mu_h \Big(\mathbb{A}_{\rho_x/2, \rho_x}(x) \Big) \ge \rho_x^{2\beta^-}, \quad \forall x \in (B_{1+\delta} \setminus B_{10\sqrt{\delta}}) \cap \frac{\delta}{100} \mathbb{Z}^2.$$
(7.6)

By the Borel–Cantelli lemma, a.s. there exists M_0 sufficiently large such that the preceding two

conditions hold for each $\delta \in \{2^{-n}\}_{n \ge M_0}$. Let t > 0, and $z \in B_1$ such that $\Lambda_t^z \in B_1$. By Proposition 4.1, there exists $\epsilon_0(t) > 0$ so that $B_{\epsilon_0}(z) \subset \Lambda_t^z$. Hence, since $\Lambda_t^z \in B_1$, by taking M_0 possibly larger (depending on ϵ_0), we can arrange that

$$(\Lambda_t^z + B_{20\sqrt{\delta}}) \setminus (\Lambda_t^z + B_{\sqrt{\delta}}) \in B_1 \setminus B_{10\sqrt{\delta}}(z), \quad \forall \delta \in \{2^{-n}\}_{n \ge M_0}.$$

$$(7.7)$$

By (7.7) and the fact that $\rho_x \in [\delta, \delta^{1/2}]$, we obtain that for each $\delta \in \{2^{-n}\}_{n \ge M_0}$, there exists **X** = $\mathbf{X}(\delta) \subset (B_{1+\delta} \setminus B_{10\sqrt{\delta}}) \cap \frac{\delta}{100} \mathbb{Z}^2$ for which

$$(\Lambda_t^z + B_{4\sqrt{\delta}}) \setminus (\Lambda_t^z + B_{3\sqrt{\delta}}) \Subset \bigcup_{x \in \mathbf{X}} B_{\rho_x/2}(x) \Subset B_{1-10\sqrt{\delta}}$$
(7.8)

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and

$$\bigcup_{x \in \mathbf{X}} B_{\rho_x}(x) \in (\Lambda_l^z)^c$$
(7.9)

for each $\delta \in \{2^{-n}\}_{n \ge M_0}$. As $\Lambda_t^z \in B_1$, by Lemma 3.4, we have $\mu_h(\Lambda_t^z) = t$. Thus, by monotonicity, Lemma 3.3,

$$\mu_h(\Lambda_{t+\epsilon}^z \backslash \Lambda_t^z) \leqslant \epsilon, \quad \forall \epsilon > 0.$$

Therefore, by (7.9), whenever $\delta \in \{2^{-n}\}_{n \ge M_0}$, we have

$$\mu_h(\mathbb{A}_{\rho_x/2,\rho_x}(x) \cap \Lambda^z_{t+\epsilon}) \le \epsilon, \quad \forall x \in \mathbf{X}, \quad \forall \epsilon > 0.$$
(7.10)

Now set

$$\epsilon = \epsilon(\delta) := \alpha \delta^{2\beta^{-}}$$

(where α is as in Proposition 6.1). Then, for each $\delta \in \{2^{-n}\}_{n \ge M_0}$ and each $x \in \mathbf{X}$, we have

$$\mu_{h}(\mathbb{A}_{\rho_{x}/2,\rho_{x}}(x) \cap \Lambda_{t+\epsilon}^{z}) \leq \alpha \delta^{2\beta^{-}} \quad (by (7.10))$$
$$\leq \alpha \rho_{x}^{2\beta^{-}} \quad (\rho_{x} \geq \delta)$$
$$\leq \alpha \mu_{h}(\mathbb{A}_{\rho_{x}/2,\rho_{x}}(x)) \quad (by (7.6)).$$

Therefore, as the event $\overline{E}_{\rho_x}(x)$ occurs for each $x \in \mathbf{X}$, by Proposition 6.1,

$$B_{\rho_{x}/2}(x) \cap \Lambda^{z}_{t+\varepsilon} = \emptyset, \quad \forall x \in \mathbf{X}, \quad \forall \delta \in \{2^{-n}\}_{n \ge M_{0}}.$$

This implies by (7.8) that

$$\sup_{(\Lambda_t^z + B_4\sqrt{\delta}) \setminus (\Lambda_t^z + B_3\sqrt{\delta})} v_{t+\epsilon}^z = 0, \quad \forall \delta \in \{2^{-n}\}_{n \ge M_0}.$$
(7.11)

Since $\sup_{\partial B_1} v_{t+\epsilon}^z = 0$ by Lemma 3.4 and $v_{t+\epsilon}^z$ is subharmonic away from z, (7.11) implies

$$\sup_{B_1 \setminus (\Lambda_t^z + B_{3\sqrt{\delta}})} v_{t+\epsilon}^z = 0, \quad \forall \delta \in \{2^{-n}\}_{n \ge M_0}.$$
(7.12)

By the definition (3.3) of $\Lambda_{t+\epsilon}^z$, this implies that

$$\Lambda_{t+\epsilon}^{z} \in \Lambda_{t}^{z} + B_{4\sqrt{\delta}}, \quad \forall \delta \in \{2^{-n}\}_{n \ge M_{0}}.$$

$$(7.13)$$

Recalling that $\epsilon = \alpha \delta^{2\beta^{-}}$, this concludes the proof.

For completeness, we indicate how the above two results imply Proposition 5.1 and Proposition 5.2.

Proof of Propositions 5.1 and 5.2. Proposition 5.1 follows immediately from Proposition 7.1.

The fact that the clusters continuously increase in t, (5.3), is implied by Proposition 7.2. We show here that Proposition 7.1 implies that the clusters decrease to the center point, (5.2).

By Proposition 4.1, for each t > 0 and $z \in B_{1/2}$, there exists $\epsilon(t) > 0$ so that $B_{\epsilon(t)}(z) \subset \Lambda_t^z$. By Proposition 7.1 and the Borel–Cantelli lemma, applied to a sequence of dyadic radii, $r_n := \{2^{-n}\}_{n \ge 2}$, a.s. there exists a sequence of positive times $\{t_n\}_{n \ge 2}$ so that

$$\overline{\Lambda_{t_n}^z} \Subset B_{r_n}(z), \quad \forall n \ge 2$$

The desired claim follows by combining the previous two sentences with monotonicity of the clusters in *t*, Lemma 3.3.

8 | BOUNDARY HAS MEASURE ZERO

We show that the boundary of a cluster compactly embedded in the unit ball has LQG-measure zero.

Proposition 8.1. On an event of probability 1,

$$\mu_h(\partial \Lambda_t^z) = 0$$
 for all $z \in B_1$ with $\Lambda_t^z \in B_1$

Our strategy for doing so is to use the Lebesgue density theorem together with some of the intermediate results from Section 6.

The Lebesgue density theorem for general Radon measures on \mathbb{C} [64, Corollary 2.14] shows that a.s. for every Borel set X, the set of μ_h -density points of X has full μ_h -mass, that is,

$$\lim_{r \to 0} \frac{\mu_h(B_r(z) \cap X)}{\mu_h(B_r(z))} = 1, \quad \text{for } \mu_h\text{-a.e. } z \in X.$$
(8.1)

We want to deduce Proposition 8.1 from the density theorem for μ_h in Euclidean balls (8.1) together with the Harnack-type estimate from Section 6. However, the results of Section 6 are in terms of the LQG mass of the intersection of a cluster with an annulus. In order to compare the μ_h -masses of balls and annuli, we require a doubling property for the μ_h -masses of Euclidean balls, that is, an up-to-constants comparison of the μ_h -masses of $B_{2^{-n}}(z)$ and $B_{2^{-n-1}}(z)$ with the constant independent of *n* and *z*. That is, we require an event of the form,

$$G_n(z) = G_n(z;m) := \left\{ \mu_h(\mathbb{A}_{2^{-n-1},2^{-n}}(z)) \ge m\mu_h(B_{2^{-n}}(z)) \right\}$$
(8.2)

for $z \in \mathbb{C}$ and m > 0. Due to the randomness of μ_h , such an event does not hold uniformly over all choices of *n* and *z*. Instead, we will show that for μ_h -a.e. $z \in \mathbb{C}$, one has this estimate *and* a Harnack-type property for "most" large values of *n*. For convenience, write

$$\overline{E}_n(z) := \overline{E}_{2^{-n}}(z) \tag{8.3}$$

for $z \in \mathbb{C}$ and $n \in \mathbb{N}$ where $\overline{E}_{\rho}(z)$ is the very good event from Section 6.1.

Lemma 8.2. Let $\zeta > 0$ and $b \in (0, 1)$. There exists m > 0 and parameters corresponding to the event $\overline{E}_{\rho}(z) = \overline{E}_{\rho}(z; N_0, a, b, C_1^{\pm}, C_2^{\pm}, C_3)$ (from Section 6.1) such that a.s. for μ_h -a.e. $z \in B_1$, it holds for each large enough $N \in \mathbb{N}$ (depending on z) that

$$\#\left\{n \in [N+1,2N] \cap \mathbb{Z} : \overline{E}_n(z) \text{ and } G_n(z) \text{ occur}\right\} \ge (1-\zeta)N.$$
(8.4)

Recall that $h^{\mathbb{C}} = h + \alpha_0 \log |\cdot|$ is the whole plane GFF as defined in (2.1). It is a standard fact from LQG theory that if $U \subset \mathbb{C}$ is open and Z is sampled from $\mu_{h^{\mathbb{C}}}|_U$, normalized to be a probability measure, then near Z the field h locally looks like $\tilde{h} - \gamma \log |\cdot -Z|$, where \tilde{h} is a GFF sampled independently from Z (see, e.g., [23, Section 3.3]). Hence, Lemma 8.2 will turn out to be a consequence of the following statement for a GFF with a logarithmic singularity at 0.

Lemma 8.3. Let $\zeta > 0$ and $b \in (0, 1)$. There exists m > 0 and parameters corresponding to the event $\overline{E}_{\rho}(0) = \overline{E}_{\rho}(0; N_0, a, b, C_1^{\pm}, C_2^{\pm}, C_3)$ (from Section 6.1) such that a.s. for each large enough $N \in \mathbb{N}$, the condition (8.4) holds.

Proof. By the scale invariance of the law of *h*, viewed modulo additive constant (2.5), and the LQG coordinate change formula for μ_h (Fact 2.1), the law of

$$\mu_h(\mathbb{A}_{2^{-n-1},2^{-n}}(0))/\mu_h(B_{2^{-n}}(0))$$

does not depend on *n*. Furthermore, this random variable is a.s. finite and strictly larger than 0. Hence, $\mathbb{P}[G_n(0;m)]$ does not depend on *n* and we can find $m = m(\alpha, \zeta, \gamma) > 0$ such that

$$\mathbb{P}[G_n] \ge 1 - \zeta/8, \quad \forall n \in \mathbb{N}, \quad \text{where } G_n := G_n(0;m).$$
(8.5)

By Lemma 6.7, there is a choice of parameters so that

$$\mathbb{P}[\overline{E}_n] \ge 1 - \zeta/8, \quad \forall n \ge 0, \quad \text{where } \overline{E}_n := \overline{E}_n(0). \tag{8.6}$$

Hence, by a union bound,

$$q := \mathbb{P}[\overline{E}_n \cap G_n] \ge 1 - \zeta/4. \tag{8.7}$$

By the scale invariance of the law of *h* modulo additive constant and the fact that the occurrence of the event $G_n \cap \overline{E}_n$ does not depend on the choice of additive constant for *h*, the sequence of random variables

$$\{1_{G_n \cap \overline{E}_n}\}_{n \ge 0}$$

is stationary. Hence, by the Birkhoff ergodic theorem,

$$\frac{1}{N}\sum_{n=1}^{N}\mathbf{1}_{G_{n}\cap\overline{E}_{n}}$$

converges a.s. and in L^1 to a (possibly random) limit. The limiting random variable is measurable with respect to the σ -algebra $\bigcap_{\varepsilon>0} \sigma(h|_{B_{\varepsilon}(0)})$, which is trivial (see [22, Lemma 7.2] for a proof of

the analogous tail triviality statement for a free-boundary GFF; the proof for a whole-plane GFF is similar). Therefore, the limiting random variable is a.s. constant, and hence is a.s. equal to the number q from (8.7). Consequently, a.s.

$$\lim_{N \to \infty} \frac{1}{N} \sum_{n=1}^{N} \mathbf{1}_{G_n \cap \overline{E}_n} = q.$$
(8.8)

Hence,

$$\lim_{N \to \infty} \frac{1}{N} \sum_{n=N+1}^{2N} \mathbf{1}_{G_n \cap \overline{E}_n} = \lim_{N \to \infty} \frac{1}{N} \sum_{n=1}^{2N} \mathbf{1}_{G_n \cap \overline{E}_n} - \lim_{N \to \infty} \frac{1}{N} \sum_{n=1}^N \mathbf{1}_{G_n \cap \overline{E}_n} = 2q - q \ge 1 - \zeta/2.$$
(8.9)

By the definition of G_n and \overline{E}_n , this implies the lemma statement.

Proof of Lemma 8.2. Recall that $h = h^{\mathbb{C}} - \alpha_0 \log |\cdot|$, where $h^{\mathbb{C}}$ is a whole-plane GFF normalized so that $h_1^{\mathbb{C}}(0) = 0$. By Weyl scaling, we have $\mu_{h^{\mathbb{C}}} = |\cdot|^{\alpha_0 \gamma} \mu_h$. Conditional on h, let Z be sampled from $|\cdot|^{\alpha_0 \gamma} \mu_h|_{B_1}$, normalized to be a probability measure. By [22, Lemma A.10], the law of the pair (h, Z) is mutually absolutely continuous with respect to the law of the pair (\tilde{h}, \tilde{Z}) , where \tilde{Z} is sampled from Lebesgue measure in B_1 independently from h and $\tilde{h} = h - \gamma \log |\cdot -\tilde{Z}| + \gamma \log \max\{|\cdot|, 1\}$, with h and \tilde{h} viewed as distributions modulo additive constant.

From the definitions of $G_n(\tilde{Z})$ and $\overline{E}_n(\tilde{Z})$ and the locality property of $\mu_{\tilde{h}}$ (Fact 2.1), we have

$$G_{n}(\tilde{Z}) \cap \overline{E}_{n}(\tilde{Z}) \in \sigma\left(\tilde{Z}, h|_{B_{2^{-n+1}}(\tilde{Z})}\right).$$

$$(8.10)$$

Almost surely, $\tilde{Z} \neq 0$. If $r < |\tilde{Z}|$, then the restriction of \tilde{h} to $B_r(\tilde{Z})$ is equal to the restriction of a whole-plane GFF to $B_r(\tilde{Z})$ plus $-\gamma \log |\cdot -\tilde{Z}|$ plus the function $-\alpha_0 \log |\cdot| + \gamma \log \max\{|\cdot|, 1\}$, which is smooth on $B_r(\tilde{Z})$. By standard absolute continuity results for the GFF (see, e.g., [68, Proposition 2.9]), the conditional law of $\tilde{h}|_{B_r(\tilde{Z})}$ given \tilde{Z} is absolutely continuous with respect to the law of the corresponding restriction of a whole-plane GFF plus $-\gamma \log |\cdot -\tilde{Z}|$. From this, (8.10), Lemma 8.3 (with $\alpha_0 = \gamma$), and the translation invariance of the law of the whole-plane GFF, viewed modulo additive constant, we get that if the parameters for $\overline{E}_n(\cdot)$ and $G_n(\cdot)$ are chosen as in Lemma 8.3, then a.s. for each large enough $N \in \mathbb{N}$,

$$\#\left\{n \in [N+1,2N] \cap \mathbb{Z} : \overline{E}_n(\tilde{Z}) \text{ and } G_n(\tilde{Z}) \text{ occur with } \tilde{h} \text{ in place of } h\right\} \ge (1-\zeta)N.$$
(8.11)

By absolute continuity, the same is also true with (h, Z) in place of (\tilde{h}, \tilde{Z}) . Since Z is sampled from $|\cdot|^{\alpha_0 \gamma} \mu_h|_{B_1}$, we get that a.s. the lemma statement holds for μ_h -a.e. $z \in B_1$.

We conclude with a proof of the desired claim.

Proof of Proposition 8.1. By Lemma 6.11 and Lemma 8.2, we can choose parameters *b*, N_0 , $a, C_1^{\pm}, C_2^{\pm}, C_3, c, m$ so that for some fixed $\alpha \in (0, 1)$, it holds for all $z \in B_1$, $x_0 \in B_1 \setminus \{z\}$ with $\overline{B}_{\rho}(x_0) \subset B_1 \setminus \{z\}$ that

$$\overline{E}_{\rho}(x_0) \operatorname{occurs} \Rightarrow \{\mu_h(\Lambda_t^z \cap \mathbb{A}_{\rho/2,\rho}(x_0)) \leqslant \alpha \mu_h(\mathbb{A}_{\rho/2,\rho}(x_0)) \Rightarrow \Lambda_t^z \cap B_{\rho/2}(x_0) = \emptyset\}$$
(8.12)

 \Box

and the implication of Lemma 8.2 holds with $\zeta = 1/2$.

We will now show that $\mu_h(\partial \Lambda_t^z) = 0$ for every t > 0 and $z \in B_1$ such that $\Lambda_t^z \in B_1$. By (8.1), a.s. for every t > 0, we have

$$\lim_{\rho \to 0} \frac{\mu_h(B_\rho(w) \cap \partial \Lambda_t^z)}{\mu_h(B_\rho(w))} = 1, \quad \text{for } \mu_h\text{-a.e. } w \in \partial \Lambda_t^z.$$
(8.13)

Since Λ_t^z is open, we have $\Lambda_t^z \cap \partial \Lambda_t^z = \emptyset$, so (8.13) implies that

$$\lim_{\rho \to 0} \frac{\mu_h(B_\rho(w) \cap \Lambda_t^z)}{\mu_h(B_\rho(w))} = 0, \quad \text{for } \mu_h\text{-a.e. } w \in \partial \Lambda_t^z.$$
(8.14)

In particular, for μ_h -a.e. $w \in \partial \Lambda_t^z$, it holds for each large enough $n \in \mathbb{N}$ that

$$\mu_h(B_{2^{-n}}(w) \cap \Lambda_t^z) \leqslant \alpha \times m \times \mu_h(B_{2^{-n}}(w)), \tag{8.15}$$

where α is as in Lemma 6.11 and *m* is as in the definition (8.2) of $G_n(w; m)$.

By Lemma 8.2, it is a.s. the case that for μ_h -a.e $w \in B_1$, there are arbitrarily large values of n such that $\overline{E}_n(w)$ and $G_n(w)$ occur. Hence, a.s. for each t > 0, it holds for μ_h -a.e. $w \in \partial \Lambda_t^z$ that there are arbitrarily large values of n such that $\overline{E}_n(w) \cap G_n(w)$ occurs and

$$\mu_{h}(\mathbb{A}_{2^{-n-1},2^{-n}}(w) \cap \Lambda_{t}^{z}) \leq \mu_{h}(B_{2^{-n}}(w) \cap \Lambda_{t}^{z})$$
$$\leq \alpha \times m \times \mu_{h}(B_{2^{-n}}(w)) \qquad (by (8.15))$$
$$\leq \alpha \mu_{h}(\mathbb{A}_{2^{-n-1},2^{-n}}(w) \cap \Lambda_{t}^{z}) \qquad (since G_{n}(w) \text{ holds}).$$

Since $\overline{E}_n(w)$ holds, this implies by (8.12) that

$$\Lambda_t^z \cap B_{2^{-n-1}}(w) = \emptyset,$$

which shows that $w \notin \partial \Lambda_t^z$. Hence, we have shown that a.s., it holds for each t > 0 that μ_h -a.e. $w \in \partial \Lambda_t^z$ does not belong to $\partial \Lambda_t^z$, which means that $\mu_h(\partial \Lambda_t^z) = 0$.

9 | UNIQUENESS OF HARMONIC BALLS

In this section, we show that there is only one family of harmonic balls satisfying the conditions given by Theorem 1.1.

9.1 | Uniqueness of subharmonic balls

The uniqueness of subharmonic balls (defined in (4.5)) for the Lebesgue measure is well known, see, for example, [79], and the proof extends verbatim to γ -LQG subharmonic balls. The idea is that every subharmonic ball generates a supersolution to the obstacle problem.

Lemma 9.1 (Theorem 2.1 in [79, 82]). Let R > 0, $z \in B_R$ and let A be a domain strictly contained which contains z and let

$$f(x) = \mu_h(A)G_{B_R}(x, z) - \int_A G_{B_R}(x, y)\mu_h(dy).$$
(9.1)

- (1) If A is a subharmonic ball centered at z, then $f \ge 0$ on B_R .
- (2) If A is a harmonic ball centered at z, then f = 0 on $B_R \setminus A$.

Proof. (1)

For all $x \in B_R$, the function $g(w) := G_{B_R}(w, x)$ is superharmonic in A, so -g is subharmonic in A. Then, since A is a subharmonic ball centered at z,

$$\int_{A} g(w)\mu_{h}(dw) \leqslant \mu_{h}(A)g(z), \tag{9.2}$$

and so,

$$\int_{A} G_{B_{R}}(w, x)\mu_{h}(dw) \leq \mu_{h}(A)G_{B_{R}}(x, z), \quad \forall x \in B_{R}.$$
(9.3)

(2)

In this case, the function $g(w) = G_{B_R}(w, x)$ is harmonic in A for all $x \in B_R \setminus A$. Hence, since A is a harmonic ball,

$$\int_{A} G_{B_R}(w, x) \mu_h(dw) = \mu_h(A) G_{B_R}(x, z), \quad \forall x \in B_R \backslash A.$$
(9.4)

The prior lemma implies uniqueness (up to sets of μ_h -measure zero) of subharmonic balls.

Proposition 9.2. The following holds on an event of probability 1. Let $A \in B_R$ be a subharmonic ball centered at $z \in B_R$ with $\mu_h(A) = t$ for some t, R > 0. Then, $\Lambda_t^{B_R;z} \subset A$ and $\mu_h(A \setminus \Lambda_t^{B_R;z}) = 0$.

Proof. Let *f* be given by (9.1) and note that by Lemma 9.1 (and since every subharmonic ball is a harmonic ball), $f \ge 0$ in B_R and f = 0 on $B_R \setminus A$. Since $f \ge 0$ and $\Delta f \le -\mu_h(A)\delta_z + \mu_h$ on B_R , we have that $(f(\cdot) - tG_{B_R}(z, \cdot)) \in S_t^{B_R;z}$ and hence $f \ge v_t^{B_R;z}$. This implies, together with f = 0 on $B_R \setminus A$, that $\Lambda_t^{B_R;z} \subset A$. Since $t = \mu_h(A) = \mu_h(\Lambda_t^{B_R;z})$, this completes the proof.

We do not use Proposition 9.2 in this paper but decided to include it explicitly as it may be useful for future work.

9.2 | Comparing harmonic and subharmonic balls

We show that any harmonic ball for μ_h (in the sense of (1.1)) centered at *z* must have a boundary contained in the closure of some Λ_t^z . Similar arguments have appeared in [82, Proposition 3.2], [41, Proposition 2.5], and [26, Section 3].

Lemma 9.3. Almost surely, every harmonic ball $A \in B_R$ centered at $z \in B_R$ with $t = \mu_h(A) > 0$ satisfies $\partial A \subset \overline{\Lambda_t(z)}$.

Proof. Let A be a harmonic ball centered at $z \in B_R$ with $t = \mu_h(A) > 0$ and $A \in B_R$. Take R possibly larger so that $\Lambda_t^{B_R;z} \in B_R$ and hence by Theorem 5.5, $\Lambda_t^{B_R;z} = \Lambda_t(z)$ is a subharmonic ball in B_R centered at z. We show that $\partial A \subset \overline{\Lambda_t}(z)$ by considering the auxiliary function

$$u(x) := \int_{A} G_{B_{R}}(x, y) \mu_{h}(dy) - \int_{\Lambda_{t}(z)} G_{B_{R}}(x, y) \mu_{h}(dy),$$
(9.5)

which satisfies $\Delta u = (1_{\Lambda_t(z)} - 1_A)\mu_h$ on B_R .

Step 1: $u \ge 0$ in B_R .

By Lemma 9.1, as A is a harmonic ball centered at z

$$tG_{B_R}(x,z) = \int_A G_{B_R}(x,y)\mu_h(dy) \quad \text{on } B_R \setminus A,$$
(9.6)

and as $\Lambda_t(z)$ is a subharmonic ball centered at z

$$tG_{B_R}(x,z) \ge \int_{\Lambda_t(z)} G_{B_R}(x,y)\mu_h(dy) \quad \text{on } B_R.$$
(9.7)

Combining (9.6) and (9.7) shows

$$u \ge 0 \quad \text{on } B_R \setminus A.$$
 (9.8)

As *u* is superharmonic on *A*, (9.8) together with the minimum principle shows $u \ge 0$ on B_R . Step 2: u = 0 on $B_R \cap \Lambda_t(z)^c \cap A^c$.

As $\Lambda_t(z)$ is also a harmonic ball, by Lemma 9.1,

$$tG_{B_R}(x,z) = \int_{\Lambda_l(z)} G_{B_R}(x,y)\mu_h(dy) \quad \text{on } B_R \setminus \Lambda_l(z).$$
(9.9)

Step 2 follows by combining (9.6) and (9.9) with the definition of u.

Step 3: Conclude.

We use the fact $\Delta u = (1_{\Lambda_t(z)} - 1_A)\mu_h$ on B_R . Suppose for sake of contradiction that there is $x_0 \in \partial A \setminus \overline{\Lambda_t(z)}$. Then, *u* is superharmonic in a neighborhood of x_0 as $x_0 \in (\overline{\Lambda_t(z)})^c$. By Step 2, $u(x_0) = 0$, which, together with Step 1 and the strong minimum principle, shows that *u* is identically 0 in a neighborhood of x_0 . This, in turn, implies that *u* is harmonic in a neighborhood of x_0 .

However, as $x_0 \in \overline{\Lambda_t(z)}$, we have that $\Delta u = -1_A \mu_h$ in a neighborhood of x_0 . As μ_h assigns positive mass to every open set, A is open, and $x_0 \in \partial A$, Δu is strictly negative on an open subset of every neighborhood of x_0 , which supplies the desired contradiction.

9.3 | Strong uniqueness

We first show that two regular open sets that coincide μ_h -a.e. are in fact equal. This fact is the reason for our assumption that $int(\overline{\Lambda}_t) = \Lambda_t$ in Theorem 1.1.

Lemma 9.4. Almost surely, the following is true. Let X and Y be two open subsets of \mathbb{C} such that $int(\overline{X}) = X$ and $int(\overline{Y}) = Y$. If $\mu_h(X \setminus Y) = \mu_h(Y \setminus X) = 0$, then X = Y.

Proof. We use the fact that a.s. μ_h assigns positive mass to every open set to show that $X \setminus Y = \emptyset$. A symmetric argument shows $Y \setminus X = \emptyset$.

Suppose for the sake of contradiction that there is $x_0 \in X \cap Y^c$. As X is open, $B_r(x_0) \subset X$ for all $r < r_0$, where r_0 is some small radius. As $\mu_h(X \cap Y^c) = 0$, $B_r(x_0) \notin Y^c$ for all $r < r_0$. Thus, x_0 is a limit point of Y and so $x_0 \in \partial Y$ by definition. Since $\operatorname{int}(\overline{Y}) = Y$, x_0 cannot be in the interior of \overline{Y} , so x_0 must be an accumulation point of \overline{Y}^c . Since \overline{Y}^c is open, this implies that every neighborhood of x_0 contains an open subset of \overline{Y}^c . Hence, $X \cap \overline{Y}^c \subset X \cap Y^c$ contains a nonempty open set. This implies $B_r(x_0) \cap Y^c$ contains a nonempty open set, and hence that $\mu_h(X \cap Y^c) > 0$, a contradiction.

We now use Lemma 9.4 to show uniqueness of the family of harmonic balls satisfying the conditions of Theorem 1.1. Our proof is inspired by the proof of Theorem 10.13 in [77].

Proof of Proposition 5.6. Let $t_0 > 0$ and $z \in \mathbb{C}$ be given and suppose $A_{t_0} \in B_R$ for some R > 0. By Lemma 9.4, it suffices to show that $\mu_h(A_{t_0} \setminus \Lambda_{t_0}) = \mu_h(\Lambda_{t_0}(z) \setminus A_{t_0}) = 0$. As we have assumed $\mu_h(A_{t_0}) = t_0$, we only need to show that $\mu_h(A_{t_0} \setminus \Lambda_{t_0}(z)) = 0$.

Suppose for the sake of contradiction that $\mu_h(A_{t_0} \setminus \Lambda_{t_0}(z)) > 0$. Since $\mu_h(\partial \Lambda_{t_0}(z)) = 0$, this implies $\mu_h(A_{t_0} \setminus \overline{\Lambda_{t_0}(z)}) > 0$. In particular, as $A_{t_0} \setminus \overline{\Lambda_{t_0}(z)}$ is open, there exists a nonempty ball $B \subset A_{t_0} \setminus \overline{\Lambda_{t_0}(z)}$ which lies at positive distance from the origin. We will show that *B* cannot exist by monotonicity

$$A_a \subseteq A_b$$
 and $\Lambda_a \subseteq \Lambda_b$, $\forall a \le b$ (9.10)

and Lemma 9.3,

$$\partial A_t \subset \overline{\Lambda_t(z)}, \quad \forall t > 0.$$
 (9.11)

As the family $\{A_t\}_{t>0}$ continuously decreases to $\{z\}$ as $t \to 0$, there exists some $0 < s_0 < t_0$ for which

$$B \subset A^c_{s_0}. \tag{9.12}$$

Now let, $s_0 < s_1 < \cdots < s_m = t_0$ be a sequence of points satisfying,

$$s_n < s_{n+1} \le s_n + \mu_h(B)/2 \quad \forall n \in \{0, \dots, m-1\}.$$
 (9.13)

We show by induction on *n* that for each $0 \le n \le m$,

$$B \subset A^c_{S_n},\tag{9.14}$$

which contradicts $B \subset A_{t_0}$. The base case n = 0 is established by (9.12).

Now assume (9.14) holds for $n \in \{0, ..., m-1\}$. We show that for

$$s_{n+1} \in [s_n, \min(s_n + \mu_h(B)/2, t_0)],$$
(9.15)

we must have

$$B \subset A^c_{s_{n+1}}.\tag{9.16}$$

First note that the interval (9.15) is nonempty as $B \subset A_{t_0}$, $B \subset A_{s_n}^c$, and $\mu_h(A_t) = t$ for all t > 0. Moreover, as $B \subset (\overline{\Lambda_{t_0}(z)})^c$ and $t_0 \ge s_{n+1}$, by monotonicity (9.10), $B \subset (\overline{\Lambda_{s_{n+1}(z)}})^c$. This together with (9.11) implies $B \cap \partial A_{s_{n+1}} = \emptyset$; equivalently

$$B \subset A_{s_{n+1}}$$
 or $B \subset \overline{A_{s_{n+1}}}^c$. (9.17)

The former case in (9.17) is impossible as

$$\mu_h(A_{s_{n+1}} \cap B) \leq \mu_h(A_{s_n+\mu_h(B)/2} \cap B) \quad (s_{n+1} \leq s_n + \mu_h(B)/2)$$

$$= \mu_h(A_{s_n} \cap B) + \mu_h((A_{s_n+\mu_h(B)/2} \setminus A_{s_n}) \cap B) \quad (\text{additivity of measure})$$

$$\leq \mu_h(A_{s_n} \cap B) + \mu_h(B)/2 \quad (\text{monotonicity and } \mu_h(A_t) = t, \forall t)$$

$$= \mu_h(B)/2 \quad (\text{by (9.14)}),$$

which shows (9.16).

10 | BOUNDARY CURVES OF HARMONIC BALLS

In this section, we show that harmonic balls have boundaries that are simple loops. We first consider clusters $\Lambda_t \in B_1$ and then rescale to achieve the result for all $\{\Lambda_t\}_{t>0}$.

Our main result is essentially a consequence of the following lemma, which limits how many times clusters cross annuli — see Figure 8.

Lemma 10.1. Almost surely, for each small enough $\epsilon > 0$, it holds for each $w \in B_1 \setminus B_{20\sqrt{\epsilon}}$ that there is a $\rho \in [\epsilon, \epsilon^{1/2}]$ (depending on w) such that for every t > 0 and $z \in \mathbb{C}$, we have that $\Lambda_t(z)$ does not cross $\mathbb{A}_{\rho/3,2\rho}(w)$ more than $K := \lceil 1/\alpha \rceil$ times for all $\Lambda_t(z) \in B_1$ where $\alpha = \alpha(\gamma) \in (0,1)$ is as in Proposition 6.2. That is, there are at most K connected components of $\Lambda_t(z) \cap B_{2\rho}(w)$ whose closures intersect both $\partial B_{\rho/3}(w)$ and $\partial B_{2\rho}(w)$.

Proof. Let t > 0 such that $\Lambda_t(z) \in B_1$. By Proposition 6.1 and the Borel–Cantelli lemma, a.s. there exists a random $M_0 \in \mathbb{N}$ and a deterministic $\alpha \in (0, 1)$ such that for all $\epsilon \in \{2^{-n}\}_{n \ge M_0}$, we have that for each $x_0 \in (B_{1+\epsilon} \setminus B_{10\sqrt{\epsilon}}) \cap \frac{\epsilon}{100} \mathbb{Z}^2$, there is a $\rho \in [\epsilon, \epsilon^{1/2}]$ for which $\overline{E}_{\rho}(x_0)$ occurs.

Fix $\epsilon \in \{2^{-n}\}_{n \ge M_0}$ and let $w \in B_1 \setminus B_{20\sqrt{\epsilon}}$. Let x_0 be a point of $(B_{1+\epsilon} \setminus B_{10\sqrt{\epsilon}}) \cap \frac{\epsilon}{100} \mathbb{Z}^2$ with $|x_0 - w| < \epsilon/50$ and let ρ be a radius in $[\epsilon, \epsilon^{1/2}]$ such that $\overline{E}_{\rho}(x_0)$ occurs, as in the statement of

 \Box



FIGURE 8 A situation ruled out by Lemma 10.1. The annulus $\mathbb{A}_{\rho/3,2\rho}$ is in light blue and the connected components of $\Lambda_t \cap \mathbb{A}_{\rho/3,2\rho}$ that cross the annulus are in gray.

Proposition 6.1. Note that since $\rho > \epsilon$ and $|x_0 - w| < \epsilon/50$,

$$B_{\rho}(x_0) \subset B_{2\rho}(w). \tag{10.1}$$

As $\Lambda_t(z)$ is open and connected (Lemma 3.2), and contains $\{z\}$ (Proposition 4.1), (10.1) shows that any nonempty connected component of $\Lambda_t(z) \cap B_{2\rho}(w)$ with closure intersecting $\partial B_{\rho/3}(w)$ and $\partial B_{2\rho}(w)$ must intersect $B_{\rho}(x_0)$ and have closure intersecting $\partial B_{\rho}(x_0)$ and $\partial B_{\rho/2}(x_0)$.

Also note that as $\overline{E}_{\rho}(x_0)$ occurs, Proposition 6.2 implies that

$$\overline{\tilde{\Lambda}_{t}} \cap \partial B_{\rho/2}(x_{0}) \neq \emptyset \Rightarrow \mu_{h}(\tilde{\Lambda}_{t} \cap \mathbb{A}_{\rho/2,\rho}(x_{0})) \geqslant \alpha \mu_{h}(\mathbb{A}_{\rho/2,\rho}(x_{0}))$$

$$\forall \tilde{\Lambda}_{t}, \text{ connected component of } \Lambda_{t}(z) \cap B_{\rho}(x_{0}).$$
(10.2)

By (10.1), every connected component of $\Lambda_t(z) \cap B_{2\rho}(w)$ with closure intersecting $\partial B_{\rho/3}(w)$ intersected with $B_{\rho}(x_0)$ decomposes into a union of connected components of $\Lambda_t(z) \cap B_{\rho}(x_0)$ each of which has closure intersecting $\partial B_{\rho}(x_0)$ and $\partial B_{\rho/2}(x_0)$. Thus, the relations (10.1) and (10.2) together imply that

$$\mu_{h}(\hat{\Lambda}_{t} \cap \mathbb{A}_{\rho/2,\rho}(x_{0})) \geq \alpha \mu_{h}(\mathbb{A}_{\rho/2,\rho}(x_{0}))$$

$$\forall \hat{\Lambda}_{t}, \text{ connected component of } \Lambda_{t}(z) \cap B_{2\rho}(w) \qquad (10.3)$$
such that $\overline{\hat{\Lambda}_{t}} \cap \partial B_{2\rho}(w) \neq \emptyset \text{ and } \overline{\hat{\Lambda}_{t}} \cap \partial B_{\rho/3}(w) \neq \emptyset.$

By (10.1), this is a lower bound on the mass of each connected component of $\Lambda_t(z) \cap B_{2\rho}(w)$. In particular, (10.3) implies that the number of such connected components with closures that intersect $\partial B_{\rho/3}(w)$ and $\partial B_{2\rho}(w)$ is at most $K := \lceil 1/\alpha \rceil$. This implies $\Lambda_t(z)$ can cross $\mathbb{A}_{\rho/3,2\rho}(w)$ (as in the statement of Lemma 10.1) at most K times.

We recall the definition of a loop.



FIGURE 9 A visual aid to the proof of Lemma 10.5. The annulus *A* is transparent, *U* is the gray simply connected domain, *C* is the connected violet domain, the components of $(C' \setminus C) \cap A$ are in yellow, and *P* is the path with two boundary points *a* and *b*; both *a* and *b* are in Γ , the boundary of *U*.

Definition 10.2. A set $\Gamma \subset \mathbb{C}$ is a *loop* if $\Gamma = \{\varphi(\zeta) : \zeta \in \mathbb{T}\}$ for a continuous function φ from the unit circle \mathbb{T} to \mathbb{C} . The set Γ is an *arc* if $\Gamma = \{\varphi(\zeta) : \alpha \leq \zeta \leq \beta\}$. Γ is a *simple loop [arc]* if Γ is a loop [arc] and φ is also injective.

We recall the definition of a locally connected set.

Definition 10.3. A set $X \subset \mathbb{C}$ is *locally connected* if every neighborhood of each $x \in X$ with respect to *X* contains a connected neighborhood of *x*.

We also recall the definition of cut points.

Definition 10.4. Let *A* be a compact, connected, and locally connected set. A point $a \in A$ is a *cut point* if $A \setminus \{a\}$ is no longer connected.

We will use Lemma 10.1 together with some basic properties of the cluster to show that the boundaries of the complementary connected components of the cluster are simple loops. Before doing so, we prove a topological lemma. Recall from the statement of Lemma 10.1 that a set *X* crosses an annulus $\mathbb{A}_{s_1,s_2}(z)$ if $\overline{X} \cap \partial B_{s_1}(z) \neq \emptyset$ and $\overline{X} \cap \partial B_{s_2}(z) \neq \emptyset$.

Lemma 10.5. Let $A \in B_1$ be an annulus, t > 0 and $z \in B_1$ such that $\Lambda_t(z) \in B_1$, and U a simply connected component of $\overline{\Lambda_t(z)}^c$ with $\Gamma = \partial U \in B_1$. Every connected component of $U^c \cap A$ that crosses A contains a connected component of $\Lambda_t(z) \cap A$ which crosses A.

Proof. See Figure 9.

Let *C* be a connected component of $U^c \cap A$ that crosses *A*. The "filling" of *C*, *C'*, is the union of *C* and the regions that are disconnected in *A* from the inner boundary of the annulus, the outer

boundary of the annulus, or both by *C*. Note that C' is a topological rectangle with two boundary segments that are part of the inner and outer boundaries of the annulus, respectively, and two boundary segments contained in Γ .

By, for example, the Poincaré–Miranda theorem [53], there is either a simple arc in $\Lambda_t(z) \cap C'$ between the inner and outer boundaries of the annulus, or there is a simple arc in $\Lambda_t(z)^c \cap C'$ between the two boundary segments contained in Γ . In the former case, $\Lambda_t(z)$ crosses A, and thus, there is a connected component of $\Lambda_t(z) \cap A$ in C which crosses A. Hence, it suffices to rule out the latter case, which we now do.

Suppose for sake of contradiction that there is a simple open arc P in $\Lambda_t(z)^c \cap C'$ between the two boundary segments contained in Γ . That is, P is the interior of a simple arc contained in $\Lambda_t(z)^c \cap C'$ and $\overline{P} = P \cup \{a\} \cup \{b\}$ with $\{a, b\} \subset \Gamma$.

As int(U^c) is simply connected, by [72, Proposition 2.12], int(U^c)\P has exactly two components G_0 and G_1 and these satisfy

$$\operatorname{int}(U^c) \cap \partial G_0 = \operatorname{int}(U^c) \cap \partial G_1 = P.$$
(10.4)

As ∂G_0 and ∂G_1 contain points in Γ , the boundary of a simply connected component of $\Lambda_t(z)^c$, by definition of component, both G_0 and G_1 must contain points in $\Lambda_t(z)$. However, this contradicts the fact $\Lambda_t(z)$ is connected, Lemma 3.2. Indeed,

$$\partial G_0 \cup \partial G_1 \subset \partial U \cup P \subset \Lambda_t(z)^c,$$

which implies, as $G_0 \cap \Lambda_t(z)$ and $G_1 \cap \Lambda_t(z)$ are open and disjoint, that they must lie in different connected components of $\Lambda_t(z)$.

Proposition 10.6. Almost surely, for all t > 0 and $z \in B_1$ such that $\Lambda_t(z) \in B_1$, each of the connected components of $B_1 \setminus \overline{\Lambda_t(z)}$ has a boundary that is a simple loop.

Proof. Suppose $\Lambda_t(z) \in B_1$ and let *U* be a component of $\overline{\Lambda_t(z)}^c$. Note that *U* and $\Lambda_t(z)$ are disjoint and $\partial U \subseteq \partial \Lambda_t(z) \in B_1$.

Let $\Gamma = \partial U \in B_1$. By Caratheodory's theorem [72, Theorem 2.6] to show that Γ is a Jordan loop, it suffices to show that Γ is locally connected and has no cut points.

Step 1: Locally connected.

As we will show, this follows from Lemma 10.1 and the definition of locally connected:

Suppose for the sake of contradiction that Γ is not locally connected. By [72, Theorem 2.1], this implies that U^c is not locally connected. By definition, this implies the existence of a point $z \in U^c$ and s > 0 so that for every subneighborhood $V \subset B_s(z)$ containing z, the set $V \cap U^c$ is not connected.

As U^c is connected, the closure of every component of $U^c \cap B_s(z)$ has nonempty intersection with $\partial B_s(z)$. Since U^c is closed, every such component not containing z must lie at positive distance from z. Hence, for each $\epsilon \in (0, s)$, the number of such components intersecting $B_{\epsilon}(z)$ must be infinite, as otherwise we could take V to be $B_{\epsilon}(z)$ minus the other components that do not contain z which intersect $B_{\epsilon}(z)$.

This implies that for all $\rho > 0$ sufficiently small, there is a ball $B_{2\rho}(z)$ with infinitely many distinct components of $U^c \cap B_{2\rho}(x_0)$ with closures intersecting $\partial B_{2\rho}(z)$ and $\partial B_{\rho/3}(z)$. Every connected component of $U^c \cap B_{2\rho}(z)$ intersected with $\mathbb{A}_{\rho/3,2\rho}(z)$ decomposes into a union of

connected components of $U^c \cap \mathbb{A}_{\rho/3,2\rho}(z)$. Hence, by Lemma 10.5 applied to each connected component of $U^c \cap \mathbb{A}_{\rho/3,2\rho}(z)$, every connected component of $U^c \cap B_{2\rho}(z)$ that crosses $\mathbb{A}_{\rho/3,2\rho}(z)$ contains a connected component of $\Lambda_t(z) \cap \mathbb{A}_{\rho/3,2\rho}(z)$ that crosses $\mathbb{A}_{\rho/3,2\rho}(z)$.

The previous paragraph implies that there is a ball $B_{2\rho}(z)$ with infinitely many distinct components of $\Lambda_t(z) \cap B_{2\rho}(x_0)$ with closures intersecting $\partial B_{2\rho}(z)$ and $\partial B_{\rho/3}(z)$, contradicting Lemma 10.1.

Step 2: No cut points.

Let $\psi : B_1 \to U$ be a conformal map, which exists since U is connected with connected complement, so is simply connected. Since Γ is locally connected, [72, Theorem 2.1] implies that ψ extends to a continuous map $\overline{B}_1 \to \overline{U} = U \cup \Gamma$.

Now, assume by way of contradiction that Γ has a cut point $a \in \Gamma$. By [72, Proposition 2.5], $\#\psi^{-1}(a) \ge 2$ (in principle $\#\psi^{-1}(a)$ could be infinite, even uncountable). Furthermore, if \mathcal{I} is the set of connected components of $\partial B_1 \setminus \phi^{-1}(a)$, then the set of connected components of $\Gamma \setminus \{a\}$ is $\{\psi(I) : I \in \mathcal{I}\}$.

Fix some $I \in \mathcal{I}$ and let *J* be equal to $\partial B_1 \setminus I$ minus its endpoints. Then, *I* and *J* are disjoint open arcs of ∂B_1 and their common endpoints are distinct points of $\psi^{-1}(a)$. Furthermore, the preceding paragraph implies that $\psi(\bar{I}) \cap \psi(J) = \emptyset$ and $\psi(I) \cap \psi(\bar{J}) = \emptyset$

Since Γ disconnects 0 from *y*, the homotopy class of the loop $\psi|_{\partial B_1}$ in $(\mathbb{C} \cup \infty) \setminus \{0, y\}$ is non-trivial. Since ψ maps the endpoints of *I* and *J* to *a*, each of $\psi|_I$ and $\psi|_J$ is a loop in \mathbb{C} , and $\psi|_{\partial B_1}$ is the concatenation of these two loops. The concatenation of two homotopically trivial loops is also homotopically trivial. Therefore, one of $\psi|_I$ or $\psi|_J$ is not homotopic to a point in $(\mathbb{C} \cup \infty) \setminus \{0, y\}$. This implies that one of $\psi(\overline{I})$ or $\psi(\overline{J})$ disconnects 0 from *y*.

Assume without loss of generality that $\psi(\bar{I})$ disconnects 0 from *y*. Since $\Lambda_t(z) \ni 0$ is connected (Lemma 3.2) and $U \ni y$ is connected by definition, $\Lambda_t(z)$ and *U* are contained in different connected components of $\mathbb{C} \setminus \psi(\bar{I})$. But, every point of $\psi(J) \subset \Gamma$ is an accumulation point of both $\Lambda_t(z)$ and *U*, so $\psi(J) \subset \psi(\bar{I})$. Since *J* is nonempty by construction, this contradicts the fact that $\psi(\bar{I}) \cap \psi(J) = \emptyset$. We conclude that Γ has no cut points.

The desired claim follows immediately from a scaling argument.

Proposition 10.7. Almost surely, for all t > 0 and $z \in \mathbb{C}$, each of the connected components of $\mathbb{C}\setminus \overline{\Lambda_t(z)}$ has a boundary that is a simple loop.

Proof. Combine Lemma 5.7 together with Lemma 10.1, a union bound, and the relation between Λ_t and $\{\Lambda_t^{B_r}\}_{r>0}$ given in Theorem 5.5.

11 | NOVELTY OF HARMONIC BALLS

In this section, we show that typical harmonic balls are too rough to have Lipschitz boundaries yet differ in a quantitative way from LQG-metric balls.

11.1 | Not lipschitz

In this section, we show that a "typical" harmonic ball is not a Lipschitz domain. Roughly, a Lipschitz domain is a domain whose boundary can be locally represented by a graph of a Lipschitz

function. Note that as every convex function is locally Lipschitz, see, for example, [31, Lemma 1.1.6], every convex domain, for example, a ball or polygon, is a Lipschitz domain.

Definition 11.1. Let *A* be a nonempty connected open set. *A* is a *Lipschitz domain* if for every point $x_0 \in \partial A$, there exists r > 0 and a Lipschitz function $f : \mathbb{R} \to \mathbb{R}$ such that — upon relabeling and reorienting the coordinate axes if necessary — we have

$$U \cap B_r(x_0) = \{ z \in B_r(x_0) : \operatorname{Im}(z) > f(\operatorname{Re}(z)) \}.$$

In this section, we prove the following.

Proposition 11.2. Almost surely, Λ_t is not a Lipschitz domain for Lebesgue-a.e. t.

To that end, we show that "typical" points on the boundary of the cluster do not satisfy the "cone condition." We define these terms.

Definition 11.3. A *cone* $Q \subset \mathbb{C}$ is a nonempty open set strictly contained in \mathbb{C} that can be written as $Q = \{cv + dw : c, d > 0\}$ for *extremal directions* $v, w \in \mathbb{C} \setminus \{0\}$. We also define complements of cones to be cones.

Note that any cone Q is scale invariant, that is, for any $\theta > 0$, $\theta Q = Q$. For a cone Q and $z \in \mathbb{C}$, we write Q(z) := Q + z.

Definition 11.4. A domain $A \subset \mathbb{C}$ satisfies the *interior* (respectively, *exterior*) *cone condition* at $z \in \partial A$ if there is a radius R > 0 and a cone Q such that $Q(z) \cap B_R(z) \subset A$ (respectively, $Q(z) \cap B_R(z) \subset A^c$). A satisfies the *cone condition* at $z \in \partial A$ if it satisfies both the interior and exterior cone conditions at z. See Figure 10

The main input in the proof of Proposition 11.2 is the following lemma.

Lemma 11.5. Almost surely, for μ_h -a.e. $z \in \mathbb{C}$, if t > 0 such that $z \in \partial \Lambda_t$, then Λ_t does not satisfy the cone condition at z.



FIGURE 10 A domain that satisfies the cone condition of Definition 11.4. The domain is in gray and the two cones are displayed in red.

Lemma 11.6. There exists a universal constant C > 0 such that the following holds for each r > 0and $z \in \mathbb{C}$ such that $\overline{B}_{10r}(z) \cap \{0\} = \emptyset$. If $\mathbb{A}_{4r,5r}(z) \cap \Lambda_t^c \neq \emptyset$, we have

$$\mu_h(\mathbb{A}_{r,2r}(z) \cap \Lambda_t) \leqslant C \times SG_{3r,6r}(z),$$

where $SG_{3r,6r}(z)$ is as in (6.4).

Proof. We use Lemma 6.8 and Lemma 6.10 that were both stated for $\Lambda_t^{B_1}$, $v_t^{B_1}$ but whose proofs and statements extend verbatim to $\Lambda_t^{B_R}$, $v_t^{B_R}$ for any R > 0. In the following chain of inequalities, *C* refers to a universal constant that may change from line to line,

$$\mu_{h}(\Lambda_{t} \cap \mathbb{A}_{r,2r}(z))$$

$$= \mu_{h}(\Lambda_{t}^{B_{R}} \cap \mathbb{A}_{r,2r}(z)) \quad (\text{as for some } R > 0, \mu_{h}(\Lambda_{t} \bigtriangleup \Lambda_{t}^{B_{R}}) = 0 \text{ by Theorem 5.5})$$

$$\leq C \times \sup_{\mathbb{A}_{0.5r,4r}(z)} v_{t}^{B_{R}} \quad (\text{by Lemma 6.8 with } (s_{1}, s_{2}, s_{3}, s_{4}) = (0.5, 1, 2, 4))$$

$$\leq C \times \sup_{\partial B_{4r}(z)} v_{t}^{B_{R}} \quad (v_{t}^{B_{R}} \text{ is subharmonic in } B_{10r}(z))$$

$$\leq C \times SG_{3r,6r}(z) \quad (\text{by Lemma 6.10 with } (s_{1}, s_{2}, s_{3}, s_{4}) = (3, 4, 5, 6)).$$

For a cone Q, M > 0, $z \in \mathbb{C}$, and r > 0, consider the event

$$\tilde{G}_r(z) = \tilde{G}_r(z; M, Q) := \left\{ \mu_h(\mathbb{A}_{r,2r}(z) \cap Q(z)) \ge M \times SG_{3r,6r}(z) \right\},\tag{11.1}$$

and observe that $\tilde{G}_r(z) \in \sigma(h|_{\mathbb{A}_r, \sigma_r(z)})$. We abbreviate

$$\tilde{G}_n(z) = \tilde{G}_{2^{-n}}(z), \quad \forall n \in \mathbb{N}$$
(11.2)

and prove an analog of Lemma 8.2 for rare events.

Lemma 11.7. Let Q be a cone and let M > 0. There exists $\delta = \delta(M) \in (0, 1)$ such that a.s. for μ_h -a.e. $z \in \mathbb{C}$, it holds for each large enough $N \in \mathbb{N}$ (depending on z) that

$$#\{n \in [N+1,2N] \cap \mathbb{Z} : \tilde{G}_n(z;M,Q) \text{ occurs}\} \ge \delta N.$$
(11.3)

In order to prove this lemma, we first prove the following.

Lemma 11.8. Let Q be a cone and let M > 0. There exists a constant $p_M \in (0, 1)$ so that

$$P[\tilde{G}_n(z;M,Q)] \ge p_M, \quad \forall z \text{ s.t. } \mathbf{dist}(\mathbb{A}_{2^{-n},6\times 2^{-n}}(z),\{0\}) > 2^{-n}/100, \forall n \ge N(z).$$
(11.4)

Proof. Recall from (2.4) that $h = h^{\mathbb{C}} - \alpha_0 \log |\cdot|$. We first show (11.4) in the case $\alpha_0 = 0$, and then use Weyl scaling to get the general case.

In the following, we write $SG^h_{3r,6r}(z)$ instead of $SG_{3r,6r}(z)$ to indicate the dependence on the underlying field *h*. Note that $SG^h_{3r,6r}(z)$ depends only on *h* restricted to $\mathbb{A}_{3r,6r}(z)$. Step 1: $\alpha_0 = 0$.

By definition, if $\alpha_0 = 0$, then *h* is a whole-plane GFF. We have chosen the event \tilde{G}_n so that it is a.s. determined by *h* viewed modulo additive constant. Hence, by the scale and translation invariance of the law of the whole-plane GFF (2.2), it suffices to bound $\mathbb{P}[\tilde{G}_1(0)]$ from below. This lower bound is achieved via the "adding a bump function" technique.

Since the random variables involved are finite and positive, there are γ -dependent constants C_1 and C_2 so that

$$\mathbb{P}\left[\mu_h(\mathbb{A}_{1,2} \cap Q) \ge C_1 \text{ and } SG_{3,6}^h \le C_2\right] \ge 1/2.$$
(11.5)

Let ϕ be a smooth, nonnegative bump function that is identically equal to $\gamma^{-1} \log \frac{MC_2}{C_1}$ on $\mathbb{A}_{1,2}$ and identically equal to 0 on $\mathbb{A}_{0.5,2.5}^c$. On the event in (11.5),

$$\begin{split} \mu_{h+\phi}(\mathbb{A}_{1,2} \cap \mathcal{Q}) &= M \times \mu_h(\mathbb{A}_{1,2} \cap \mathcal{Q}) \times \frac{C_2}{C_1} \qquad \text{(by Weyl scaling)} \\ &\geq M \times C_2 \qquad (\mu_h(\mathbb{A}_{1,2} \cap \mathcal{Q}) \geq C_1 \text{ by the event}) \\ &\geq M \times SG^h_{3,6} \qquad (C_2 \geq SG^h_{3,6} \text{ by the event (11.5)}) \\ &= M \times SG^{h+\phi}_{3,6} \qquad (\phi \equiv 0 \text{ on } \mathbb{A}_{3,6}). \end{split}$$

Since the laws of *h* and $h + \phi$ are mutually absolutely continuous viewed modulo additive constant [68, Proposition 2.9], this implies

$$\mathbb{P}[\tilde{G}_1(0)] := p_M > 0,$$

completing the proof of Step 1.

Step 2: $\alpha_0 \in (-\infty, Q)$. Write $r := 2^{-n}$. In the general case, we fix *z* and take $n \ge N(z)$ sufficiently large so that

$$dist(A_{r,6r}(z), \{0\}) > r/100.$$

By Weyl scaling, Fact 2.1,

$$\frac{\mu_h(\mathbb{A}_{r,2r}(z) \cap Q)}{SG^h_{3r,6r}(z)} \ge C \frac{\mu_h C(\mathbb{A}_{r,2r}(z) \cap Q)}{SG^{h^C}_{3r,6r}(z)}, \quad \text{for a universal constant } C > 0$$

By Step 1, with probability $p_{M/C}$,

$$\frac{\mu_{h^{\mathbb{C}}}(\mathbb{A}_{r,2r} \cap Q)}{SG_{3r,6r}^{h^{\mathbb{C}}}} \ge M/C,$$

This leads to a proof of Lemma 11.7.

Proof of Lemma 11.7. The proof is nearly identical to that of Lemma 8.2, the only difference being the event under consideration only has positive probability meaning we get δN instead of $(1 - \zeta)N$ "good" scales.

Specifically, we may carry out the proof of Lemma 8.3 and substitute Lemma 11.8 as the bound in (8.7). This shows that there exists $\delta = \delta(M) \in (0, 1)$ such that it holds for each large enough $N \in \mathbb{N}$

$$#\{n \in [N+1,2N] \cap \mathbb{Z} : \tilde{G}_n(0;M,Q) \text{ occurs}\} \ge \delta N.$$
(11.6)

Then the argument in the proof of Lemma 8.2 together with (11.6) implies a.s. the lemma statement holds for μ_h -a.e. $z \in B_1$ and then by scaling for μ_h -a.e. $z \in \mathbb{C}$.

We use Lemma 11.7 to show that " μ_h -typical points" on the boundaries of clusters do not satisfy the cone condition.

Proof of Lemma 11.5. Take M = 2C where *C* is the universal constant from Lemma 11.6. Condition on *h* and sample *z* from μ_h .

By Lemma 11.7, a.s. for every cone Q with rational extremal directions v, w, there exist arbitrarily large $n \in \mathbb{N}$ (depending on z and Q) for which the event $\tilde{G}_n(z; M, Q)$ occurs. Since every cone not equal to all of \mathbb{C} is contained within a cone with rational extremal directions, we get that a.s. for *every* cone Q, there exist arbitrarily large $n \in \mathbb{N}$ (depending on z and Q) for which the event $\tilde{G}_n(z; M, Q)$ occurs.

Suppose t > 0 is such that $z \in \partial \Lambda_t$. and let Q(z) be a cone with apex at z. Let *n* be such that $\tilde{G}_n(z; M, Q)$ holds and $B_{10 \times 2^{-n}}(z) \cap \{0\} = \emptyset$. Write $r = 2^{-n}$. By the contrapositive of Lemma 11.6,

$$\mu_h(A_{r,2r}(z) \cap \Lambda_t) > C \times SG_{3r,6r}(z) \Rightarrow \mathbb{A}_{4r,5r}(z) \cap \Lambda_t^c = \emptyset.$$
(11.7)

Since the event $\tilde{G}_n(z; M, Q)$ occurs with M = 2C,

$$\mu_h(A_{3r,5r}(z) \cap Q(z)) \ge M \times SG_{3r,6r}(z) > C \times SG_{3r,6r}(z).$$
(11.8)

We, however, also have the following implications of the cone condition:

$$B_{R}(z) \cap Q(z) \subset \Lambda_{t} \Rightarrow \mu_{h}(A_{r,2r}(z) \cap \Lambda_{t}) \ge \mu_{h}(A_{r,2r}(z) \cap Q(z)), \quad \forall R > 2r,$$
(11.9)

and for any cone Q',

$$B_{R}(z) \cap Q'(z) \subset \Lambda_{t}^{c} \Rightarrow \mathbb{A}_{4r,5r}(z) \cap \Lambda_{t}^{c} \neq \emptyset, \quad \forall R > 5r.$$
(11.10)

For any R > 0, we can take *n* sufficiently large so that $R > 5 \times 2^{-n} = 5r$. Thus, the interior cone condition (11.9) together with (11.8) implies by (11.7) that $A_{4r,5r}(z) \cap \Lambda_t^c = \emptyset$ that is incompatible with the exterior cone condition (11.10).

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We use this to show that for Lebesgue a.e. t, Λ_t is not a Lipschitz domain.

Proof of Proposition 11.2. The set Λ_t is parameterized so that $\mu_h(\Lambda_t) = t$, so if A is a Lebesgue measurable subset of $[0, \infty)$, then

$$\mu_h(\{z : z \in \partial \Lambda_t \text{ for some } t \in A\}) = \text{Leb}(A), \tag{11.11}$$

where Leb denotes one-dimensional Lebesgue measure. This follows from the standard machine. Indeed, (11.11) holds for intervals, A = [a, b],

$$\mu_h(\{z : z \in \partial \Lambda_t \text{ for some } t \in [a, b]\}) = \mu_h(\overline{\Lambda_h} \setminus \Lambda_a) = (b - a),$$

by Theorem 5.5. By approximation, this implies that (11.11) holds for all Lebesgue measurable subsets of $[0, \infty)$.

By (11.11) applied to the set

$$A = \{t > 0 : \Lambda_t \text{ satisfies the cone condition at each } z \in \partial \Lambda_t \}$$

together with Lemma 11.5, we get that a.s. the Lebesgue measure of the set of t > 0 for which Λ_t satisfies the cone condition at each boundary point is zero. One easily gets from Definition 11.1 that every Lipschitz domain satisfies the cone condition at each of its boundary points. Hence, a.s. Λ_t is not a Lipschitz domain for a.e. t > 0.

11.2 | Small diameter and large LQG mass

Recall from Section 2.2 that D_h denotes the γ -LQG metric associated with h. We will eventually show that Λ_t is not an LQG metric ball for a.e. t > 0 by showing that LQG metric balls do not satisfy the Harnack-type condition of Section 6. For this purpose, we will need to force an LQG metric ball to contain certain sets of large μ_h -mass. In order to do this, we will need the following proposition, which we prove in this subsection.

Proposition 11.9. Let $U \subset V \subset W \subset \mathbb{C}$ be bounded, connected open sets such that $\overline{V} \subset W$ and W does not intersect the unit circle $\partial B_1(0)$. For each $C > \epsilon > 0$, it holds with positive probability (depending on U, V, W, C, ϵ) that

$$\sup_{u,v \in V} D_h(u,v;W) \le \epsilon \quad and \quad \mu_h(U) \ge C, \tag{11.12}$$

where here we use the notation for the internal metric from (2.8).

It is not obvious how to apply the "adding a bump function" technique used in Section 11.1 to prove Proposition 11.9 since if the bump function ϕ is positive, then adding ϕ tends to increase both D_h and μ_h , and the reverse is true if ϕ is negative. So, some work is needed to simultaneously make the D_h -diameter small and the μ_h -mass large.

We first prove a version of Proposition 11.9 for dyadic squares.



FIGURE 11 Illustration of the proof of Lemma 11.10. The squares $S_1 \subset S_2$ are shown in pink and gray, respectively (only part of S_2 is shown). The smaller dyadic squares $S \in S_n^3$ are shown in yellow and the corresponding larger squares \hat{S} are shown in light blue. The set *G* is equal to S_2 minus the squares \hat{S} for $S \in S_N^i$, for an appropriate deterministic choice of $N \ge n_0$ and $i \in \{1, 2, 3, 4\}$.

Lemma 11.10. Fix two closed dyadic squares $S_1 \subset S_2$ such that S_2 does not intersect the Euclidean unit circle $\partial B_1(0)$. For each $C > \epsilon > 0$, it holds with positive probability (depending on S_1, S_2, C, ϵ) that

$$\sup_{u,v\in\mathsf{S}_2} D_h(u,v;\mathsf{S}_2) \leqslant \epsilon \quad and \quad \mu_h(\mathsf{S}_1) \geqslant C. \tag{11.13}$$

Proof. See Figure 11 for an illustration. Let $n_0 \in \mathbb{Z}$ be chosen so that the side length of S_1 is 2^{-n_0} . For $n \ge n_0$, let S_n be the set of closed $2^{-n} \times 2^{-n}$ squares *S* that are contained in S_1 . Since S_1 is dyadic, S_1 is the union of the squares in S_1 . Furthermore, S_n is the disjoint union of the following four sets of squares:

$$\begin{split} S_n^1 &:= \{[(k-1)2^{-n}, k2^{-n}] \times [(m-1)2^{-n}, m2^{-n}] \in S_n : k \text{ is even, } m \text{ is even}\}, \\ S_n^2 &:= \{[(k-1)2^{-n}, k2^{-n}] \times [(m-1)2^{-n}, m2^{-n}] \in S_n : k \text{ is even, } m \text{ is odd}\}, \\ S_n^3 &:= \{[(k-1)2^{-n}, k2^{-n}] \times [(m-1)2^{-n}, m2^{-n}] \in S_n : k \text{ is odd, } m \text{ is even}\}, \\ S_n^4 &:= \{[(k-1)2^{-n}, k2^{-n}] \times [(m-1)2^{-n}, m2^{-n}] \in S_n : k \text{ is odd, } m \text{ is odd}\}. \end{split}$$

As $\mu_h(S_1)$ is a strictly positive random variable, there exists a constant $C_1 > 0$ so that $\mathbb{P}[\mu_h(S_1) \ge C_1] \ge 1/2$. Let $\phi : [0,1] \to \mathbb{C}$ be a smooth bump function that is identically equal to 1 on S_1 and that is identically equal to zero outside a neighborhood of $\overline{S_1}$ and let $\tilde{h} := h + \frac{\phi}{\gamma} \log(4C/C_1)$. By the Weyl scaling property of μ_h , Fact 2.1, on the positive-probability event $\{\mu_h(S_1) \ge C_1\}$, we have $\{\mu_{\tilde{h}}(S_1) \ge 4C\}$. Therefore, by absolute continuity, there is $p = p(S_1, C) > 0$ such that with probability at least p,

$$\mu_h(\mathsf{S}_1) \geqslant 4C. \tag{11.14}$$

For $S \in S_n$, define the larger square

$$\hat{S} := ($$
square of side length $2^{-n} + 2^{-n-2}$ with same center as $S)$. (11.15)

By, for example, [20, Lemma 3.19] and a union bound over all $S \in S_n$, the supremum over all $S \in S_n$ of the $D_h(\cdot, \cdot; \hat{S} \cap S_2)$ diameter of $\hat{S} \cap S_2$ tends to zero in probability as $n \to \infty$. Consequently, we can find a deterministic $N \ge n_0$ such that with probability at least p/2, (11.14) holds and also

$$\sup_{S \in S_N} \sup_{u,v \in \hat{S} \cap S_2} D_h(u,v;\hat{S} \cap S_2) \leq \frac{\epsilon}{2}.$$
(11.16)

Since S₁ is the union of $\bigcup_{S \in S_n^i} S$ for i = 1, 2, 3, 4, on the event that (11.14) holds, there exists $i \in \{1, 2, 3, 4\}$ such that $\mu_h \left(\bigcup_{S \in S_n^i} S\right) \ge C$. Since (11.14) and (11.16) hold simultaneously with probability at least p/2, we can find a deterministic choice of $i \in \{1, 2, 3, 4\}$ such that with probability at least p/8,

$$\mu_h \left(\bigcup_{S \in S_N^i} S \right) \ge C \quad \text{and} \quad \sup_{S \in S_N^i} \sup_{u, v \in \hat{S} \cap S_2} D_h(u, v; \hat{S} \cap S_2) \le \frac{\epsilon}{2}.$$
(11.17)

Any two squares in S_N^i lie at Euclidean distance at least 2^{-n} from each other, so the set

$$G := \mathsf{S}_2 \setminus \bigcup_{S \in S_N^i} \hat{S} \tag{11.18}$$

is connected. Since \overline{G} is a finite union of closed Euclidean squares, it follows from, for example, [20, Lemma 3.9] that a.s. the $D_h(\cdot, \cdot; \overline{G})$ diameter of \overline{G} is finite. Hence, we can find a deterministic A > 0 such that with probability at least p/16, (11.17) holds and also

$$\sup_{u,v\in\overline{G}} D_h(u,v;\overline{G}) \leqslant A.$$
(11.19)

Let $\phi : \mathbb{C} \to [0, 1]$ be a smooth compactly supported bump function that is identically equal to 1 on \overline{G} and that is identically equal to zero on $\partial B_1(0) \cup \bigcup_{S \in S_{\lambda_s}^i} S$. Let

$$\tilde{h} := h - \frac{\phi}{\xi} \log(2A/\epsilon). \tag{11.20}$$

By the Weyl scaling properties of μ_h and D_h , if (11.17) and (11.19) hold (which happens with probability at least p/16), then

$$\mu_{\tilde{h}}\left(\bigcup_{S\in S_{N}^{i}}S\right) \ge C, \quad \sup_{S\in S_{N}^{i}}\sup_{u,v\in \hat{S}\cap S_{2}}D_{\tilde{h}}(u,v;\hat{S}\cap S_{2}) \le \frac{\epsilon}{2}, \quad \text{and} \quad \sup_{u,v\in \overline{G}}D_{\tilde{h}}(u,v;\overline{G}) \le \frac{\epsilon}{2}.$$
(11.21)

The second and third conditions in (11.21) together with the triangle inequality imply that

$$\sup_{u,v\in\mathsf{S}_2} D_{\tilde{h}}(u,v;\mathsf{S}_2) \leqslant \epsilon. \tag{11.22}$$

Furthermore, the first condition in (11.21) implies that $\mu_{\tilde{h}}(S_1) \ge C$.

Since $\phi \equiv 0$ on $\partial B_1(0)$, the average of \tilde{h} over $\partial B_1(0)$ is zero. By standard absolute continuity results for the GFF (see, e.g., [68, Proposition 2.9]), the laws of h and \tilde{h} are mutually absolutely continuous. The previous paragraph tells us that with probability at least p/16, (11.13) holds with \tilde{h} in place of h. Therefore, (11.13) holds with positive probability for h.

Proof of Proposition 11.9. Since *U* is open, we can find deterministic closed dyadic squares $S_1 \subset S_2 \subset U$ with the property that S_1 is contained in the interior of S_2 . By Lemma 11.10, it holds with positive probability that

$$\sup_{u,v\in\mathsf{S}_2} D_h(u,v;\mathsf{S}_2) \leqslant \frac{\epsilon}{2} \quad \text{and} \quad \mu_h(\mathsf{S}_1) \geqslant C. \tag{11.23}$$

Our hypotheses on V, W and S_1 , S_2 imply that the closure of $V \setminus S_2$ is contained in the interior of $W \setminus S_1$. Hence, we can find an intermediate open set O such that

$$\overline{V \setminus S_2} \subset O \quad \text{and} \quad \overline{O} \subset W \setminus S_1. \tag{11.24}$$

Since D_h induces the Euclidean topology and $V \setminus S_2$ is connected, there exists a deterministic A > 0 such that with positive probability, (11.23) holds and also

$$\sup_{u,v \in V \setminus S_2} D_h(u,v;O) \leqslant A.$$
(11.25)

We now use a "subtracting a bump function" argument similar to the one at the end of the proof of Lemma 11.10. Let $\phi : [0,1] \to \mathbb{C}$ be a smooth bump function that is identically equal to 1 on *O* and that is identically equal to zero outside of $W \setminus S_1$. Let

$$\tilde{h} := h - \frac{\phi}{\xi} \log(2A/\epsilon). \tag{11.26}$$

By the Weyl scaling properties of μ_h and D_h , on the positive-probability event that (11.23) and (11.25) hold,

$$\sup_{u,v\in\mathsf{S}_2} D_{\tilde{h}}(u,v;\mathsf{S}_2) \leqslant \frac{\epsilon}{2}, \quad \mu_{\tilde{h}}(\mathsf{S}_1) \geqslant C, \quad \text{and} \quad \sup_{u,v\in V\setminus\mathsf{S}_2} D_{\tilde{h}}(u,v;O) \leqslant \frac{\epsilon}{2}.$$
(11.27)

By the triangle inequality, (11.27) implies (11.12) with \tilde{h} in place of h. Since the laws of h and \tilde{h} are mutually absolutely continuous [68, Proposition 2.9], we conclude the proof.

11.3 | Not LQG metric balls

In this subsection, we prove the following.

Proposition 11.11. Almost surely, Λ_t is not an LQG-metric ball for Lebesgue-a.e. t > 0.

We follow a strategy similar to that of Section 11.1 although the arguments are slightly more complicated. To that end, let $U \in T$ and $Q' \in Q$ be connected open sets as shown in Figure 12. We



FIGURE 12 Sets U, V, W, T, Q, Q' used in the proof of Lemma 11.12 and to define the event (11.28). The origin is the black dot; the set *T* is the green key-hole shaped set; $Q' \in Q$ are gray ellipses; and $U \in V \in W$ are gray concentric balls. The picture is not drawn to scale and only part of the set *T* is shown. The sets *V* and *W* are only used in the proof of Lemma 11.12.

require that *U* is a ball contained in $\mathbb{A}_{1,2}$, that *Q'* and *Q* are contained in $\mathbb{A}_{4,5} \setminus \overline{T}$, and that *T* is a keyhole-shaped region contained in $\mathbb{A}_{1,5}$ with $\partial B_5 \subset \partial T$, as shown in the figure. For a set *A*, r > 0, and $z \in \mathbb{C}$, we write

$$A_r(z) := rA + z.$$

For $z \in \mathbb{C}$ and M > 0, let $\hat{G}_r(z) = \hat{G}_r(z; M)$ denote the event that the following holds:

$$D_{h}(Q_{r}'(z), \partial Q_{r}(z)) > \sup_{x \in \partial B_{5r}(z)} D_{h}(z, x)$$

$$D_{h}(z, \partial B_{5r}(z)) > \sup_{x, y \in T_{r}(z)} D_{h}(x, y)$$

$$\mu_{h}(U_{r}(z)) > M \times SG_{3r \ 6r}(z).$$
(11.28)

Write

$$\hat{G}_n(z) := \hat{G}_{2^{-n}}(z).$$

Showing that this event occurs with positive probability is somewhat technical, and hence, the proof of the following will be postponed to the end of this subsection.

Lemma 11.12. In the case $\alpha_0 = 0$, as in (2.4), $\mathbb{P}[\tilde{G}_1(0)] > 0$.

The preceding lemma implies the following.

Lemma 11.13. Let M > 0. There exists $\delta \in (0, 1)$ such that a.s. for μ_h -a.e. $z \in \mathbb{C}$, it holds for each large enough $N \in \mathbb{N}$ (depending on z) that

$$#\{n \in [N+1,2N] \cap \mathbb{Z} : \hat{G}_n(z;M) \text{ occurs}\} \ge \delta N.$$
(11.29)

Proof. Lemma 11.12 implies, by an argument similar to the proof of Lemma 8.3, existence of a $\delta = \delta(M) \in (0, 1)$ such that (11.29) holds for z = 0 for each large enough $N \in \mathbb{N}$. The exact same argument outlined in the proof of Lemma 11.7 then leads to the lemma statement.



FIGURE 13 Geodesic decomposition used in proof of Lemma 11.14. Geodesics are drawn as dashed lines. Sets are not drawn to scale and not all of $T_r(z)$ is shown. Note that various geodesics in the figure merge into each other. This property is called confluence of geodesics [35] and is not needed for our proofs.

We now observe a deterministic consequence of the event $\hat{G}_r(z)$ on the shape of an LQG metric ball whose boundary contains z. For the statement, we recall that $\mathcal{B}_u(0; D_h)$ denotes the open LQG metric ball of radius u centered at 0.

Lemma 11.14. The following holds a.s. for each M > 0, each $z \in \mathbb{C}$, and each r > 0 such that $B_{10r}(z)$ does not contain the origin. If u > 0 is such that $\hat{G}_r(z)$ occurs and $z \in \partial \mathcal{B}_u(0; D_h)$, then $Q'_r(z) \subset (\mathcal{B}_u(0; D_h))^c$ and $T_r(z) \subset \mathcal{B}_u(0; D_h)$.

Proof. The reader is encouraged to refer to Figure 13 as a visual aid during the proof. For notational convenience, write $\mathcal{B}_u := \mathcal{B}_u(0; D_h)$. Assume that $z \in \partial \mathcal{B}_u$ and $\hat{G}_r(z)$ occurs, where *r* is sufficiently small so that $B_{10r}(z)$ does not contain the origin. Since $z \in \partial \mathcal{B}_u$, we have $D_h(0, z) = u$.

Step 1: $Q'_r(z) \subset (\mathcal{B}_u)^c$

Recall the definition of LQG geodesics between compact sets from just after (2.10). As $B_{10r}(z)$ does not contain the origin, any geodesic from 0 to $\overline{Q'_r(z)}$ can be decomposed into geodesics from $0 \rightarrow q_1 \in \partial B_{5r}(z)$, from q_1 to $q_2 \in \partial Q_r(z)$, and from q_2 to $q_3 \in \partial Q'_r(z)$. From this and the definition (11.28) of $\hat{G}_r(z)$, we obtain

$$\begin{split} D_h(0,Q'_r(z)) &= D_h(0,q_1) + D_h(q_1,q_2) + D_h(q_2,q_3) \\ &> D_h(0,q_1) + D_h(q_2,q_3) \qquad (D_h(q_1,q_2) > 0) \\ &> D_h(0,q_1) + D_h(q_1,z) \qquad (D_h(Q'_r(z),\partial Q_r(z)) > \sup_{x \in \partial B_{5r}(z)} D_h(z,x)) \\ &\ge D_h(0,z) \qquad (\text{triangle inequality}). \end{split}$$

Since $D_h(0, z) = u$, this implies $Q'_r(z) \subset (\mathcal{B}_u)^c$.

Step 2: $T_r(z) \subset \mathcal{B}_u$

The proof is similar to Step 1. Let $y \in T_r(z)$. Also, let z_1 be a point of $\partial B_{5r}(z)$ that is hit by a geodesic from 0 to z (such a point exists since $0 \notin B_{10r}(z)$). Then,

$$D_h(0,z) = D_h(0,z_1) + D_h(z_1,z).$$
(11.30)

We now use the definition (11.28) of $\hat{G}_r(z)$ to get

$$D_{h}(0, z) = D_{h}(0, z_{1}) + D_{h}(z_{1}, z) \quad (11.30)$$

$$\geq D_{h}(0, z_{1}) + D_{h}(z, \partial B_{5r}(z)) \quad (z_{1} \in \partial B_{5r}(z))$$

$$> D_{h}(0, z_{1}) + D_{h}(z_{1}, y) \quad (D_{h}(z, \partial B_{5r}(z)) > \sup_{x, y \in T_{r}(z)} D_{h}(x, y) \text{ and } \partial T_{r}(z) \supset \partial B_{5r}(z))$$

$$\geq D_{h}(0, y) \quad (\text{triangle ineq.}).$$

Since $D_h(0, z) = u$, this implies $T_r(z) \subset \mathcal{B}_u$.

Lemmas 11.13 and 11.14 immediately lead to a proof of Proposition 11.11 via a similar argument as the proof of Lemma 11.5.

Proof of Proposition 11.11. By the exact same argument as in the beginning of the proof of Proposition 11.2, it suffices to show that a.s. for μ_h -a.e. z, no cluster Λ_t coincides with a LQG-metric ball containing z on its boundary.

Throughout the proof, we take M = C, where C > 0 is the universal constant from Lemma 11.6. Almost surely, the conclusion of Lemma 11.13 (with this choice of M) holds for μ_h -a.e. z. So, it suffices to consider a z such that the conclusion of Lemma 11.13 holds and show that a.s. no cluster Λ_i coincides with an LQG metric ball that has z on its boundary.

By Lemma 11.13, a.s. there exist arbitrarily large $n \in \mathbb{N}$ (depending on *z*) for which the event $\hat{G}_n(z; C)$ occurs. Consider such an *n* that is large enough so that $0 \notin B_{10 \times 2^{-n}}(z)$ and write $r := 2^{-n}$.

Since $\hat{G}_n(z; C)$ occurs, Lemma 11.14 implies that $Q'_r(z) \subset B^c$ and $U_r(z) \subset T_r(z) \subset B$. In particular, by the third inequality of the event (11.28),

$$\mu_h(\mathbb{A}_{r,2r}(z) \cap \mathcal{B}) \ge \mu_h(U_r(z)) > C \times SG_{3r,6r}(z).$$

$$(11.31)$$

On the other hand, the contrapositive of Lemma 11.6 shows that for each t > 0,

$$\mu_h(\mathbb{A}_{r,2r}(z) \cap \Lambda_t) > C \times SG_{3r,6r}(z) \Rightarrow \mathbb{A}_{4r,5r}(z) \cap \Lambda_t^c = \emptyset.$$
(11.32)

Since $Q'_r(z) \in \mathbb{A}_{4r,5r}(z)$, (11.32) implies that it cannot be the case that $\mu_h(\mathbb{A}_{r,2r}(z) \cap \Lambda_t) > C \times SG_{3r,6r}(z)$ and $Q'_r(z) \subset \Lambda_t^c$. Since $Q'_r(z) \subset \mathcal{B}^c$ and by (11.31), we get that a.s. \mathcal{B} is not equal to Λ_t for any t > 0.

It remains to prove Lemma 11.12, which we do in several steps. In the remainder of the subsection, let T, U, V, W, Q', Q be as in Figure 12. In particular, $U \in V \in W \in T$ and U, V, W are concentric Euclidean balls contained in $\mathbb{A}_{1,2}$.

Fix $\delta_0 \in (0, 1/100)$ sufficiently small so that:

$$B_{10\delta_0}(T) \Subset A_{1,6}, \quad B_{10\delta_0}(U) \Subset V, \quad B_{10\delta_0}(V) \Subset W,$$
$$B_{10\delta_0}(W) \Subset A_{1,2}, \quad B_{10\delta_0}(Q') \Subset Q, \quad B_{10\delta_0}(Q) \Subset A_{4,5} \setminus B_{10\delta_0}(T).$$
(11.33)

Π

Recall the notation for the internal metric from (2.8). To be succinct, we write, for a set *A* and $\delta > 0$,

$$\operatorname{diam}_{h}^{\delta}(A) := \sup_{x,y \in A} D_{h}(x,y;B_{\delta}(A)).$$
(11.34)

To prove Lemma 11.12, we will show that several auxiliary events occur with positive probability. We let \tilde{E}_1 be the event that

$$D_{h}(Q', \partial Q) > \sup_{x \in \partial B_{5}} D_{h}(0, x; (B_{2\delta_{0}}(Q \cup W))^{c})$$

$$D_{h}(0, \partial B_{\delta_{0}}) > \operatorname{diam}_{h}^{\delta_{0}}(T \setminus B_{3\delta_{0}}(W)).$$
(11.35)

We let $\tilde{E}_2 := \tilde{E}_2(M)$ be the event that

$$D_{h}(\partial B_{\delta_{0}}, \partial B_{2\delta_{0}}) > \operatorname{diam}_{h}^{\delta_{0}}(V)$$

$$\mu_{h}(U) > M \times SG_{3,6}(0).$$
(11.36)

We let \tilde{E}_3 be the event that

$$D_h(\partial B_{2\delta_0}, \partial B_{3\delta_0}) > \operatorname{diam}_h^{\delta_0}(B_{3\delta_0}(W) \backslash V).$$
(11.37)

We will successively prove the following lemmas.

Lemma 11.15. *We have* $\mathbb{P}[\tilde{E}_1] > 0$ *.*

Lemma 11.16. For each M > 0, $\mathbb{P}[\tilde{E}_1 \cap \tilde{E}_2(M)] > 0$.

Lemma 11.17. For each M > 0, $\mathbb{P}[\tilde{E}_1 \cap \tilde{E}_2(M) \cap \tilde{E}_3] > 0$.

Before we prove these lemmas, we show that Lemma 11.17 implies Lemma 11.12.

Proof of Lemma 11.12. Let M > 0 be given. By Lemma 11.17, it then suffices to show that

$$\{\tilde{E}_1 \cap \tilde{E}_2(M) \cap \tilde{E}_3\} \subset \hat{G}_1(0;M).$$
 (11.38)

Henceforth assume that $\tilde{E}_1 \cap \tilde{E}_2(M) \cap \tilde{E}_3$ occurs. The first inequality in the definition (11.35) of \tilde{E}_1 implies

$$D_h(Q',\partial Q) > \sup_{x \in \partial B_5} D_h(0,x; (B_{2\delta_0}(Q \cup W))^c) \ge \sup_{x \in \partial B_5} D_h(0,x),$$

which is the first inequality in the definition (11.28) of the event $\hat{G}_1(0; M)$. We have

$$T = (T \setminus B_{3\delta_0}(W)) \cup V \cup (B_{3\delta_0}(W) \setminus V).$$
(11.39)

Thus, the second inequality in the definition (11.35) of \tilde{E}_1 , the first inequality in the definition (11.36) of \tilde{E}_2 , and the definition (11.37) of \tilde{E}_3 imply

$$\begin{aligned} D_h(0,\partial B_5) > D_h(0,\partial B_{\delta_0}) + D_h(\partial B_{\delta_0},\partial B_{2\delta_0}) + D_h(\partial B_{2\delta_0},\partial B_{3\delta_0}) \quad \text{(triangle ineq.)} \\ \geqslant \operatorname{diam}_h^{\delta_0}(T \setminus B_{3\delta_0}(W)) + \operatorname{diam}_h^{\delta_0}(V) + \operatorname{diam}_h^{\delta_0}(B_{3\delta_0}(W)) \\ \geqslant \sup_{x,y \in T} D_h(x,y) \quad \text{((11.39) and triangle ineq.),} \end{aligned}$$

which is the second inequality in the definition of $\hat{G}_1(0; M)$. The second inequality in the definition (11.36) of \tilde{E}_2 is the third and final inequalities of $\hat{G}_1(0; M)$.

We will now show that $\mathbb{P}[\tilde{E}_1] > 0$ by adding an appropriate bump function to *h*.

Proof of Lemma 11.15. Since the random variables involved are strictly positive and finite, there exists positive finite constants C_1, C_2, C_3, C_4 so that the event

$$D_{h}(Q', \partial Q) \ge C_{1}$$

$$\sup_{x \in \partial B_{5}} D_{h}(0, x; (B_{2\delta_{0}}(Q \cup W))^{c}) \le C_{2}$$

$$D_{h}(0, \partial B_{\delta_{0}/2}) \ge C_{3}$$

$$\operatorname{diam}_{h}^{\delta_{0}}(T \setminus B_{3\delta_{0}}(W)) \le C_{4}$$
(11.40)

satisfies $\mathbb{P}[(11.40)] > 0$. Henceforth assume that the event in (11.40) occurs.

Take smooth compactly supported bump functions $\phi_1, \phi_2 : \mathbb{C} \to [0, 1]$ so that

$$\phi_1 \equiv \begin{cases} 1 & \text{on } Q \\ 0 & \text{on } (B_{\delta_0}(Q))^{\epsilon} \end{cases}$$

and

$$\phi_2 \equiv \begin{cases} 1 & \text{on } B_{\delta_0/2} \\ 0 & \text{on } B_{\delta_0}^c. \end{cases}$$

With $\xi = \xi(\gamma)$ as in (2.9), let

$$\tilde{h} := h + \frac{\phi_1}{\xi} \log\left(\left(\frac{2C_2}{C_1} \lor 1\right) \times \left(\frac{2C_4}{C_3} \lor 1\right)\right) + \frac{\phi_2}{\xi} \log\left(\frac{2C_4}{C_3} \lor 1\right). \tag{11.41}$$

Suppose (11.40) holds. Then

$$\begin{split} D_{\tilde{h}}(0,B_{\delta_0}) &\geq D_{\tilde{h}}(0,B_{\delta_0/2}) \qquad \text{(positivity of length)} \\ &\geq \frac{2C_4}{C_2} D_h(0,B_{\delta_0/2}) \qquad \text{(Weyl scaling, Fact 2.2)} \end{split}$$

$$> \operatorname{diam}_{h}^{\delta_{0}}(T \setminus B_{3\delta_{0}}(W)) \qquad (\text{the event (11.40)})$$
$$= \operatorname{diam}_{\tilde{h}}^{\delta_{0}}(T \setminus B_{3\delta_{0}}(W)) \qquad (\phi_{1} + \phi_{2} \equiv 0 \text{ on } B_{\delta_{0}}(T)). \qquad (11.42)$$

Also note that by Weyl scaling and since the bump function ϕ_2 has support contained in $(B_{2\delta_0}(Q \cup W))^c$,

$$\sup_{x \in \partial B_5} D_{\tilde{h}}(0, x; (B_{2\delta_0}(Q \cup W))^c)$$

$$\leq \left(\frac{2C_4}{C_3} \vee 1\right) \times \sup_{x \in \partial B_5} D_{h}(0, x; (B_{2\delta_0}(Q \cup W))^c).$$
(11.43)

Thus,

$$D_{\tilde{h}}(Q',\partial Q) \ge \frac{2C_2}{C_1} \times \left(\frac{2C_4}{C_3} \lor 1\right) \times D_h(Q',\partial Q) \quad (\text{Weyl scaling})$$
$$> \left(\frac{2C_4}{C_3} \lor 1\right) \times \sup_{x \in \partial B_5} D_h(0,x; (B_{2\delta_0}(Q \cup W))^c) \quad (\text{the event (11.40)})$$
$$\ge \sup_{x \in \partial B_5} D_{\tilde{h}}(0,x; (B_{2\delta_0}(Q \cup W))^c) \quad (\text{by (11.43)}). \quad (11.44)$$

By (11.42) and (11.44) and since $\mathbb{P}[(11.40)] > 0$, the event \tilde{E}_1 occurs with positive probability with \tilde{h} in place of h. By [68, Proposition 2.9], the laws of h and \tilde{h} are mutually absolutely continuous, viewed modulo additive constant. By Weyl scaling, the occurrence of \tilde{E}_1 is unaffected by adding a constant to h. Thus, the fact that \tilde{E}_1 occurs with positive probability with \tilde{h} instead of h implies that $\mathbb{P}[\tilde{E}_1] > 0$.

We next show that $\mathbb{P}[\tilde{E}_1] > 0 \Rightarrow \mathbb{P}[\tilde{E}_1 \cap \tilde{E}_2(M)] > 0$ using the domain Markov property with a set selected to be disjoint from the domain of dependence of \tilde{E}_1 .

Proof of Lemma 11.16. By the domain Markov property of the GFF, [68, Proposition 2.8], we can decompose

$$h = h_0 + \varphi, \tag{11.45}$$

where h_0 is a zero-boundary GFF on W, φ is harmonic on W, and h_0 and φ are independent.

Since the random variables involved are strictly positive and finite and $\mathbb{P}[\tilde{E}_1] > 0$, there exists positive finite constants C_1, C_2 so that the event

$$D_{h}(\partial B_{\delta_{0}}, \partial B_{2\delta_{0}}) \ge C_{1}$$

$$M \times SG_{3,6}(0) \le C_{2}$$
(11.46)

satisfies $\mathbb{P}[\tilde{E}_1 \cap (11.46)] > 0$.

We will also need to consider the event

$$diam_{h_0}^{\delta_0}(V) \leqslant e^{-\xi \sup_W \varphi} C_1$$

$$\mu_{h_0}(U) \geqslant e^{-\gamma \inf_U \varphi} C_2.$$
(11.47)

By the locality properties of μ_h and D_h (Facts 2.1 and 2.2), the events (11.46) and \tilde{E}_1 are both measurable with respect to the restriction of *h* to

$$Q \cup B_{2\delta_0}(Q \cup W)^c \cup B_{2\delta_0} \cup B_{2\delta_0}(W)^c \cup \mathbb{A}_{3,6},$$

which is a compact subset of W^c . Furthermore, the event (11.47) is measurable with respect to the restriction of *h* to $B_{\delta_0}(V)$ and the function ϕ (which is measurable with respect to $h|_{W^c}$).

By standard absolute continuity results for the GFF (see, e.g., [67, Proposition 3.4]) together with (11.45), the conditional law of $h|_{B_{\delta_0}(V)}$ given $h|_{W^c}$ is mutually absolutely continuous with respect to its marginal law. From this and Lemma 11.10, we obtain

$$\mathbb{P}[(11.47) | (11.46) \cap \tilde{E}_1] > 0.$$

Since $\mathbb{P}[\tilde{E}_1 \cap (11.46)] > 0$, we thus have

$$\mathbb{P}[(11.47) \cap (11.46) \cap \tilde{E}_1] > 0.$$

We will now conclude the proof by showing that $(11.47) \cap (11.46) \subset \tilde{E}_2$. Assume that $(11.47) \cap (11.46)$ occurs. Then,

$$\operatorname{diam}_{h}^{\delta_{0}}(V) \leq e^{\xi \operatorname{sup}_{B_{\delta_{0}}(V)}\varphi} \operatorname{diam}_{h_{0}}^{\delta_{0}}(V) \quad (\text{Weyl scaling})$$
$$\leq D_{h}(\partial B_{\delta_{0}}, \partial B_{2\delta_{0}}) \quad (\text{the events (11.47) and (11.46)})$$

and

$$\mu_{h}(U) \ge e^{\gamma \inf_{U} \varphi} \mu_{h_{0}}(U) \quad \text{(Weyl scaling)}$$
$$\ge M \times SG_{3,6}(0) \quad \text{(the events (11.47) and (11)}$$

which is exactly the event \tilde{E}_2 .

We finally show that $\mathbb{P}[\tilde{E}_1 \cap \tilde{E}_2(M)] > 0 \Rightarrow \mathbb{P}[\tilde{E}_1 \cap \tilde{E}_2(M) \cap \tilde{E}_3] > 0$. The proof involves adding a bump function to make \tilde{E}_3 to occur and then checking that the events $\tilde{E}_1 \cap \tilde{E}_2(M)$ still occur after adding the bump function.

Proof of Lemma 11.17. Let $\phi : \mathbb{C} \to [0, 1]$ be a smooth compactly supported bump function such that

$$\phi \equiv \begin{cases} 1 & \text{on } B_{3\delta_0}(W) \setminus B_{\delta_0}(U) \\ 0 & \text{on } (U \cup B_{4\delta_0}(W))^c. \end{cases}$$

Since we know that $\mathbb{P}[\tilde{E}_1 \cap \tilde{E}_2(M)] > 0$ (Lemma 11.16) and the quantities involved are a.s. finite and positive, we can find finite positive constants C_1, C_2 (depending on *M*) such that the event

$$D_{h}(\partial B_{2\delta_{0}}, \partial B_{3\delta_{0}}) \ge C_{1}$$

$$\operatorname{diam}_{h}^{\delta_{0}}(B_{3\delta_{0}}(W) \setminus V) \le C_{2}$$
(11.48)

.46)),

 \Box

satisfies $\mathbb{P}[\tilde{E}_1 \cap \tilde{E}_2 \cap (11.48)] > 0.$

Let

$$\tilde{h} = h + \frac{\phi}{\xi} \log\left(\frac{C_2}{C_1} \wedge 1\right).$$
(11.49)

Recall from (11.33) that $B_{\delta_0}(U) \subset V$. Hence, on $\tilde{E}_1 \cap \tilde{E}_2 \cap (11.48)$,

$$\operatorname{diam}_{\tilde{h}}^{\delta_0}(B_{3\delta_0}(W) \setminus V) \leqslant \frac{C_2}{C_1} \operatorname{diam}_{h}^{\delta_0}(B_{3\delta_0}(W) \setminus V) \quad \text{(Weyl scaling)}$$
$$\leqslant D_h(\partial B_{2\delta_0}, \partial B_{3\delta_0}) \quad \text{(the event (11.48))}$$
$$= D_{\tilde{h}}(\partial B_{2\delta_0}, \partial B_{3\delta_0}) \quad (\phi \equiv 0 \text{ on } \overline{B}_{3\delta_0}),$$

which is the event \tilde{E}_3 with \tilde{h} in place of *h*. Hence, this event has positive probability.

As we will see below, by Weyl scaling, the fact $\log(\frac{C_2}{C_1} \wedge 1) \leq 0$, and since $\phi \equiv 0$ on $U \cup \mathbb{A}_{3,6} \cup B_{3\delta_0}$, on the event $\tilde{E}_1 \cap \tilde{E}_2(M) \cap (11.48)$ the event $\tilde{E}_1 \cap \tilde{E}_2(M)$ occurs with \tilde{h} in place of h. By [68, Proposition 2.9], the laws of h and \tilde{h} , viewed modulo additive constant, are mutually absolutely continuous. Since the occurrence of the event $\tilde{E}_1 \cap \tilde{E}_2(M) \cap \tilde{E}_3$ is unaffected by adding a constant to h, we conclude that $\mathbb{P}[\tilde{E}_1 \cap \tilde{E}_2(M) \cap \tilde{E}_3] > 0$, as required.

That adding the bump function did not change the occurrence of the events \tilde{E}_1 and \tilde{E}_2 , defined in (11.35) and (11.36), respectively. The first inequality in \tilde{E}_1 is

$$D_{\tilde{h}}(Q', \partial Q) = D_{h}(Q', \partial Q) \quad (\phi \equiv 0 \text{ on } Q)$$

$$> \sup_{x \in \partial B_{5}} D_{h}(0, x; (B_{2\delta_{0}}(Q \cup W))^{c}) \quad (\text{event } \tilde{E}_{1} \text{ for } h)$$

$$\geqslant e^{-\log(\frac{C_{2}}{C_{1}} \wedge 1)} \sup_{x \in \partial B_{5}} D_{\tilde{h}}(0, x; (B_{2\delta_{0}}(Q \cup W))^{c}) \quad (\text{Weyl scaling})$$

$$\geqslant \sup_{x \in \partial B_{5}} D_{\tilde{h}}(0, x; (B_{2\delta_{0}}(Q \cup W))^{c}) \quad (\log(\frac{C_{2}}{C_{1}} \wedge 1) \leq 0).$$

The second inequality in \tilde{E}_1 and the first inequality in \tilde{E}_2 are checked in a similar fashion, using $\log(\frac{C_2}{C_1} \wedge 1) \leq 0$, and $\phi \equiv 0$ on $\overline{B_{2\delta_0}}$. Since $\phi \equiv 0$ on $U \cup \mathbb{A}_{3,6}$, the last inequality in \tilde{E}_2 is preserved. Hence, on the event $\tilde{E}_1 \cap \tilde{E}_2(M) \cap (11.48)$, the event $\tilde{E}_1 \cap \tilde{E}_2(M)$ occurs with \tilde{h} in place of h.

APPENDIX: OBSTACLE PROBLEM FOR RADON MEASURES

In this appendix, we provide the proofs that were omitted in Section 3.2. For clarity, we prove these results for any Radon measure μ satisfying, for some R > 0,

$$r^{\beta^-} \leqslant \mu(B_r(z)) \leqslant r^{\beta^-} \quad \text{for all } z \in B_R, \tag{A.1}$$

for some exponents β^+ , $\beta^- > 0$, for all *r* sufficiently small. This implies the results in Section 3.2 as the Liouville measure is a.s. a Radon measure that satisfies (A.1). Indeed, this follows from Lemma 2.4 and the scaling properties of *h* and μ_h , namely, (2.5) and (2.7).
For R > 0, let

$$q_{B_R}(\cdot) = \int_{B_R} G_{B_R}(y, \cdot)\mu(dy), \qquad (A.2)$$

where G_{B_R} is the Green's function for B_R . Under the condition (A.1), the function q_{B_R} satisfies the following properties:

- (1) Continuous: q_{B_R} is Hölder continuous in $\overline{B_R}$ and finite;
- (2) Potential: q_{B_R} is superharmonic and $\Delta q_{B_R} = -\mu$ in B_R ;
- (3) Zero boundary: $q_{B_R}(z) = 0$ for $z \in \partial B_R$;
- (4) Positive: $q_{B_R}(x) > 0$ for $x \in B_R$.

The first property follows by the same argument outlined in the proof of Proposition 2.5; the second, by, for example, [2, Theorem 4.3.8]; the third as $G_{B_R}(0, \cdot) = 0$ on ∂B_R ; and the fourth by the strong maximum principle.

For notational simplicity, we consider R = 1 in all but the last subsection. We will also only consider the case where *z* is the origin.

A.1 Definition

For t > 0, denote the *obstacle* $\beta_t : \overline{B_1} \to \mathbb{R} \cup \{\infty\}$ as

$$\beta_t(x) = -tG_{B_1}(0, x) + q_{B_1}(x).$$
(A.3)

The set of supersolutions is

$$\tilde{S}_t = \{ w \in C(\overline{B_1}) : \Delta w \le 0 \text{ in } B_1 \text{ and } w \ge \beta_t \text{ in } \overline{B_1} \},$$
(A.4)

where $C(B_1)$ denotes the set of continuous functions on the closed unit ball.

Consider the *least supersolution* or *least superharmonic majorant* as the pointwise infimum of all functions in \tilde{S}_t

$$\tilde{w}_t = \inf\{w \in \tilde{S}_t\} \tag{A.5}$$

and the odometer

$$v_t = \tilde{w}_t - \beta_t. \tag{A.6}$$

Note that \tilde{S}_t is nonempty as it contains q_{B_1} — thus \tilde{w}_t always exists. Denote the *noncoincidence* set by

$$\Lambda_t = \{ x \in B_1 : \tilde{w}_t > \beta_t \}. \tag{A.7}$$

Note that the least supersolution in (A.5) is related to (3.2) by $w_t = \tilde{w}_t - q_{B_1}$. In particular, A_t coincides with A_t and v_t with v_t — each of the lemmas in Section 3.2 will follow via this substitution. We choose to work with \tilde{S}_t as this allows us to directly cite results concerning superharmonic functions.

A.2 | Existence

We first verify that the solution to the obstacle problem is nondegenerate in the following sense, this implies Lemma 3.1.

Lemma A.1. For all t > 0, \tilde{w}_t is finite, continuous, and an element of \tilde{S}_t .

Proof. Let

$$f_t := \inf\{g : g \text{ is superharmonic in } B_1 \text{ and } g \ge \beta_t \text{ in } \overline{B}_1\},$$
 (A.8)

where, as before, the infimum is pointwise. Note that this definition differs from \tilde{w}_t in that admissible superharmonic functions need only be lower semicontinuous. It suffices to show that f_t satisfies the desired properties. Indeed, by definition $f_t \leq \tilde{w}_t$ and the reverse inequality follows from $f_t \in \tilde{S}_t$.

Step 1: Finiteness.

If $g \ge \beta_t$ is superharmonic, then, by the minimum principle, $g \ge 0$ on B_1 as $g \ge \beta_t = 0$ on ∂B_1 . As this holds for all such g, $f_t \ge 0$. This together with $\infty > q_{B_1} \ge f_t$ (q_{B_1} is admissible in (A.8)) shows finiteness.

Step 2: Superharmonicity.

We use [2, Theorem 3.7.5] which we recall for the reader's convenience. Let *O* be a bounded open set and let $f : O \to [-\infty, \infty]$. The *lower semicontinuous regularization* of *f* is defined by

$$\hat{f}(x) = \min\{f(x), \liminf_{y \to x} f(y)\}.$$
 (A.9)

[2, Theorem 3.7.5] states that if $f > -\infty$ is the infimum of a family of superharmonic functions on *O*, then \hat{f} is superharmonic on *O* and $\hat{f}(x) = \liminf_{y \to x} f(y)$.

Since f_t is finite, we may use this to see that its lower semicontinuous regularization, \hat{f}_t , is superharmonic on B_1 and satisfies $\hat{f}_t(x) = \liminf_{y \to x} f_t(y) \leq f_t(x)$. In fact, (A.8) implies f_t is equal to its lower semicontinuous regularization. Indeed, \hat{f}_t is superharmonic and

$$\hat{f}_t(x) = \liminf_{y \to x} f_t(y) \ge \liminf_{y \to x} \beta_t(y) = \beta_t(x)$$

as the obstacle, β_t , is continuous, implying that $\hat{f}_t \ge f_t$ by (A.8).

Step 3: Continuity.

By Step 2, f_t is lower semicontinuous. It remains to verify upper semicontinuity. Let $\epsilon > 0$ and $x_0 \in B_1$ be given. By continuity of β_t , there exists $\delta > 0$ sufficiently small so that

$$\beta_t(x) + \epsilon/2 \ge \beta_t(y), \quad \forall x, y \in B_\delta(x_0),$$

and hence, since $f_t(x) \ge \beta_t(x)$,

$$\varepsilon + f_t(x) \ge \beta_t(x_0) + \varepsilon/2 \ge \beta_t(x), \quad \forall x \in B_\delta(x_0).$$
 (A.10)

Let g_1 be the unique function that is harmonic in $B_{\delta}(x_0)$ and coincides with $\epsilon + f_t$ on $\partial B_{\delta}(x_0)$. Note that since $\epsilon + f_t - g_1$ is superharmonic in $B_{\delta}(x_0)$ and equal to 0 on $\partial B_{\delta}(x_0)$,

$$\epsilon + f_t \ge g_1, \quad \text{on } B_\delta(x_0).$$
 (A.11)

Define the function g to be g_1 on $B_{\delta}(x_0)$ and $\epsilon + f_t$ on $B_1 \setminus B_{\delta}(x_0)$. One may check, using the supermean-value property and (A.11), that g is superharmonic in B_1 . Hence, by (A.10), g is admissible in (A.8) and, in turn, $g \ge f_t$. Therefore,

$$\begin{split} \limsup_{x \to x_0} f_t(x) &\leq \limsup_{x \to x_0} g(x) \quad (g \geq f_t \text{ on } B_1) \\ &= g(x_0) \quad (g \text{ is harmonic and hence continuous in a neighborhood of } x_0) \\ &\leqslant \epsilon + f_t(x_0) \quad (by (A.11) \text{ and definition of } g). \end{split}$$

We conclude by observing the prior inequality holds for any $\epsilon > 0$.

We next check that the least supersolution is harmonic on the noncoincidence set, this together with Lemma A.1 implies Lemma 3.2.

Lemma A.2. The noncoincidence set, Λ_i , is open and connected and

$$\Delta \tilde{w}_t = 0 \quad on \Lambda_t.$$

Proof. Step 1: Λ_t is open.

As \tilde{w}_t and β_t are continuous and the disk B_1 is open, the set Λ_t is open (this is the topological definition of a continuous function).

Step 2: \tilde{w}_t is harmonic on Λ_t .

If Λ_t is empty, we are done, so suppose not. (This never happens but is proved later in Proposition 4.1.) Further, suppose for sake of contradiction that \tilde{w}_t is not harmonic on Λ_t . Since we know that \tilde{w}_t is superharmonic (Lemma A.1), this means that \tilde{w}_t is not subharmonic on Λ_t .

The idea of the rest of the proof is the following. Since $\tilde{w}_t > \beta_t$ on Λ_t , there is some extra room to "lower" \tilde{w}_t . If $\Delta \tilde{w}_t(z) < 0$ at some $z \in \Lambda_t$, then we can decrease \tilde{w}_t around z by bending it up just enough to not break superharmonicity. This contradicts the minimality of \tilde{w}_t . We cannot carry out this strategy literally since \tilde{w}_t is a priori not differentiable, so we instead use one of the equivalent definitions of subharmonic.

Here are the details. Since we are assuming that \tilde{w}_t is not subharmonic, by, for example, [2, Theorem 3.2.2], there is some $z \in \Lambda_t$ such that for every R > 0, there is a closed ball $\overline{B_r}(z) \subset \Lambda_t$ of radius r < R and a function $H : \overline{B_r}(z) \to \mathbb{R}$ that is continuous in $\overline{B_r}(z)$ and harmonic in $B_r(z)$ such that

$$H \ge \tilde{w}_t \quad \text{on } \partial B_r(z)$$
 (A.12)

but

$$\tilde{w}_t(x_0) > H(x_0) \tag{A.13}$$

for some $x_0 \in B_r(z)$.

Next, since \tilde{w}_t and β_t are continuous and $\overline{B_R}(z) \subset \Lambda_t$, for *R* sufficiently small,

$$\inf_{x \in \partial B_r(z)} \tilde{w}_t(x) > \sup_{y \in \overline{B_r}(z)} \beta_t(y), \quad \forall r < R.$$
(A.14)

 \Box

Fix r > 0 small so that (A.12), (A.13), and (A.14) hold. As *H* is harmonic,

$$\inf_{x \in B_r(z)} H(x) \ge \inf_{y \in \partial B_r(z)} H(y) \ge \inf_{x \in \partial B_r(z)} \tilde{w}_t(x) > \sup_{y \in \overline{B_r}(z)} \beta_t(y),$$

in particular,

$$H > \beta_t \quad \text{in } \overline{B_r}(z). \tag{A.15}$$

The above inequalities allow us to "lower" \tilde{w}_t using *H*. Indeed, take the function $\psi : \overline{B_r}(z) \to \mathbb{R}$ defined by

$$\psi := \min(H, \tilde{w}_t) \tag{A.16}$$

and note that by continuity and (A.12), $\psi = \tilde{w}_t$ in a neighborhood of $\partial B_r(z)$. In particular, we may continuously extend ψ to all of $\overline{B_1}$ by defining $\psi = \tilde{w}_t$ on $\overline{B_1} \setminus B_r(z)$. As *H* is harmonic in $B_r(z)$ and \tilde{w}_t is superharmonic, this extension ψ is superharmonic. Also, by (A.15), $\psi \ge \beta_t$. This shows that $\psi \in \tilde{S}_t$. However, by (A.13), $\tilde{w}_t(x_0) > \psi(x_0)$, contradicting the minimality of \tilde{w}_t .

Step 3: Λ_t *is connected.*

Otherwise there is a connected component of Λ_t not containing the origin upon which v_t is nonzero, subharmonic, and 0 on its boundary — this violates the strong maximum principle.

A.3 | Monotonicity

We now check monotonicity, this proves Lemma 3.3. Lemma A.3. If $t_1 \leq t_2$, then $\Lambda_{t_1} \subseteq \Lambda_{t_2}$.

Proof. Recall that the odometer can be expressed as $v_t = \tilde{w}_t - \beta_t$. Showing monotonicity is equivalent to verifying $v_{t_1} \leq v_{t_2}$. Unpack the difference to see that

$$\begin{split} v_{t_2} - v_{t_1} &= \tilde{w}_{t_2} - \tilde{w}_{t_1} + \beta_{t_1} - \beta_{t_2} \\ &= \tilde{w}_{t_2} - \tilde{w}_{t_1} + (-t_1 + t_2)G_{B_1}(0, \cdot). \end{split}$$

This motivates considering the superharmonic function

$$\tilde{s} := \tilde{w}_{t_2} + (t_2 - t_1)G_{B_1}(0, \cdot).$$

In particular, we have

$$v_{t_2} - v_{t_1} = \tilde{s} - \tilde{w}_{t_1},$$

thus it suffices to show

$$\tilde{s} \ge \tilde{w}_{t_1}.$$
 (A.17)

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This inequality follows from the obstacle problem. Indeed, as

$$\tilde{w}_{t_2} \ge \beta_{t_2} = q_{B_1} - t_2 G_{B_1}(0, \cdot),$$

we have, after plugging in the definition of \tilde{s} ,

$$\tilde{s} \ge q_{B_1} - t_1 G_{B_1}(0, \cdot) = \beta_{t_1}$$

Therefore, $\tilde{s} \in \tilde{S}_{t_1}$ and by minimality of \tilde{w}_{t_1} we have (A.17).

A.4 | Conservation of mass

In this section, we prove that no mass comes in from the boundary, that is, $\mu_h(\Lambda_t) \leq t$. This establishes Lemma 3.4. To that end, we observe that the odometer is 0 on the boundary of the domain.

Lemma A.4. For all t > 0, $v_t = 0$ on ∂B_1 .

Proof. This is immediate from $q_{B_1} \in \tilde{S}_t$ and $q_{B_1} = G_{B_1}(0, \cdot) = 0$ on ∂B_1

We then use this together with the definition of weak normal derivative to prove the desired claim.

Lemma A.5. For all t > 0, $\mu(\Lambda_t) \leq t$. Moreover, if $\overline{\Lambda_t} \subset B_1$ and $\mu(\partial \Lambda_t) = 0$, then $\mu_h(\Lambda_t) = t$.

Proof. Fix t > 0 and recall that Λ_t is an open set. By Lemma A.4, Lemma A.2, the superharmonicity of \tilde{w}_t , and the definition of v_t ,

$$\begin{cases} v_t = 0 & \text{on } \partial B_1 \\ \Delta v_t = -t\delta_0 + \mu|_{A_t} + \nu|_{\partial A_t} & \text{on } B_1, \end{cases}$$
(A.18)

where $0 \le v \le \mu$ is a Radon measure that is absolutely continuous with respect to μ . Hence, v_t solves a linear Dirichlet problem on B_1 , and so, by [73, Proposition 7.3], there exists a weak normal derivative $\frac{\partial v_t}{\partial n}$ so that

$$-t + \mu(\Lambda_t) + \nu(\partial \Lambda_t) = \int_{\partial B_1} \frac{\partial v_t}{\partial n} d\sigma, \qquad (A.19)$$

where $d\sigma$ denotes integration with respect to surface measure. Since $v_t \ge 0$ on B_1 and $v_t = 0$ on ∂B_1 , by [73, Lemma 12.15],

$$\frac{\partial v_t}{\partial n} \le 0 \tag{A.20}$$

almost everywhere with respect to the surface measure. Moreover,

$$\overline{\Lambda_t} \subset B_1 \Rightarrow \frac{\partial v_t}{\partial n} = 0, \tag{A.21}$$

as the weak normal derivative coincides with the classical normal derivative if it exists. In particular, by (A.19),

$$-t + \mu(\Lambda_t) + \nu(\partial \Lambda_t) \le 0, \tag{A.22}$$

and

$$\Lambda_t \subset B_1 \Rightarrow -t + \mu(\Lambda_t) + \nu(\partial \Lambda_t) = 0, \tag{A.23}$$

completing the proof as $0 \le \nu \le \mu$.

A.5 | Compatibility

We prove Lemma 3.5 in this section. As previously mentioned, the results proved so far in this appendix apply to $w_t^{B_R}$, $\Lambda_t^{B_R}$, $v_t^{B_R}$ as long as (A.1) is satisfied for μ in B_R . That is, if (A.1) is satisfied, then $w_t^{B_R} \in S_t^{B_R}$ and

$$\begin{cases} v_t^{B_R} = 0 & \text{on } \partial B_R \\ \Delta v_t^{B_R} = -t\delta_0 + \mu|_{A_t^{B_R}} + \nu|_{\partial A_t^{B_R}} & \text{on } B_R \end{cases}$$
(A.24)

for a Radon measure $0 \le \nu \le \mu$ that is absolutely continuous with respect to μ . **Lemma A.6.** Suppose (A.1) is satisfied for fixed R > 0. For all $s_1 \le R$, if, for some $s_2 \in [s_1, R]$, we have $\overline{\Lambda_t^{B_{s_2}}} \subset B_{s_1}$, then $\Lambda_t^{B_s} = \Lambda_t^{B_{s_2}}$ for all $s \in [s_1, R]$.

Proof. Fix R > 0. Note that if (A.1) is satisfied for R, then it is satisfied for all $s \in R$. Meaning $w_t^{B_s} \in S_t^{B_s}$ and (A.24) holds for $v_t^{B_s}$ for all $s \in R$. Let $s_1 \in R$ be given and fix $s_2 \in [s_1, R]$ for which we have $\overline{A_t^{B_{s_2}}} \subset B_{s_1}$.

We first claim that

$$v_t^{B_{r_1}} \leqslant v_t^{B_{r_2}} \quad \text{in } B_{r_1}, \quad \forall r_1 \leqslant r_2 \leqslant R.$$
(A.25)

To prove (A.25), fix $r_1 \leq r_2 \leq R$ and write

$$v_t^{B_{r_1}} - v_t^{B_{r_2}} = w_t^{B_{r_1}} - w_t^{B_{r_2}} + tG_{B_{r_1}}(0, \cdot) - tG_{B_{r_2}}(0, \cdot) = w_t^{B_{r_1}} - \hat{w}_t,$$
(A.26)

where

$$\hat{w}_t := w_t^{B_{r_2}} - t(G_{B_{r_1}}(0, \cdot) - G_{B_{r_2}}(0, \cdot)).$$
(A.27)

Since $w_t^{B_{r_2}} \in S_t^{B_{r_2}}$ and $\Delta G_B(0, \cdot) = -\delta_0$ in *B* for any ball *B*,

$$\Delta \hat{w}_{t} = \Delta w_{t}^{B_{r_{2}}} - t(\Delta G_{B_{r_{1}}}(0, \cdot) - \Delta G_{B_{r_{2}}}(0, \cdot)) \leq \mu \quad \text{in } B_{r_{1}}$$
(A.28)

and

$$\hat{w}_t = (w_t^{B_{r_2}} + tG_{B_{r_2}}(0, \cdot)) - tG_{B_{r_1}}(0, \cdot) \ge -tG_{B_{r_1}}(0, \cdot) \quad \text{in } B_{r_1}.$$
(A.29)

Therefore, $\hat{w}_t \in S_t^{B_{r_1}}$, which shows $w_t^{B_{r_1}} \leq \hat{w}_t$ and hence (A.25) by (A.26).

For the other direction, we use the hypothesis $\overline{\Lambda_t^{B_{s_2}}} \subset B_{s_1}$. This together with (A.25) implies that $v_t^{B_{s_1}}$ is identically zero in a neighborhood of ∂B_{s_1} and so can be extended by 0 to be harmonic in $B_R \setminus B_{s_1}$. Also, observe that (A.25) implies $\Lambda_t^{B_{s_1}} \subset \Lambda_t^{B_R}$ by definition. Therefore, by (A.24) for B_{s_1} and B_R , $v_t^{B_R} - v_t^{B_{s_1}}$ is subharmonic in $\Lambda_t^{B_R}$ and 0 on its boundary that shows

$$v_t^{B_R} \leqslant v_t^{B_{s_1}}.\tag{A.30}$$

Combining (A.25) and (A.30) shows that

$$v_t^{B_R} = v_t^{B_{s_1}} \leqslant v_t^{B_s} \leqslant v_t^{B_r} \leqslant v_t^{B_R}, \quad \forall s_1 \leqslant s \leqslant r \leqslant R,$$
(A.31)

completing the proof by the definition of Λ_t .

ACKNOWLEDGMENTS

We thank the anonymous referees for helpful comments. We also thank Charlie Smart and Bill Cooperman for useful discussions. A.B. was partially supported by NSF grant DMS-2202940 and a Stevanovich fellowship. E.G. was partially supported by a Clay research fellowship.

JOURNAL INFORMATION

The *Proceedings of the London Mathematical Society* is wholly owned and managed by the London Mathematical Society, a not-for-profit Charity registered with the UK Charity Commission. All surplus income from its publishing programme is used to support mathematicians and mathematics research in the form of research grants, conference grants, prizes, initiatives for early career researchers and the promotion of mathematics.

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